

CDC922

133-MHz CLOCK SYNTHESIZER/DRIVER FOR PC MOTHERBOARDS WITH 3-STATE OUTPUTS

SCAS634—JULY 28, 1999

- Generates Clocks for Pentium™ III Class Microprocessors
- Supports a Single Pentium III Microprocessor
- Uses a 14.318 MHz Crystal Input to Generate Multiple Output Frequencies
- Includes Spread Spectrum Clocking (SSC), 0.34% Downspread for Reduced EMI Performance
- Power Management Control Terminals
- Low Output Skew and Jitter for Clock Distribution
- Operates from Dual 2.5-V and 3.3-V Supplies
- Generates the Following Clocks:
 - 3 CPU (2.5 V, 100/133 MHz)
 - 10 PCI (3.3 V, 33.3 MHz)
 - 1 CPU/2 (2.5 V, 50/66 MHz)
 - 1 APIC (2.5 V, 16.67 MHz)
 - 3 3V66 (3.3 V, 66 MHz)
 - 2 REF (3.3 V, 14.318 MHz)
 - 1 48MHz (3.3 V, 48 MHz)
- Packaged in 48-Pin SSOP Package
- Designed for Use with TI's Direct Rambus™ Clock Generators (CDCR81, CDCR82, CDCR83)

DL PACKAGE
(TOP VIEW)

| | | | |
|----------------------|----|----|----------------------|
| REF0 | 1 | 48 | GND |
| REF1 | 2 | 47 | V _{DD} 2.5V |
| V _{DD} 3.3V | 3 | 46 | APIC |
| XIN | 4 | 45 | GND |
| XOUT | 5 | 44 | V _{DD} 2.5V |
| GND | 6 | 43 | CPU_DIV2 |
| PCI0 | 7 | 42 | GND |
| PCI1 | 8 | 41 | V _{DD} 2.5V |
| V _{DD} 3.3V | 9 | 40 | CPU2 |
| PCI2 | 10 | 39 | GND |
| PCI3 | 11 | 38 | V _{DD} 2.5V |
| PCI4 | 12 | 37 | CPU1 |
| PCI5 | 13 | 36 | CPU0 |
| GND | 14 | 35 | GND |
| PCI6 | 15 | 34 | V _{DD} 3.3V |
| PCI7 | 16 | 33 | GND |
| V _{DD} 3.3V | 17 | 32 | <u>PWR_DWN</u> |
| PCI8 | 18 | 31 | <u>SPREAD</u> |
| PCI9 | 19 | 30 | SEL1 |
| GND | 20 | 29 | SEL0 |
| 3V66(0) | 21 | 28 | V _{DD} 3.3V |
| 3V66(1) | 22 | 27 | 48MHz |
| 3V66(2) | 23 | 26 | GND |
| V _{DD} 3.3V | 24 | 25 | <u>SEL133/100</u> |

description

The CDC922 is a clock synthesizer/driver that generates CPU, CPU_DIV2, 3V66, PCI, APIC, 48MHz, and REF system clock signals to support computer systems with a single Pentium III class microprocessor.

All output frequencies are generated from a 14.318-MHz crystal input. Instead of a crystal, a reference clock input can be provided at the XIN input. Two phase-locked loops (PLLs) are used to generate the host frequencies and the 48-MHz clock frequency. On-chip loop filters and internal feedback eliminate the need for external components.

The host and PCI clock outputs provide low-skew and low-jitter clock signals for reliable clock operation. All outputs have 3-state capability, which can be selected via control inputs SEL0, SEL1, and SEL133/100.

The 48MHz clock can be independently disabled via the control inputs SEL0, SEL1, and SEL133/100. In this state, the 48-MHz PLL is disabled and the 48MHz clock is driven to high impedance to reduce component jitter.

The outputs are either 3.3-V or 2.5-V single-ended CMOS buffers. With a logic high-level on the PWR_DWN terminal, the device operates normally, but when a logical low-level input is applied, the device powers down completely with the outputs in a low-level output state.



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**TEXAS
INSTRUMENTS**

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description (continued)

The CPU bus can operate at 100 MHz or 133 MHz. Output frequency selection is done with corresponding setting for SEL133/100 control input. The PCI bus frequency is fixed to 33 MHz.

Since the CDC922 is based on PLL circuitry, it requires a stabilization time to achieve phase lock of the PLL. This stabilization time is required after power up or after changes to the SEL inputs are made. With use of an external reference clock, this signal must be fixed-frequency and fixed-phase before the stabilization time starts.

Function Tables

SELECT FUNCTIONS

| INPUTS | | | OUTPUTS | | | | | | | FUNCTION |
|----------------|------|------|---------|----------|--------|--------|--------|------------|-----------|----------------|
| SEL133/ 100 | SEL1 | SEL0 | CPU | CPU_DIV2 | 3V66 | PCI | 48MHz | REF | APIC | |
| L | L | L | Hi-Z | Hi-Z | Hi-Z | Hi-Z | Hi-Z | Hi-Z | Hi-Z | 3-state |
| L | L | H | N/A | N/A | N/A | N/A | N/A | N/A | N/A | Reserved |
| L | H | L | 100 MHz | 50 MHz | 66 MHz | 33 MHz | Hi-Z | 14.318 MHz | 16.67 MHz | 48-MHz PLL off |
| L | H | H | 100 MHz | 50 MHz | 66 MHz | 33 MHz | 48 MHz | 14.318 MHz | 16.67 MHz | 48-MHz PLL on |
| H | L | L | TCLK/2 | TCLK/4 | TCLK/4 | TCLK/8 | TCLK/2 | TCLK | TCLK/16 | Test |
| H | L | H | N/A | N/A | N/A | N/A | N/A | N/A | N/A | Reserved |
| H | H | L | 133 MHz | 66 MHz | 66 MHz | 33 MHz | Hi-Z | 14.318 MHz | 16.67 MHz | 48-MHz PLL off |
| H | H | H | 133 MHz | 66 MHz | 66 MHz | 33 MHz | 48 MHz | 14.318 MHz | 16.67 MHz | 48-MHz PLL on |

ENABLE FUNCTIONS

| INPUTS | OUTPUTS | | | | | | INTERNAL | |
|---------|---------|----------|------|------|-----|---------------|----------|------|
| PWR_DWN | CPU | CPU_DIV2 | APIC | 3V66 | PCI | REF, 48MHz | CRYSTAL | VCOs |
| L | L | L | L | L | L | L | Off | Off |
| H | On | On | On | On | On | On | On | On |

OUTPUT BUFFER SPECIFICATIONS

| BUFFER NAME | V _{DD} RANGE (V) | IMPEDANCE (Ω) | BUFFER TYPE |
|---------------------|---------------------------|---------------|-------------|
| CPU, CPU_DIV2, APIC | 2.375 – 2.625 | 13.5 – 45 | TYPE 1 |
| 48MHz, REF | 3.135 – 3.465 | 20 – 60 | TYPE 3 |
| PCI, 3V66 | 3.135 – 3.465 | 12 – 55 | TYPE 5 |

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Terminal Functions

| TERMINAL | | I/O | DESCRIPTION |
|--------------------------------|---|-----|--|
| NAME | NO. | | |
| 3V66 [0–2] | 21–23 | O | 3.3 V, Type 5, 66-MHz clock outputs |
| 48MHz | 27 | O | 3.3 V, Type 3, 48-MHz clock output |
| APIC | 46 | O | 2.5 V, Type 2, APIC clock output at 16.67 MHz |
| CPU [0–2] | 36, 37, 40 | O | 2.5 V, Type 1, CPU clock outputs |
| CPU_DIV2 | 43 | O | 2.5 V, Type 1, CPU_DIV2 clock output |
| GND | 6, 14, 20, 26, 33, 35, 39, 42, 45, 48 | | Ground for PCI, 3V66, 48MHz, CPU, CPU_DIV2, APIC, REF [0–1] outputs and CORE |
| PCI [0–9] | 7, 8, 10–13, 15, 16, 18, 19 | O | 3.3 V, Type 5, 33-MHz PCI clock outputs |
| $\overline{\text{PWR_DWN}}$ | 32 | I | Power down for complete device with outputs forced low |
| REF0, REF1 | 1, 2 | O | 3.3 V, Type 3, 14.318-MHz reference clock outputs |
| SEL0, SEL1 | 29, 30 | I | LVTTL level logic select terminals for function selection |
| $\overline{\text{SEL133/100}}$ | 25 | I | LVTTL level logic select terminal for enabling 100/133 MHz |
| $\overline{\text{SPREAD}}$ | 31 | I | Disables SSC function |
| V _{DD} 2.5V | 38, 41, 44, 47 | | Power for CPU, CPU_DIV2, and APIC outputs |
| V _{DD} 3.3V | 3, 9, 17, 24, 28, 34 | | Power for the REF, PCI, 3V66, 48MHz outputs and CORE |
| XIN | 4 | I | Crystal input – 14.318 MHz |
| XOUT | 5 | O | Crystal output – 14.318 MHz |



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spread spectrum clock (SSC) implementation for CDC922

Simultaneously switching at fixed frequency generates a significant power peak at the selected frequency, which in turn will cause EMI disturbance to the environment. The purpose of the internal frequency modulation of the CPU-PLL allows to distribute the energy to many different frequencies which reduces the power peak. A typical characteristic for a single frequency spectrum and a frequency modulated spectrum is shown in Figure 1.

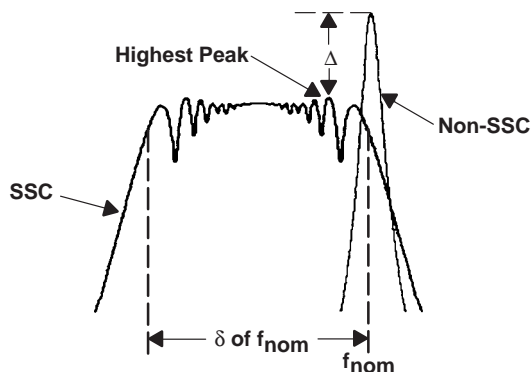


Figure 1. Frequency Power Spectrum With and Without the Use of SSC

The modulated spectrum has its distribution left hand to the single frequency spectrum which indicates a “down-spread modulation”.

The peak reduction depends on the modulation scheme and modulation profile. System performance and timing requirements are the limiting factors for actual design implementations. The implementation was driven to keep the average clock frequency closed to its upper specification limit. The modulation amount was set to approximately -0.34% (compared to -0.5% on the CDC921).

In order to allow a downstream PLL to follow the frequency modulated signal, the bandwidth of the modulation signal is limited in order to minimize SSC induced tracking skew jitter. The ideal modulation profile used for CDC922 is shown in Figure 2.

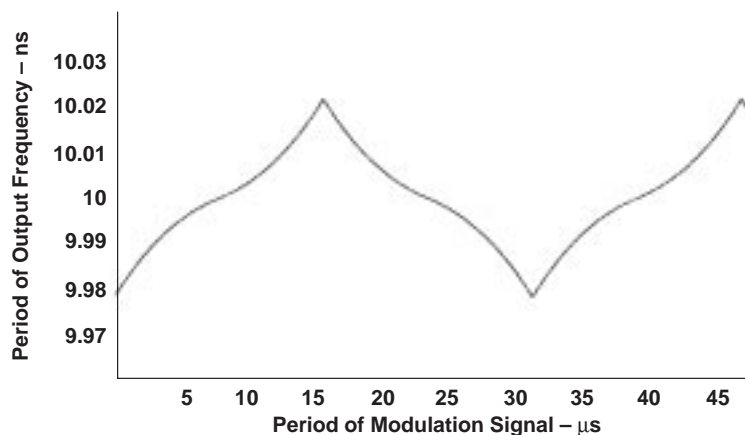


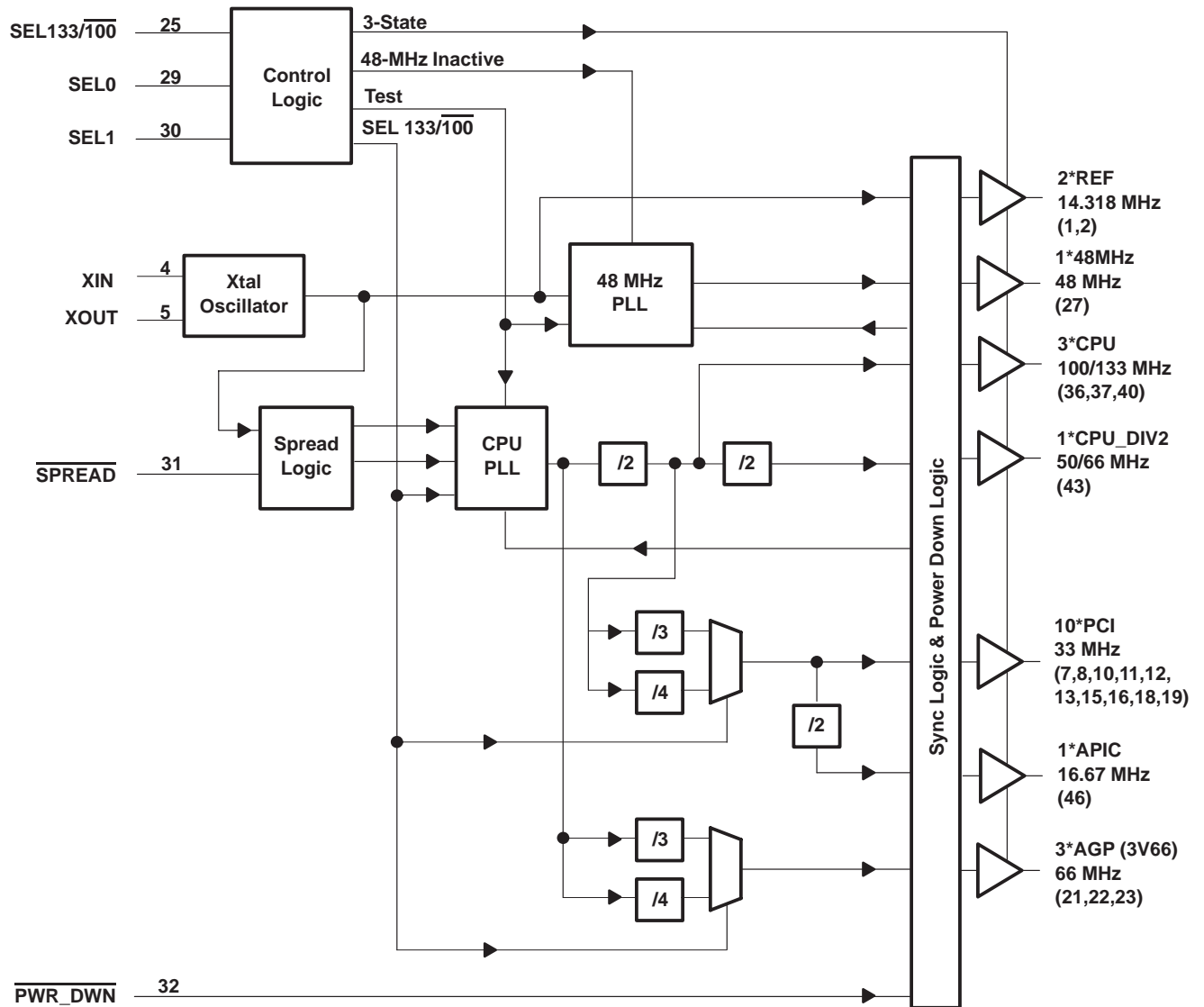
Figure 2. SSC Modulation Profile

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functional block diagram



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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

| | |
|--|----------------------------|
| Supply voltage range, V_{DD} | –0.5 V to 4.6 V |
| Input voltage range, V_I (see Note 1) | –0.5 V to 4.6 V |
| Voltage range applied to any output in the high-impedance state or power-off state, V_O (see Note 1) | –0.5 V to $V_{DD} + 0.5$ V |
| Current into any output in the low state, I_O | $2 \times I_{OL}$ |
| Input clamp current, I_{IK} ($V_I < 0$) | –18 mA |
| Output clamp current, I_{OK} ($V_O < 0$) | –50 mA |
| Operating free-air temperature range, T_A | –0°C to 85°C |
| Storage temperature range, T_{stg} | –65°C to 150°C |
| Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds | 260°C |

† Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

DISSIPATION RATING TABLE

| PACKAGE | $T_A \leq 25^\circ\text{C}$ POWER RATNG | DERATING FACTORT ABOVE $T_A = 25^\circ\text{C}$ | $T_A = 70^\circ\text{C}$ POWER RATING | $T_A = 85^\circ\text{C}$ POWER RATING |
|---------|--|--|--|--|
| DL | 1315.7 mW | 10.53 mW/°C | 842.1 mW | 684.2 mW |

† This is the inverse of the traditional junction-to-case thermal resistance ($R_{\theta JA}$) and uses a board-mounted device at 95°C/W.

recommended operating conditions (see Note 2)

| | | MIN | NOM† | MAX | UNIT |
|--|--------------------|-------------|--------|------------------|------|
| Supply voltage, V_{DD} | 3.3 V | 3.135 | | 3.465 | V |
| | 2.5 V | 2.375 | | 2.625 | |
| High-level input voltage, V_{IH} | | 2 | | $V_{DD} + 0.3$ V | V |
| Low-level input voltage, V_{IL} | | GND – 0.3 V | | 0.8 | V |
| Input voltage, V_I | | 0 | | V_{DD} | V |
| High-level output current, I_{OH} | CPUx, CPU_DIV2 | | | –12 | mA |
| | APIC | | | –12 | |
| | 48MHz, REFx | | | –14 | |
| | PCIx, PCI_F, 3V66x | | | –18 | |
| Low-level output current, I_{OL} | CPUx, CPU_DIV2 | | | 12 | mA |
| | APIC | | | 12 | |
| | 48MHz, REFx | | | 9 | |
| | PCIx, PCI_F, 3V66x | | | 12 | |
| Reference frequency, $f_{(XTAL)}^\ddagger$ | Test mode | | 130 | | MHz |
| Crystal frequency, $f_{(XTAL)}^\S$ | Normal mode | 13.8 | 14.318 | 14.8 | MHz |
| Operating free-air temperature, T_A | | 0 | | 85 | °C |

NOTE 2: Unused inputs must be held high or low to prevent them from floating.

† All nominal values are measured at their respective nominal V_{DD} values.

‡ Reference frequency is a test clock driven on the XIN input during the device test mode and normal mode. In test mode, XIN can be driven externally up to $f_{(XTAL)} = 130$ MHz. If XIN is driven externally, XOUT is floating.

§ This is a series fundamental crystal with $f_O = 14.31818$ MHz.



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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | MIN | TYP† | MAX | UNIT | |
|-------------------------|-------------------------------------|---|---------------------------|------|------|------|----|
| V _{IK} | Input clamp voltage | V _{DD} = 3.135 V, I _I = -18 mA | | | -1.2 | V | |
| R _I | Input resistance | XIN, XOUT V _{DD} = 3.465 V, V _I = V _{DD} - 0.5 V | 80 | | 350 | kΩ | |
| I _{IH} | High-level input current | XOUT V _{DD} = 3.135 V, V _I = V _{DD} - 0.5 V | | 20 | 50 | mA | |
| | | SEL0, SEL1, SPREAD V _{DD} = 3.465 V, V _I = V _{DD} | | <10 | 10 | μA | |
| | | PWR_DWN V _{DD} = 3.465 V, V _I = V _{DD} | | <10 | 10 | μA | |
| | | SEL133/100 V _{DD} = 3.465 V, V _I = V _{DD} | | <10 | 10 | μA | |
| I _{IL} | Low-level input current | XOUT V _{DD} = 3.135 V, V _I = 0 V | | -2 | -5 | mA | |
| | | SEL0, SEL1, SPREAD V _{DD} = 3.465 V, V _I = GND | | <10 | -10 | μA | |
| | | PWR_DWN V _{DD} = 3.465 V, V _I = GND | | <10 | -10 | μA | |
| | | SEL133/100 V _{DD} = 3.465 V, V _I = GND | | <10 | -10 | μA | |
| I _{OZ} | High-impedance-state output current | V _{DD} = max, V _O = V _{DD} or GND | | | ±10 | μA | |
| I _{DD} | Supply current | V _{DD} = 2.625 V, All outputs = low, PWR_DWN = low | | <20 | 100 | μA | |
| | | V _{DD} = 2.625 V, All outputs = high | | <20 | 100 | μA | |
| | | V _{DD} = 3.465 V, All outputs = low, PWR_DWN = low | | <50 | 200 | μA | |
| | | V _{DD} = 3.465 V, All outputs = high | | 12 | 37 | mA | |
| I _{DD(Z)} | High-impedance-state supply current | V _{DD} = 2.625 V | | | 1.4 | mA | |
| | | V _{DD} = 3.465 V | | | 30 | | |
| Dynamic I _{DD} | | C _L = 20 pF, CPU = 133 MHz | V _{DD} = 3.465 V | | 114 | 156 | mA |
| | | | V _{DD} = 2.625 V | | 44 | 60 | |
| C _I | Input capacitance | V _{DD} = 3.3 V, V _I = V _{DD} or GND | 3.3 | | 5.8 | pF | |
| | Crystal terminal capacitance | V _{DD} = 3.3 V, V _I = 0.3 V | 18 | 18.5 | 22.5 | pF | |

† All typical values are measured at their respective nominal V_{DD} values.



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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (continued)

CPUx, CPU_DIV2, APIC (Type 1)

| PARAMETER | | TEST CONDITIONS | MIN | TYP† | MAX | UNIT |
|-----------------|---------------------------|--|-------------------------|------|-----|------|
| V _{OH} | High-level output voltage | V _{DD} = min to max, I _{OH} = -1 mA | V _{DD} - 0.1 V | | | V |
| | | V _{DD} = 2.375 V, I _{OH} = -12 mA | 2 | | | |
| V _{OL} | Low-level output voltage | V _{DD} = min to max, I _{OL} = 1 mA | | | 0.1 | V |
| | | V _{DD} = 2.375 V, I _{OL} = 12 mA | | 0.18 | 0.4 | |
| I _{OH} | High-level output current | V _{DD} = 2.375 V, V _O = 1 V | -26 | -42 | | mA |
| | | V _{DD} = 2.5 V, V _O = 1.25 V | | -46 | | |
| | | V _{DD} = 2.625 V, V _O = 2.375 V | | -16 | -27 | |
| I _{OL} | Low-level output current | V _{DD} = 2.375 V, V _O = 1.2 V | 27 | 57 | | mA |
| | | V _{DD} = 2.5 V, V _O = 1.25 V | | 63 | | |
| | | V _{DD} = 2.625 V, V _O = 0.3 V | | 23 | 43 | |
| C _O | Output capacitance | V _{DD} = 3.3 V, V _O = V _{DD} or GND | 5.8 | | 8.5 | pF |
| Z _O | Output impedance | High state V _O = 0.5 V _{DD} , V _O /I _{OH} | 13.5 | 27 | 45 | Ω |
| | | Low state V _O = 0.5 V _{DD} , V _O /I _{OL} | 13.5 | 20 | 45 | |

† All typical values are measured at their respective nominal V_{DD} values.

48MHz, REFx (Type 3)

| PARAMETER | | TEST CONDITIONS | MIN | TYP† | MAX | UNIT |
|-----------------|---------------------------|--|-------------------------|------|-----|------|
| V _{OH} | High-level output voltage | V _{DD} = min to max, I _{OH} = -1 mA | V _{DD} - 0.1 V | | | V |
| | | V _{DD} = 3.135 V, I _{OH} = -14 mA | 2.4 | | | |
| V _{OL} | Low-level output voltage | V _{DD} = min to max, I _{OL} = 1 mA | | | 0.1 | V |
| | | V _{DD} = 3.135 V, I _{OL} = 9 mA | | 0.18 | 0.4 | |
| I _{OH} | High-level output current | V _{DD} = 3.135 V, V _O = 1 V | -27 | -41 | | mA |
| | | V _{DD} = 3.3 V, V _O = 1.65 V | | -41 | | |
| | | V _{DD} = 3.465 V, V _O = 3.135 V | | -12 | -23 | |
| I _{OL} | Low-level output current | V _{DD} = 3.135 V, V _O = 1.95 V | 29 | 50 | | mA |
| | | V _{DD} = 3.3 V, V _O = 1.65 V | | 53 | | |
| | | V _{DD} = 3.465 V, V _O = 0.4 V | | 20 | 37 | |
| C _O | Output capacitance | V _{DD} = 3.3 V, V _O = V _{DD} or GND | 4.5 | | 7 | pF |
| Z _O | Output impedance | High state V _O = 0.5 V _{DD} , V _O /I _{OH} | 20 | 40 | 60 | Ω |
| | | Low state V _O = 0.5 V _{DD} , V _O /I _{OL} | 20 | 31 | 60 | |

† All typical values are measured at their respective nominal V_{DD} values.



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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (continued)

PC1x, 3V66x (Type 5)

| PARAMETER | | TEST CONDITIONS | MIN | TYP† | MAX | UNIT |
|-----------------|---------------------------|--|-------------------------|------|-----|------|
| V _{OH} | High-level output voltage | V _{DD} = min to max, I _{OH} = –1 mA | V _{DD} – 0.1 V | | | V |
| | | V _{DD} = 3.135 V, I _{OH} = –18 mA | 2.4 | | | |
| V _{OL} | Low-level output voltage | V _{DD} = min to max, I _{OL} = 1 mA | | | 0.1 | V |
| | | V _{DD} = 3.135 V, I _{OL} = 12 mA | | 0.15 | 0.4 | |
| I _{OH} | High-level output current | V _{DD} = 3.135 V, V _O = 1 V | –33 | –53 | | mA |
| | | V _{DD} = 3.3 V, V _O = 1.65 V | | –53 | | |
| | | V _{DD} = 3.465 V, V _O = 3.135 V | | –16 | –33 | |
| I _{OL} | Low-level output current | V _{DD} = 3.135 V, V _O = 1.95 V | 30 | 67 | | mA |
| | | V _{DD} = 3.3 V, V _O = 1.65 V | | 70 | | |
| | | V _{DD} = 3.465 V, V _O = 0.4 V | | 27 | 49 | |
| C _O | Output capacitance | V _{DD} = 3.3 V, V _O = V _{DD} or GND | 4.5 | | 7.5 | pF |
| Z _O | Output impedance | High state V _O = 0.5 V _{DD} , V _O /I _{OH} | 12 | 31 | 55 | Ω |
| | | Low state V _O = 0.5 V _{DD} , V _O /I _{OL} | 12 | 24 | 55 | |

† All typical values are measured at their respective nominal V_{DD} values.

switching characteristics, V_{DD} = 3.135 V to 3.465 V, T_A = 0°C to 85°C

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--|--|------------------|-------------------------|------|-------------------------|------|
| Overshoot/undershoot | | | GND – 0.7 V | | V _{DD} + 0.7 V | V |
| Ring back | | | V _{IL} – 0.1 V | | V _{IH} + 0.1 V | V |
| Stabilization time, $\overline{\text{PWR_DWN}}$ to PC1x | | f(CPU) = 133 MHz | | 0.05 | 3 | ms |
| t _{dis3} | Disable time, $\overline{\text{PWR_DWN}}$ to PC1x | f(CPU) = 133 MHz | | 50 | | ns |
| Stabilization time, $\overline{\text{PWR_DWN}}$ to CPUx | | f(CPU) = 133 MHz | | 0.03 | 3 | ms |
| t _{dis4} | Disable time, $\overline{\text{PWR_DWN}}$ to CPUx | f(CPU) = 133 MHz | | 50 | | ns |
| Stabilization time† | | After SEL1, SEL0 | | | 3 | ms |
| | | After power up | | | 3 | |

† Stabilization time is the time required for the integrated PLL circuit to obtain phase lock of its feedback signal to its reference signal. In order for phase lock to be obtained, a fixed-frequency, fixed-phase reference signal must be present at X1. Until phase lock is obtained, the specifications for propagation delay and skew parameters given in the switching characteristics tables are not applicable. Stabilization time is defined as the time from when V_{DD} achieves its nominal operating level until the output frequency is stable and operating within specification.

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switching characteristics, $V_{DD} = 2.375\text{ V to }2.625\text{ V}$, $T_A = 0^\circ\text{C to }85^\circ\text{C}$ (continued)

CPUx

| PARAMETER | | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------|---|------------------|------------------|---|-----|-------|------|------|
| t_{en1} | Output enable time | SEL133/100 | CPUx | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | 6 | 10 | ns |
| t_{dis1} | Output disable time | SEL133/100 | CPUx | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | 8 | 10 | ns |
| t_c | CPU clock period [†] | | | $f_{(CPU)} = 100\text{ MHz}$ | 10 | 10.04 | 10.2 | ns |
| | | | | $f_{(CPU)} = 133\text{ MHz}$ | 7.5 | 7.53 | 7.7 | ns |
| Cycle to cycle jitter | | | | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | | 250 | ps |
| Duty cycle | | | | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | 45 | | 55 | % |
| $t_{sk(o)}$ | CPU bus skew | CPUx | CPUx | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | 50 | 175 | ps |
| $t_{sk(p)}$ | CPU pulse skew | CPU _n | CPU _n | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | | 2.2 | ns |
| $t_{(off)}$ | CPU clock to APIC clock offset, rising edge | | | | 1.5 | 2.8 | 4 | ns |
| $t_{(off)}$ | CPU clock to 3V66 clock offset, rising edge | | | | 0 | 0.75 | 1.5 | ns |
| t_{w1} | Pulse duration width, high | | | $f_{(CPU)} = 100\text{ MHz}$ | 2.6 | 4.3 | | ns |
| | | | | $f_{(CPU)} = 133\text{ MHz}$ | 1.4 | 3.7 | | |
| t_{w2} | Pulse duration width, low | | | $f_{(CPU)} = 100\text{ MHz}$ | 2.8 | 4.3 | | ns |
| | | | | $f_{(CPU)} = 133\text{ MHz}$ | 1.7 | 4 | | |
| t_r | Rise time | | | $V_O = 0.4\text{ V to }2.0\text{ V}$ | 0.4 | 1.5 | 2.2 | ns |
| t_f | Fall time | | | $V_O = 0.4\text{ V to }2.0\text{ V}$ | 0.4 | 1.4 | 2 | ns |

[†] The average over any 1- μs period of time is greater than the minimum specified period.

CPU_DIV2

| PARAMETER | | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------|------------------------------------|--------------|-------------|---|-----|-------|------|------|
| t_{en1} | Output enable time | SEL133/100 | CPU_DIV2 | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | 6 | 10 | ns |
| t_{dis1} | Output disable time | SEL133/100 | CPU_DIV2 | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | 8 | 10 | ns |
| t_c | CPU_DIV2 clock period [†] | | | $f_{(CPU)} = 100\text{ MHz}$ | 20 | 20.08 | 20.4 | ns |
| | | | | $f_{(CPU)} = 133\text{ MHz}$ | 15 | 15.06 | 15.3 | ns |
| Cycle to cycle jitter | | | | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | | 250 | ps |
| Duty cycle | | | | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | 45 | | 55 | % |
| $t_{sk(p)}$ | CPU_DIV2 pulse skew | | | $f_{(CPU)} = 100\text{ or }133\text{MHz}$ | | | 1.6 | ns |
| t_{w1} | Pulse duration width, high | | | $f_{(CPU)} = 100\text{ MHz}$ | 7.1 | | | ns |
| | | | | $f_{(CPU)} = 133\text{ MHz}$ | 4.7 | | | |
| t_{w2} | Pulse duration width, low | | | $f_{(CPU)} = 100\text{ MHz}$ | 7.3 | 8.9 | | ns |
| | | | | $f_{(CPU)} = 133\text{ MHz}$ | 5 | 6.6 | | |
| t_r | Rise time | | | $V_O = 0.4\text{ V to }2.0\text{ V}$ | 0.4 | 1.4 | 2 | ns |
| t_f | Fall time | | | $V_O = 0.4\text{ V to }2.0\text{ V}$ | 0.4 | 1.3 | 1.8 | ns |

[†] The average over any 1- μs period of time is greater than the minimum specified period.



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switching characteristics, $V_{DD} = 2.375\text{ V to }2.625\text{ V}$, $T_A = 0^\circ\text{C to }85^\circ\text{C}$ (continued)

APIC

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------|---|-------------|-----------------|--|-----|-----|------|
| t_{en1} | Output enable time | SEL133/100 | APIC | $f_{(APIC)} = 16.67\text{ MHz}$ | | | ns |
| t_{dis1} | Output disable time | SEL133/100 | APIC | $f_{(APIC)} = 16.67\text{ MHz}$ | | | ns |
| t_c | APIC clock period† | | | $f_{(APIC)} = 16.67\text{ MHz}$ | | | ns |
| | Cycle to cycle jitter | | | $f_{(CPU)} = 100\text{ or }133\text{ MHz}$ | | | ps |
| | Duty cycle | | | $f_{(APIC)} = 16.67\text{ MHz}$ | | | % |
| $t_{sk(p)}$ | APIC pulse skew | | | $f_{(APIC)} = 16.67\text{ MHz}$ | | | ns |
| $t_{(off)}$ | APIC clock to CPU clock offset, rising edge | APIC | CPUx | | | | ns |
| t_{w1} | Pulse duration width, high | | | $f_{(APIC)} = 16.67\text{ MHz}$ | | | ns |
| t_{w2} | Pulse duration width, low | | | $f_{(APIC)} = 16.67\text{ MHz}$ | | | ns |
| t_r | Rise time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | | ns |
| t_f | Fall time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | | ns |

† The average over any 1- μs period of time is greater than the minimum specified period.

switching characteristics, $V_{DD} = 3.135\text{ V to }3.465\text{ V}$, $T_A = 0^\circ\text{C to }85^\circ\text{C}$

3V66

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------|---|-------------|-----------------|--|-----|-----|------|
| t_{en1} | Output enable time | SEL133/100 | 3V66x | $f_{(3V66)} = 66\text{ MHz}$ | | | ns |
| t_{dis1} | Output disable time | SEL133/100 | 3V66x | $f_{(3V66)} = 66\text{ MHz}$ | | | ns |
| t_c | 3V66 clock period† | | | $f_{(3V66)} = 66\text{ MHz}$ | | | ns |
| | Cycle to cycle jitter | | | $f_{(CPU)} = 100\text{ or }133\text{ MHz}$ | | | ps |
| | Duty cycle | | | $f_{(3V66)} = 66\text{ MHz}$ | | | % |
| $t_{sk(o)}$ | 3V66 bus skew | 3V66x | 3V66x | $f_{(3V66)} = 66\text{ MHz}$ | | | ps |
| $t_{sk(p)}$ | 3V66 pulse skew | 3V66n | 3V66n | $f_{(3V66)} = 66\text{ MHz}$ | | | ns |
| $t_{(off)}$ | 3V66 clock to CPU clock offset | 3V66x | CPUx | | | | ns |
| $t_{(off)}$ | 3V66 clock to PCI clock offset, rising edge | | | | | | ns |
| t_{w1} | Pulse duration width, high | | | $f_{(3V66)} = 66\text{ MHz}$ | | | ns |
| t_{w2} | Pulse duration width, low | | | $f_{(3V66)} = 66\text{ MHz}$ | | | ns |
| t_r | Rise time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | | ns |
| t_f | Fall time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | | ns |

† The average over any 1- μs period of time is greater than the minimum specified period.



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switching characteristics, $V_{DD} = 3.135\text{ V to }3.465\text{ V}$, $T_A = 0^\circ\text{C to }85^\circ\text{C}$ (continued)

48MHz

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------|---------------------------------|-------------|-----------------|---|-----|-----------------|------|
| t_{en1} | Output enable time | SEL133/100 | 48MHz | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 6 10 | ns |
| t_{dis1} | Output disable time | SEL133/100 | 48MHz | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 8 10 | ns |
| t_c | 48MHz clock period [†] | | | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 20.5 20.83 21.1 | ns |
| | Cycle to cycle jitter | | | $f_{(\text{CPU})} = 100\text{ or }133\text{ MHz}$ | | 500 | ps |
| | Duty cycle | | | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 45 55 | % |
| $t_{sk(p)}$ | 48MHz pulse skew | 48MHz | 48MHz | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 3 | ns |
| t_{w1} | Pulse duration width, high | | | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 7.8 | ns |
| t_{w2} | Pulse duration width, low | | | $f_{(48\text{MHz})} = 48\text{ MHz}$ | | 7.8 | ns |
| t_r | Rise time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | 1 2.1 2.8 | ns |
| t_f | Fall time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | 1 1.9 2.8 | ns |

[†] The average over any 1- μs period of time is greater than the minimum specified period.

REF

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------|-------------------------------|-------------|-----------------|---|-----|-----------|------|
| t_{en1} | Output enable time | SEL133/100 | REFx | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 6 10 | ns |
| t_{dis1} | Output disable time | SEL133/100 | REFx | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 8 10 | ns |
| t_c | REF clock period [†] | | | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 69.84 | ns |
| | Cycle to cycle jitter | | | $f_{(\text{CPU})} = 100\text{ or }133\text{ MHz}$ | | 700 | ps |
| | Duty cycle | | | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 45 55 | % |
| $t_{sk(o)}$ | REF bus skew | REFx | REFx | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 150 250 | ps |
| $t_{sk(p)}$ | REF pulse skew | REFn | REFn | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 2 | ns |
| t_{w1} | Pulse duration width, high | | | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 26.2 32.7 | ns |
| t_{w2} | Pulse duration width, low | | | $f_{(\text{REF})} = 14.318\text{ MHz}$ | | 26.2 31.2 | ns |
| t_r | Rise time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | 1 2 2.8 | ns |
| t_f | Fall time | | | $V_O = 0.4\text{ V to }2\text{ V}$ | | 1 1.9 2.8 | ns |

[†] The average over any 1- μs period of time is greater than the minimum specified period.



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switching characteristics, $V_{DD} = 3.135\text{ V to }3.465\text{ V}$, $T_A = 0^\circ\text{C to }85^\circ\text{C}$ (continued)

PCI

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------|---------------------------------|-------------|--|-----------------------------|-------|------|------|
| t_{en1} | Output enable time | SEL133/100 | PCIx | | 6 | 10 | ns |
| t_{dis1} | Output disable time | SEL133/100 | PCIx | $f_{(PCI)} = 33\text{ MHz}$ | 8 | 10 | ns |
| t_c | PCIx clock period [†] | | | | | | |
| | Cycle to cycle jitter | | $f_{(CPU)} = 100\text{ or }133\text{ MHz}$ | 30 | 30.12 | 30.5 | ns |
| | Duty cycle | | $f_{(PCI)} = 33\text{ MHz}$ | | | 300 | ps |
| | | | | 45 | | 55 | % |
| $t_{sk(o)}$ | PCIx bus skew | PCIx | PCIx | $f_{(PCI)} = 33\text{ MHz}$ | 70 | 300 | ps |
| $t_{sk(p)}$ | PCIx pulse skew | PCIn | PCIn | $f_{(PCI)} = 33\text{ MHz}$ | | 4 | ns |
| $t_{(off)}$ | PCIx clock to 3V66 clock offset | | | | -1.2 | -3 | ns |
| t_{w1} | Pulse duration width, high | | $f_{(PCI)} = 33\text{ MHz}$ | 12 | | | ns |
| t_{w2} | Pulse duration width, low | | $f_{(PCI)} = 33\text{ MHz}$ | 12 | | | ns |
| t_r | Rise time | | $V_O = 0.4\text{ V to }2\text{ V}$ | 0.5 | 1.6 | 2 | ns |
| t_f | Fall time | | $V_O = 0.4\text{ V to }2\text{ V}$ | 0.5 | 1.5 | 2 | ns |

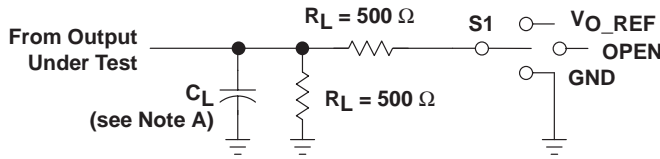
[†] The average over any 1- μs period of time is greater than the minimum specified period.



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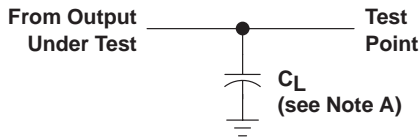
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PARAMETER MEASUREMENT INFORMATION

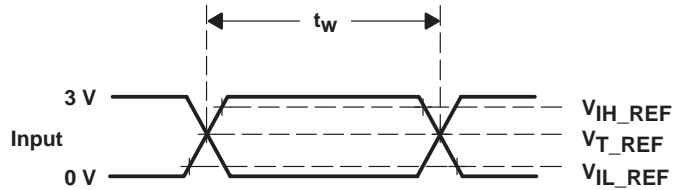


| TEST | S1 |
|-----------|--------|
| tPLH/tPHL | Open |
| tPLZ/tPZL | VO_REF |
| tPHZ/tPZH | GND |

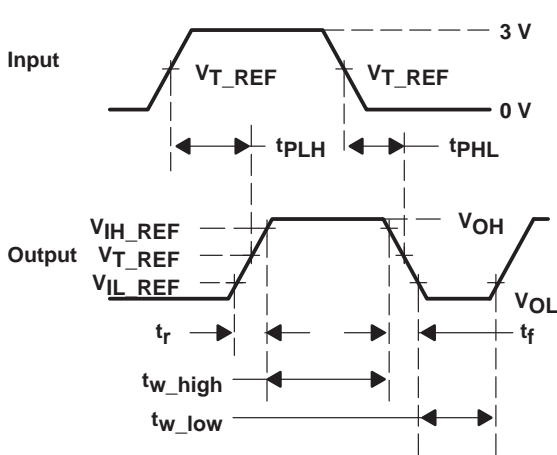
LOAD CIRCUIT for t_{pd} and t_{sk}



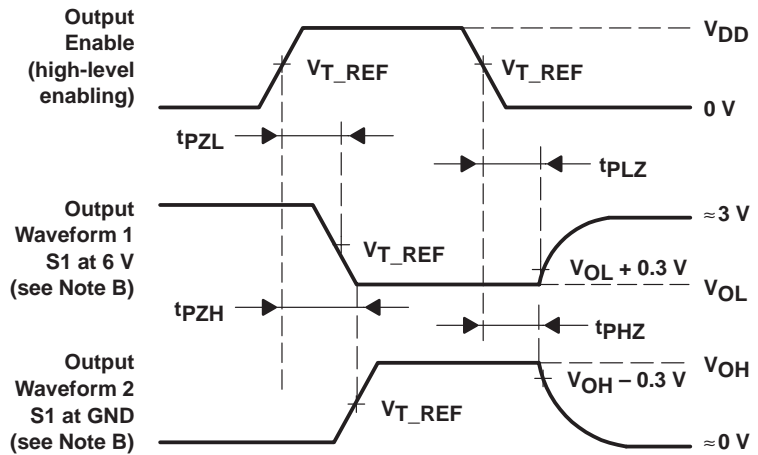
LOAD CIRCUIT FOR t_r and t_f



VOLTAGE WAVEFORMS



VOLTAGE WAVEFORMS



VOLTAGE WAVEFORMS

- NOTES: A. C_L includes probe and jig capacitance. $C_L = 20$ pF (CPUx, APIC, 48MHz, REF), $C_L = 30$ pF (PC1x)
 B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
 C. All input pulses are supplied by generators having the following characteristics: $PRR \leq 14.318$ MHz, $Z_O = 50 \Omega$, $t_r \leq 2.5$ ns, $t_f \leq 2.5$ ns.
 D. The outputs are measured one at a time with one transition per measurement.

| PARAMETER | | 3.3-V INTERFACE | 2.5-V INTERFACE | UNIT |
|-----------|-----------------------------------|-----------------|-----------------|------|
| VIH_REF | High-level reference voltage | 2.4 | 2 | V |
| VIL_REF | Low-level reference voltage | 0.4 | 0.4 | V |
| VT_REF | Input Threshold reference voltage | 1.5 | 1.25 | V |
| VO_REF | Off-state reference voltage | 6 | 4.6 | V |

Figure 3. Load Circuit and Voltage Waveforms

PARAMETER MEASUREMENT INFORMATION

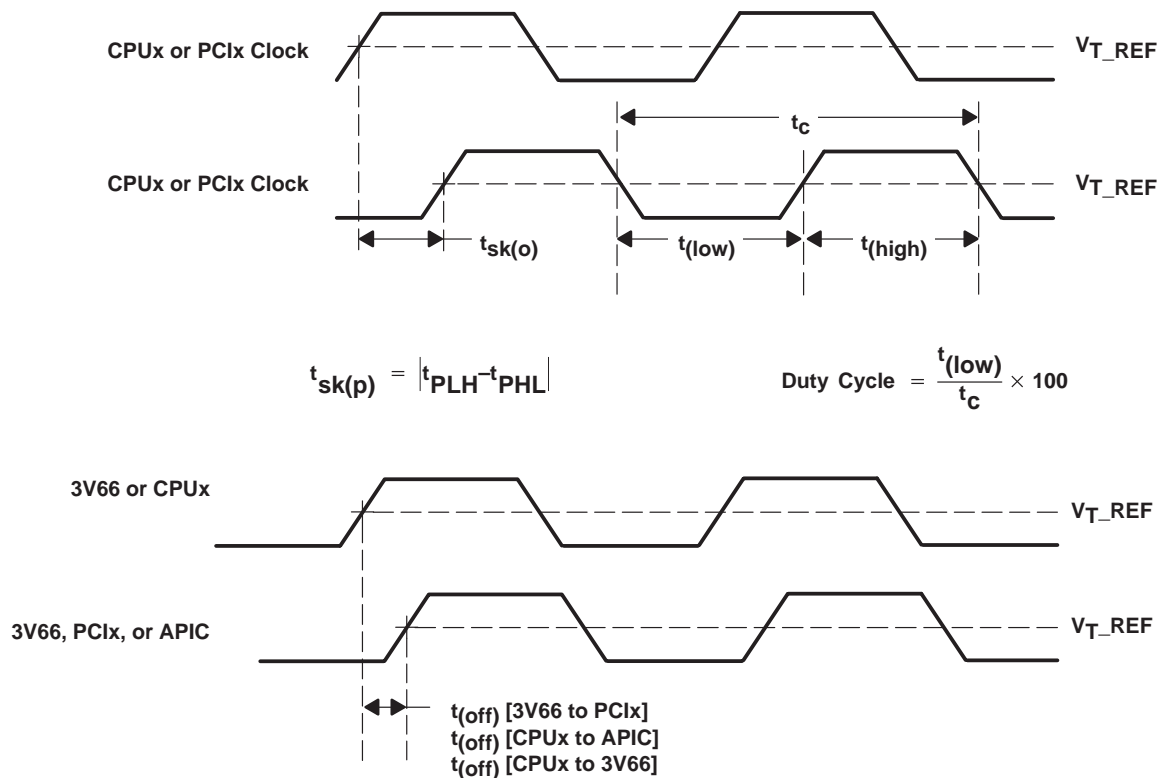
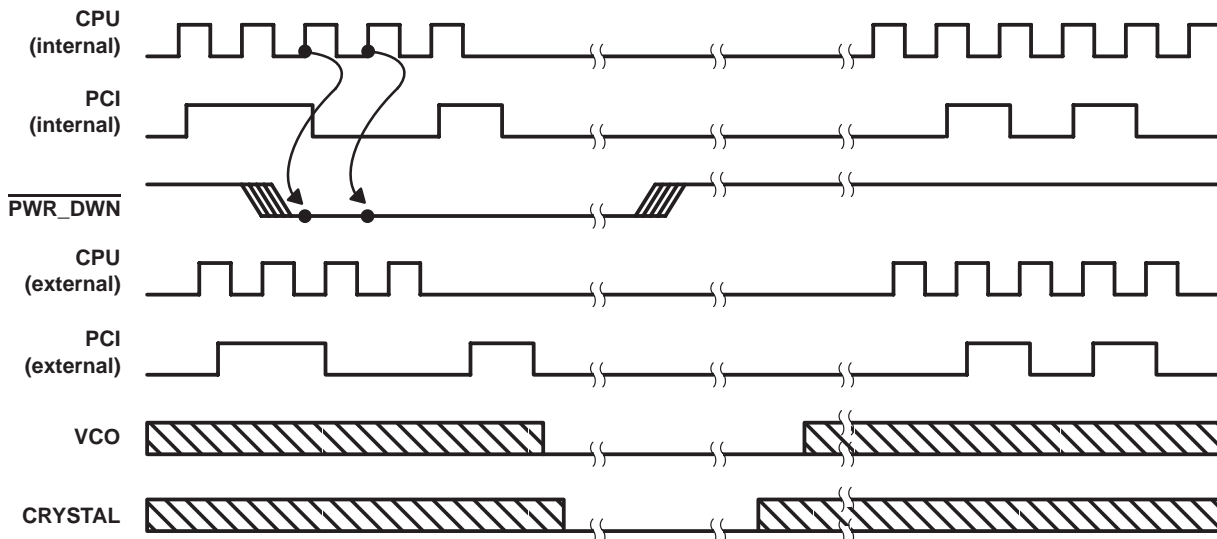


Figure 4. Waveforms for Calculation of Skew, Offset, and Jitter



NOTE A: Shaded sections on the VCO and Crystal waveforms indicate that the VCO and crystal oscillators are active and there is a valid clock.

Figure 5. Power-Down Timing

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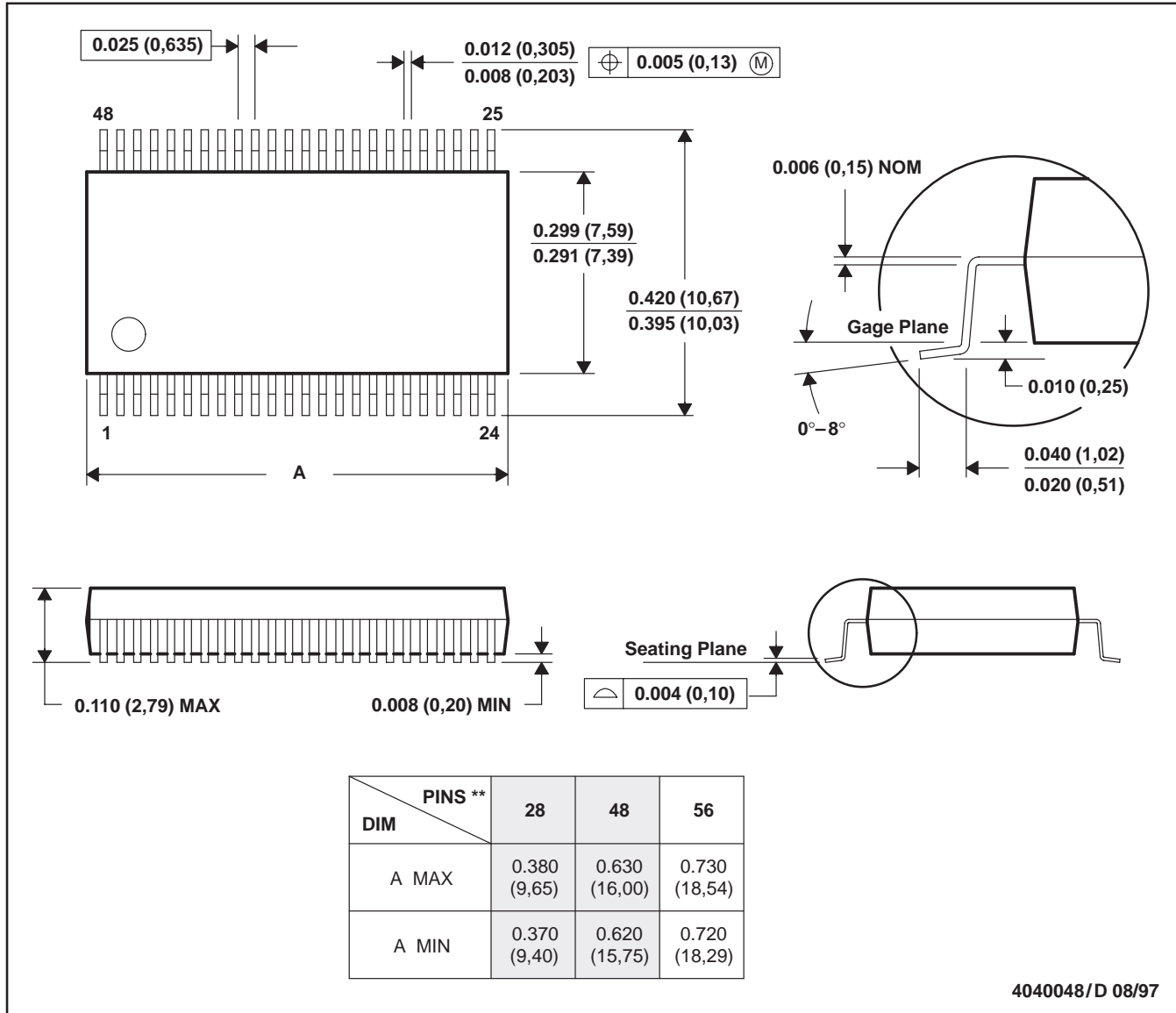
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MECHANICAL DATA

DL (R-PDSO-G)**

PLASTIC SMALL-OUTLINE PACKAGE

48-PIN SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).
 B. This drawing is subject to change without notice.
 C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
 D. Falls within JEDEC MO-118

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