



AKD4683-B

AK4683 Evaluation Board Rev.0

FEATURE

AKD4683-B is an evaluation board for AK4683, a single chip 24bit CODEC that has two channels of ADC and four channels of DAC with internal DIR, DIT. This board has interfaces with AKM's evaluation boards for A/D converter and D/A converter and makes easy to evaluate AK4683. Also this board has the digital audio interface and then achieves the interface with digital audio systems via opt-connector or RCA connector.

■ **Ordering guide**

AKD4683-B --- AK4683 Evaluation Board

10 wire flat cable for connection with printer port of PC (IBM-AT compatible machine), control software for AK4683, driver for control software on Windows 2000/XP are packed with this.

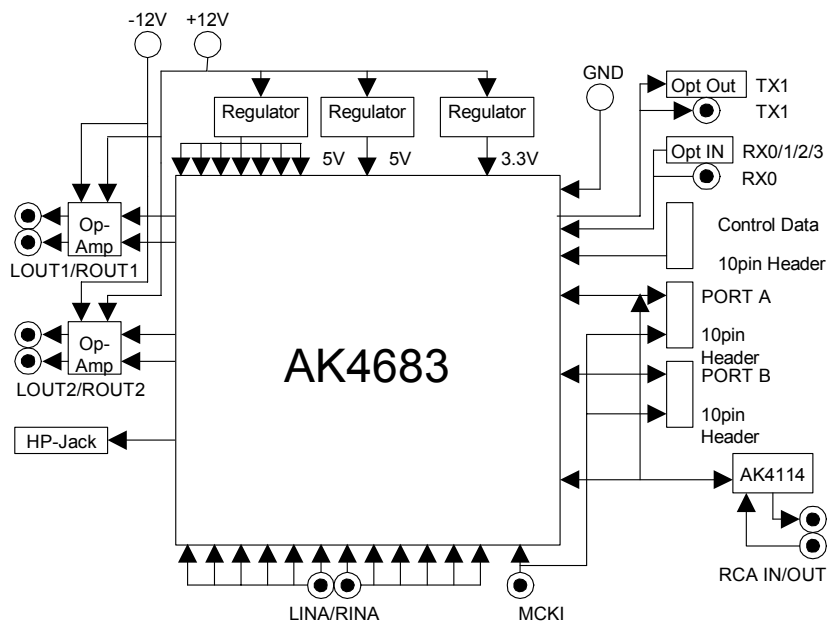
Control software does not work on Windows NT

Windows 2000/XP needs an installation of driver.

Windows 95/98/ME does not need an installation of driver.

FUNCTION

- On-board clock generator (use AK4114)
- Compatible with 2 types of digital audio interface
 - Optical output/input and RCA input/output
 - 10pin header for interface with external data source (x2)
- RCA connector for clock input with external clock source
- 10pin header for register control



(Note) AK4114 has DIR, DIT and X'tal oscillator.

Figure 1. AKD4683-B Block Diagram

(* Circuit diagram and PCB layout are attached at the end of this manual.)

EVALUATION BOARD MANUAL

■ Operating sequence

(1) **Set up power supply lines.**

[+12V]	(Orange) = +12V
[-12V]	(Blue) = -12V
[AVSS1]	(Black) = 0V
[AVSS2]	(Black) = 0V
[DVSS]	(Black) = 0V
[PVSS]	(Black) = 0V
[HVSS]	(Black) = 0V
[DGND]	(Black) = 0V

Each supply line should be distributed from the power supply unit.

(2) **Set up evaluation mode and jumper pins.** (Refer to the following item.)

(3) **Connect cables.** (Refer to the following item.)

(4) **Power on.**

The AK4683 should be reset once bringing PDN (SW3) “L” upon power-up.

(5) **Set up control software registers.** (Refer to the following item.)

■ Evaluation modes

(1) DAC with internal DIR

1. Connection of connector

In case of digital input through RX0, optical connector PORT5 (TORX176) or RCA connector J14 (RX0) are available. In case of digital input through RX1, RX2 or RX3, only the optical connector PORT5 is available.

2. Setting of jumper pin

RX0 and RX1-3 should not select optical connector at the same time.

In case of digital input through RX1, RX2 or RX3, set jumpers JP32 (RX1), JP34 (RX2) or JP36 (RX3) as Table 2. Set unused channels to GND.

Connector	JP33 (RX0)	Default
Optical (PORT5)	OPT	
RCA (J14)	RCA	

Table 1. Set-up of RX0

Input	JP32 (RX1)	JP34 (RX2)	JP36 (RX3)
RX1	OPT	GND	GND
RX2	GND	OPT	GND
RX3	GND	GND	OPT

Table 2. Set-up of RX1, RX2, and RX3

3. Setting of toggle switch

Set SW1 (AK4114-PDN) to OFF.

(2) ADC with internal DIT

1. Connection of connector

For digital output, optical connector PORT3 (TOTX176) or RCA connector J13 (TX1) are available.

2. Setting of jumper pin

JP30 (TX1) controls digital output (optical connector PORT3 or RCA connector J13).

Connector	JP30(TX)	Default
Optical (PORT3)	OPT	
RCA (J13)	RCA	

Table 3. Set-up of TX

3. Setting of toggle switch

Set SW1 (AK4114-PDN) to OFF.

(3) DAC with external DIR

1. Connection of connector

For digital input, RCA connector J10 (AK4114-RX0) is available.

2. Setting of jumper pin

Setting of interface signal of PORTA/PORTB: AK4114 (U5) is as follows.
(Default input of PORTA is SDTIA1.)

PORT	JP22 (BICKA)	JP24 (OLRCKA)	JP16 (ILRCKA)	JP17 (SDTIA1)	JP19 (SDTIA2)	JP20 (SDTIA3)
PORTA	Short	Open	Short	DIR	GND	GND
PORTB	Open	Open	Open	GND	GND	GND

Table 4. Set-up of AK4114 interface (1/2)

PORT	JP27 (BICKB)	JP28 (LRCKB)	JP25 (SDTIB)	JP21 (MCLK-SEL)	JP29 (MCLK)	JP15 (XTIA)	JP23 (SDTO)
PORTA	Open	Open	GND	MCKO1	Open	Open	SDTOA
PORTB	Short	Short	DIR	MCKO1	Open	Open	SDTOB

Table 5. Set-up of AK4114 interface (2/2)

3. Setting of toggle switch

Set SW1 (AK4114-PDN) to ON.

4. Setting of DIP switch

Set SW2 (PORTA-DIR/4683): 2pin (DIF1) to OFF.

(4) ADC with external DIT

1. Connection of connector

For digital output, RCA connector J11 (AK4114-TX1) is available.

2. Setting of jumper pin

Setting of interface signal of PORTA/PORTB: AK4114 (U5) is as follows.

PORT	JP22 (BICKA)	JP24 (OLRCKA)	JP16 (ILRCKA)	JP17 (SDTIA1)	JP19 (SDTIA2)	JP20 (SDTIA3)
PORTA	Short	Short	Open	GND	GND	GND
PORTB	Open	Open	Open	GND	GND	GND

Table 6. Set-up of AK4114 interface (1/2)

PORT	JP27 (BICKB)	JP28 (LRCKB)	JP25 (SDTIB)	JP21 (MCLK-SEL)	JP29 (MCLK)	JP15 (XTIA)	JP23 (SDTO)
PORTA	Open	Open	GND	Open	Open	Short	SDTOA
PORTB	Short	Short	GND	Open	Open	Short	SDTOB

Table 7. Set-up of AK4114 interface (2/2)

3. Setting of toggle switch

Set SW1 (AK4114-PDN) to ON.

4. Setting of DIP switch

Set SW2 (PORTA-DIR/4683): 4pin (CM0) to ON.

(5) Internal loop back (Analog input → ADC → DAC → Analog output)

1. Connection of connector

For analog input, RCA connector J3 (LINA)/ J6 (RINA) are available.

For analog output, RCA connector J1 (LOUT1)/ J4 (ROUT1), J2 (LOUT2)/ J5 (ROUT2) are available.

2. Setting of jumper pin

Input	JP1 (LIN1)/ JP7 (RIN1)	JP2 (LIN2)/ JP8 (RIN2)	JP3 (LIN3)/ JP9 (RIN3)	JP4 (LIN4)/ JP10 (RIN4)	JP5 (LIN5)/ JP11 (RIN5)	JP6 (LIN6)/ JP12 (RIN6)
LIN1/ RIN1	LINA/ RINA	Open	Open	Open	Open	Open
LIN2/ RIN2	Open	LINA/ RINA	Open	Open	Open	Open
LIN3/ RIN3	Open	Open	LINA/ RINA	Open	Open	Open
LIN4/ RIN4	Open	Open	Open	LINA/ RINA	Open	Open
LIN5/ RIN5	Open	Open	Open	Open	LINA/ RINA	Open
LIN6/ RIN6	Open	Open	Open	Open	Open	LINA/ RINA

(Default)

Table 8. Set-up of LINA/RINA

Input	JP1 (LIN1)/ JP7 (RIN1)	JP2 (LIN2)/ JP8 (RIN2)	JP3 (LIN3)/ JP9 (RIN3)	JP4 (LIN4)/ JP10 (RIN4)	JP5 (LIN5)/ JP11 (RIN5)	JP6 (LIN6)/ JP12 (RIN6)
LIN1/ RIN1	LINB/ RINB	Open	Open	Open	Open	Open
LIN2/ RIN2	Open	LINB/ RINB	Open	Open	Open	Open
LIN3/ RIN3	Open	Open	LINB/ RINB	Open	Open	Open
LIN4/ RIN4	Open	Open	Open	LINB/ RINB	Open	Open
LIN5/ RIN5	Open	Open	Open	Open	LINB/ RINB	Open
LIN6/ RIN6	Open	Open	Open	Open	Open	LINB/ RINB

Table 9. Set-up of LINB/RINB

3. Setting of toggle switch

Set SW1 (AK4114-PDN) to OFF.

■ Register control

AKD4683-B can be controlled via the printer port (parallel port) of IBM-AT compatible PC. Connect PORT4 (uP-I/F) to PC by 10-line flat cable packed with this. Take care of the direction of connector. There is a mark at pin#1. The pin layout of PORT4 is as Figure 2.

Mode	SW2 8
4-wire Serial	L
I2C	H

Table 10. Set-up of Parallel mode and Serial mode

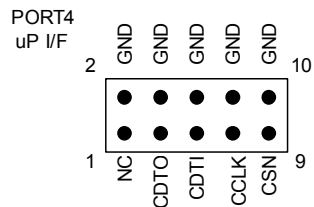


Figure 2. PORT4 pin layout

Control software is packed with this evaluation board. Software operation procedure is included in evaluation board manual.

■ Set-up DIP switch (SW2)

No.	Name	ON (“H”)	OFF (“L”)	Default
1	DIF0	Setting of AK4114 Audio Interface Format (Refer Table 12.)		OFF
2	DIF1			ON
3	DIF2			ON
4	CM0	Selection of AK4114 Clock Mode (Clock Source) (Refer Table 13.)		OFF
5	CM1			OFF
6	OCKS0	Selection of AK4114 Master Clock Output frequency (Refer Table 14.)		OFF
7	OCKS1			OFF
8	I2C	I ² C-bus control mode	4-wire serial control mode	OFF

Table 11. Set up modes of AK4114 (U5) and AK4683 (U1)

Mode	DIF2	DIF1	DIF0	DAUX	SDTO	LRCK		BICK	
							I/O		I/O
0	0	0	0	24bit, Left justified	16bit, Right justified	H/L	O	64fs	O
1	0	0	1	24bit, Left justified	18bit, Right justified	H/L	O	64fs	O
2	0	1	0	24bit, Left justified	20bit, Right justified	H/L	O	64fs	O
3	0	1	1	24bit, Left justified	24bit, Right justified	H/L	O	64fs	O
4	1	0	0	24bit, Left justified	24bit, Left justified	H/L	O	64fs	O
5	1	0	1	24bit, I ² S	24bit, I ² S	L/H	O	64fs	O
6	1	1	0	24bit, Left justified	24bit, Left justified	H/L	I	64-128fs	I
7	1	1	1	24bit, I ² S	24bit, I ² S	L/H	I	64-128fs	I

Table 12. AK4114 Audio Interface Format

Mode	CM1	CM0	UNLOCK	PLL	X'tal	Clock source	SDTO
0	0	0	-	ON	ON (Note1)	PLL	RX
1	0	1	-	OFF	ON	X'tal	DAUX
2	1	0	0	ON	ON	PLL	RX
			1	ON	ON	X'tal	DAUX
3	1	1	-	ON	ON	X'tal	DAUX

Table 13. AK4114 Clock Mode (Clock Source)

No.	OCKS1	OCKS0	MCKO1	MCKO2	X'tal	fs (max)
0	0	0	256fs	256fs	256fs	96 kHz
1	0	1	256fs	128fs	256fs	96 kHz
2	1	0	512fs	256fs	512fs	48 kHz
3	1	1	128fs	64fs	128fs	192 kHz

Table 14. AK4114 Master Clock Output Frequency

■ Toggle switch

[SW3] (PDN): Switch for power down reset of AK4683 (U1). Keep “H” during operation of AK4683 (U1). Power down reset of AK4683 will be done by setting SW3 (PDN) to “L” once, after power on.

[SW1] (AK4114-PDN): Switch for power down reset of AK4114 (U5). Keep “H” during operation of AK4114 (U5). Power down reset of AK4114 (U5) will be done by setting SW1 to “L” once, after power on.

■ LED indication

[LE1] (INT): LED for output of AK4683 (U1): INT. It turns on when output of AK4683 (U1): INT is “H”.
 [LED1] (ERF): LED for output of AK4114 (U5): INT0. It turns on when output of AK4114 (U5): INT0 is “H”.

■ Set up Jumper pins

Jumper	Evaluation Mode				
	1	2	3	4	5
JP1 (LIN1)	LINA	LINA	LINA	LINA	LINA
JP2 (LIN2)	Open	Open	Open	Open	Open
JP3 (LIN3)	Open	Open	Open	Open	Open
JP4 (LIN4)	Open	Open	Open	Open	Open
JP5 (LIN5)	Open	Open	Open	Open	Open
JP6 (LIN6)	Open	Open	Open	Open	Open
JP7 (RIN1)	RINA	RINA	RINA	RINA	RINA
JP8 (RIN2)	Open	Open	Open	Open	Open
JP9 (RIN3)	Open	Open	Open	Open	Open
JP10 (RIN4)	Open	Open	Open	Open	Open
JP11 (RIN5)	Open	Open	Open	Open	Open
JP12 (RIN6)	Open	Open	Open	Open	Open
JP15 (XTIA)	Open	Open	Open	Short	Open
JP16 (ILRCKA)	Short	Short	Short	Open	Short
JP17 (SDTIA1)	GND	GND	DIR	GND	GND
JP19 (SDTIA2)	GND	GND	GND	GND	GND
JP20 (SDTIA3)	GND	GND	GND	GND	GND
JP21 (MCLK-SEL)	Open	Open	MCKO1	Open	Open
JP22 (BICKA)	Short	Short	Short	Short	Short
JP23 (SDTO)	SDTOA	SDTOA	SDTOA	SDTOA	SDTOA
JP24 (OLRCKA)	Open	Open	Open	Short	Open
JP25 (SDTIB)	GND	GND	GND	GND	GND
JP27 (BICKB)	Open	Open	Open	Open	Open
JP28 (LRCKB)	Open	Open	Open	Open	Open
JP29 (MCLK)	Open	Open	Open	Open	Open
JP30 (TX)	OPT	OPT	OPT	OPT	OPT
JP32 (RX1)	GND	GND	GND	GND	GND
JP33 (RX0)	OPT	OPT	OPT	OPT	OPT
JP34 (RX2)	GND	GND	GND	GND	GND
JP35 (GND)	Short	Short	Short	Short	Short
JP36 (RX3)	GND	GND	GND	GND	GND

(Default)

■ Set up control software registers

After the reset, setting example files are available as follows in CD-ROM to set registers in each evaluation modes.

Evaluation Mode 1

ADC/DAC: ak4683_adc_dac_mode1.akr
DIR/DIT: ak4683_dir_dit_mode1.akr

Evaluation Mode 2

ADC/DAC: ak4683_adc_dac_mode2.akr
DIR/DIT: ak4683_dir_dit_mode2.akr

Evaluation Mode 3

ADC/DAC: ak4683_adc_dac_mode3.akr
DIR/DIT: ak4683_dir_dit_mode3.akr

Evaluation Mode 4

ADC/DAC: ak4683_adc_dac_mode4.akr
DIR/DIT: ak4683_dir_dit_mode4.akr

Evaluation Mode 5

ADC/DAC: ak4683_adc_dac_mode5.akr
DIR/DIT: ak4683_dir_dit_mode5.akr

■ Analog Input Circuit

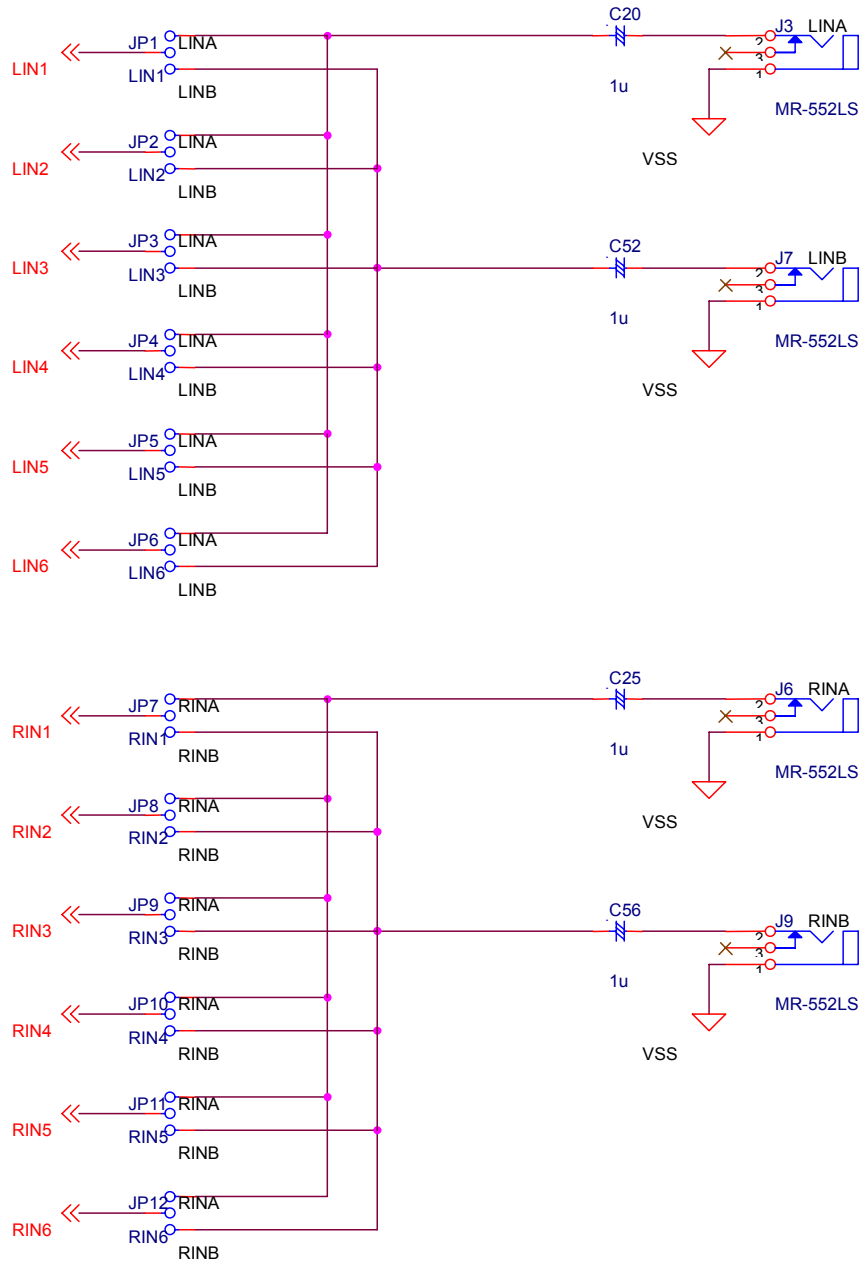


Figure 3. Analog Input Circuit

For analog input, RCA connector: J3 (LINA), J6 (RINA), J7 (LINB), J9 (RINB) are available to use.
 Analog inputs are single-ended and input ranges of each channel are nominally 6.1Vpp@5V (R1~R12=47kΩ, R=14,15=24kΩ).

■ Analog Output Circuit

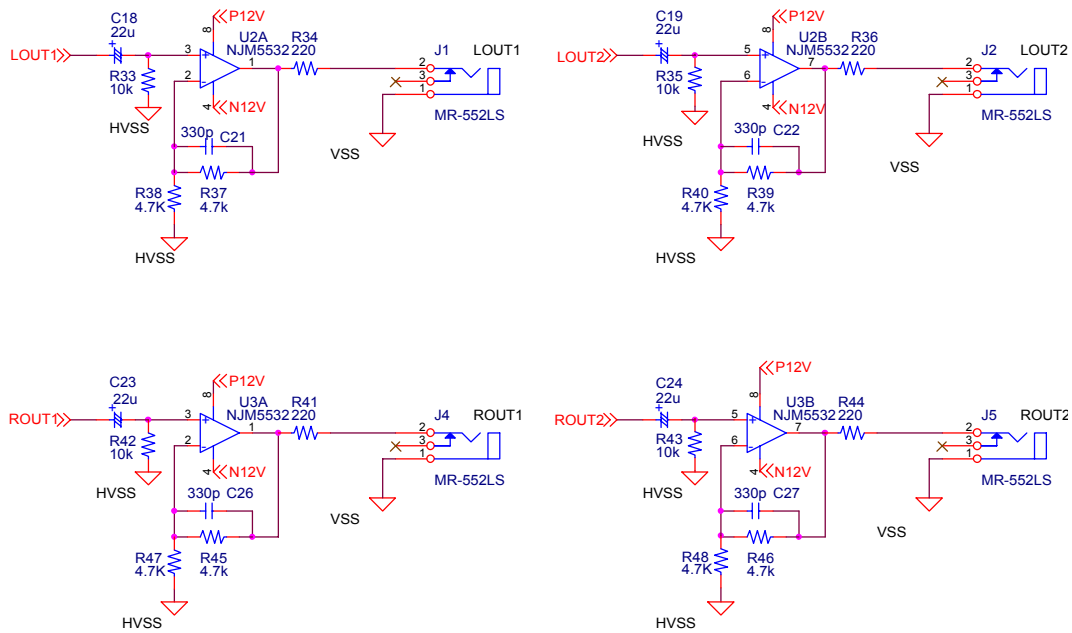


Figure 4. Analog Output Circuit

For analog output, RCA connector: J1 (LOUT1), J4 (ROUT1), J2 (LOUT2), J5 (ROUT2) are available to use. Analog outputs are single-ended and output ranges of each channel are nominally 3.0Vpp@5V. Output range: AOUT is proportional to AVDD2 (AOUT=0.6 x AVDD2=0.6 x 5=3.0).

■ Digital Input Circuit (Internal DIR)

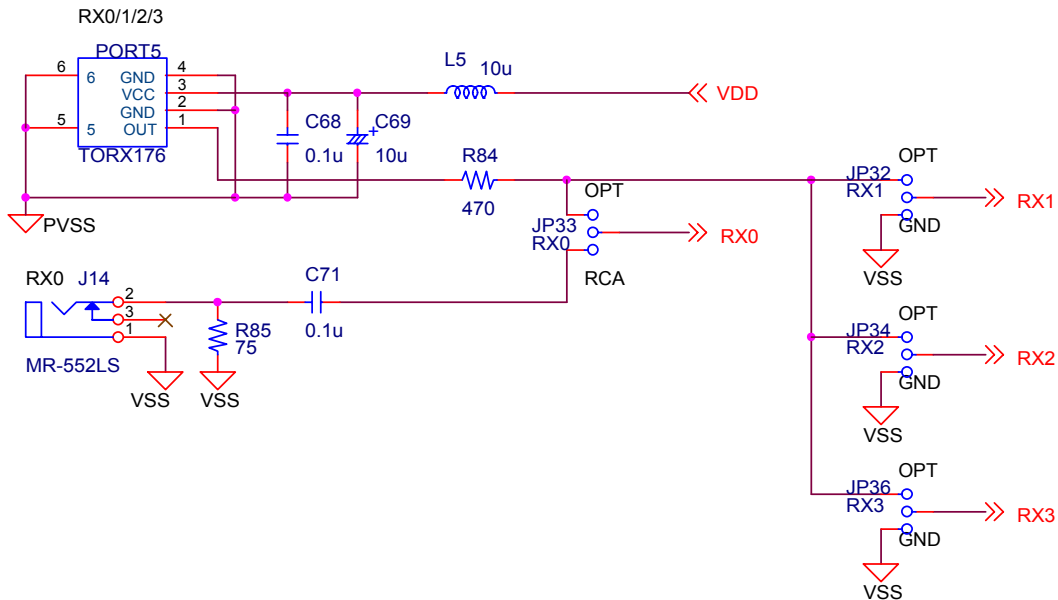


Figure 5. Digital Input Circuit (Internal DIR)

In case of input through RX0, optical connector PORT5 (TORX176) or RCA connector J14 (RX0) are available.
 In case of input through RX1, RX2 or RX3, only the optical connector PORT5 is available.
 Digital input: RX0, RX1, RX2 and RX3 is available to select overwriting IPS10 bit of control register (Addr=03H) of AK4683: DIR/DIT part by control software.

■ Digital Input Circuit (External DIR: PORT A)

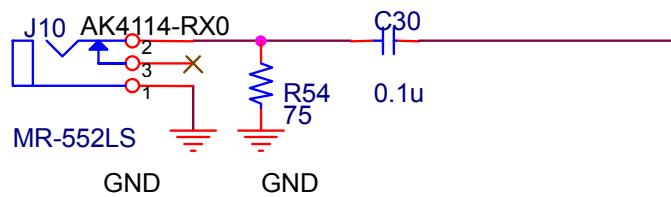


Figure 6. Digital Input Circuit (External DIR)

For digital input, RCA connector: J10 (AK4114-RX0) is available.

■ Digital Output Circuit (Internal DIT)

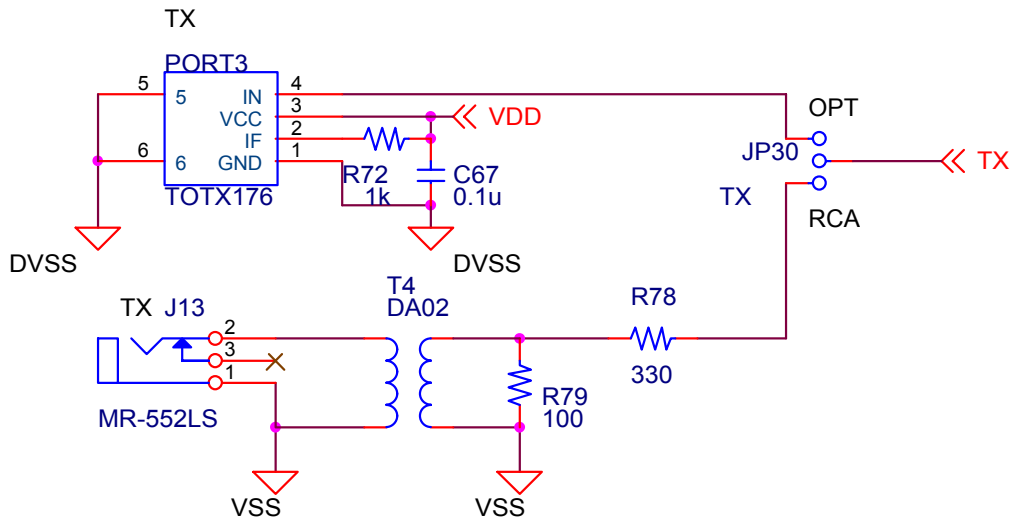


Figure 7. Digital Output Circuit (Internal DIT)

For digital output, optical connector PORT3 (TOTX176) or RCA connector J13 (TX1) are available.

■ Digital Output Circuit (External DIT)

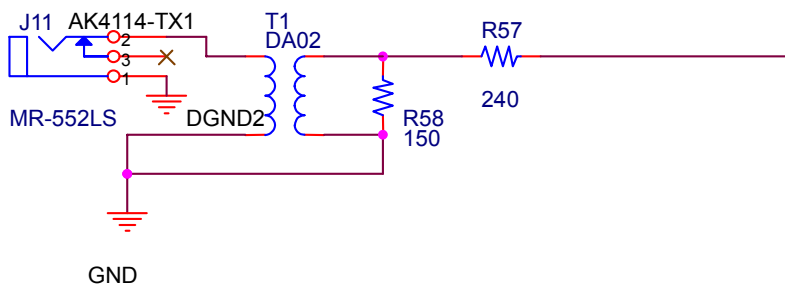


Figure 8. Digital Output Circuit (External DIT)

For digital output, RCA connector: J11 (AK4114-TX1) is available.

■ Headphone Output Circuit

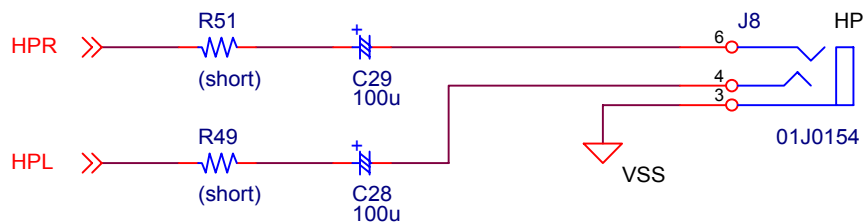


Figure 9. Headphone Output Circuit

For headphone output, stereo mini jack J8 (HP) are available.

Control Software Manual

■ Set-up of evaluation board and control software

1. Set up the AKD4683-B according to previous term.
2. Connect IBM-AT compatible PC with AKD4683-B by 10-line type flat cable (packed with AKD4683-B). Take care of the direction of 10pin header. (Please install the driver in the CD-ROM when this control software is used on Windows 2000/XP. Please refer "Installation Manual of Control Software Driver by AKM device control software". In case of Windows95/98/ME, this installation is not needed. This control software does not operate on Windows NT.)
3. Insert the CD-ROM labeled "AKD4683-B Evaluation Kit" into the CD-ROM drive.
4. Access the CD-ROM drive, and double-click the icon of "akd4683-b_adc_dac.exe" and "akd4683-b_dir_dit.exe", and set up the control program.
 - akd4683-b_adc_dac.exe: AK4683 ADC/DAC control program
 - akd4683-b_dir_dit.exe: AK4683 DIR/DIT control program
5. Then evaluate according to the follows.

■ Operation flow

Keep the following flow.

1. Set up the control program according to explanation above.
2. Click "Port Reset" button.

■ Explanation of each buttons

1. [Port Reset]: Set up the USB interface board (AKDUSBIF-A).
2. [Write default]: Initialize the registers.
3. [All Write]: Write all registers data that is currently displayed.
4. [Function1]: Dialog to write data by keyboard operation.
5. [Function2]: Dialog to write data by keyboard operation.
6. [Function3]: The sequence of register setting can be set and executed.
7. [Function4]: The sequence that is created on [Function3] can be assigned to buttons and executed.
8. [Function5]: The register setting that is created by [SAVE] function on main window can be assigned to buttons and executed.
9. [SAVE]: Save the current register setting.
10. [OPEN]: Write the saved values to all register.
11. [Write]: Dialog to write data by mouse operation.

■ Indication of data

Input data is indicated on the register map. Red letter indicates "H" or "1" and blue one indicates "L" or "0". Blank is the part that is not defined in the datasheet.

■ Explanation of each dialog

1. [Write Dialog]: Dialog to write data by mouse operation

There are dialogs corresponding to each register.

Click the [Write] button corresponding to each register to set up the dialog. If you check the check box, data becomes "H" or "L". If not, "0" or "1".

When writing the input data to register, click [OK] button. If not, click [Cancel] button.

2. [Function1 Dialog]: Dialog to write data by keyboard operation

Address Box: Input registers address in 2 figures of hexadecimal.

Data Box: Input registers data in 2 figures of hexadecimal.

When writing the input data to register, click [OK] button. If not, click [Cancel] button.

3. [Function2 Dialog]: Dialog to evaluate ATT

This is a dialog corresponding to address: 0CH, 0DH, 0EH, 0FH, 10H, and 11H of AK4683.

Address Box: Input registers address in 2 figures of hexadecimal.

Start Data Box: Input starts data in 2 figures of hexadecimal.

End Data Box: Input end data in 2 figures of hexadecimal.

Interval Box: Data is written to register by this interval.

Step Box: Data changes by this step.

Mode Select Box:

With checking this check box, data reaches end data, and returns to start data.

[Example] Start Data = 00, End Data = 09

Data flow: 00 01 02 03 04 05 06 07 08 09 09 08 07 06 05 04 03 02 01 00

Without checking this check box, data reaches end data, but does not return to start data.

[Example] Start Data = 00, End Data = 09

Data flow: 00 01 02 03 04 05 06 07 08 09

When writing the input data to register, click [OK] button. If not, click [Cancel] button.

4. [Save] and [Open]

4-1. [Save]

Save the current register setting data to the file. The extension of file name is “.akr”.

(Operation flow)

- (1) Click [Save] Button.
- (2) Set the file name and push [Save] Button. The extension of file name is “.akr”.

4-2. [Open]

The register setting data saved to the file by [Save] is written to register. The file type is the same as [Save].

(Operation flow)

- (1) Click [Open] Button.
- (2) Select the file (*.akr) and Click [Open] Button.

5. [Function3 Dialog]

The sequence of register setting can be set and executed.

(1) Click [F3] Button.

Set the control sequence.

Set the address, Data and Interval time. Set “-1” to the address of the step where the sequence should be paused.

(3) Click [Start] button. Then this sequence is executed.

The sequence is paused at the step of Interval="-1". Click [START] button, the sequence restarts from the paused step. This sequence can be saved and opened by [Save] and [Open] button on the [Function3] window. The extension of file name is “aks”.

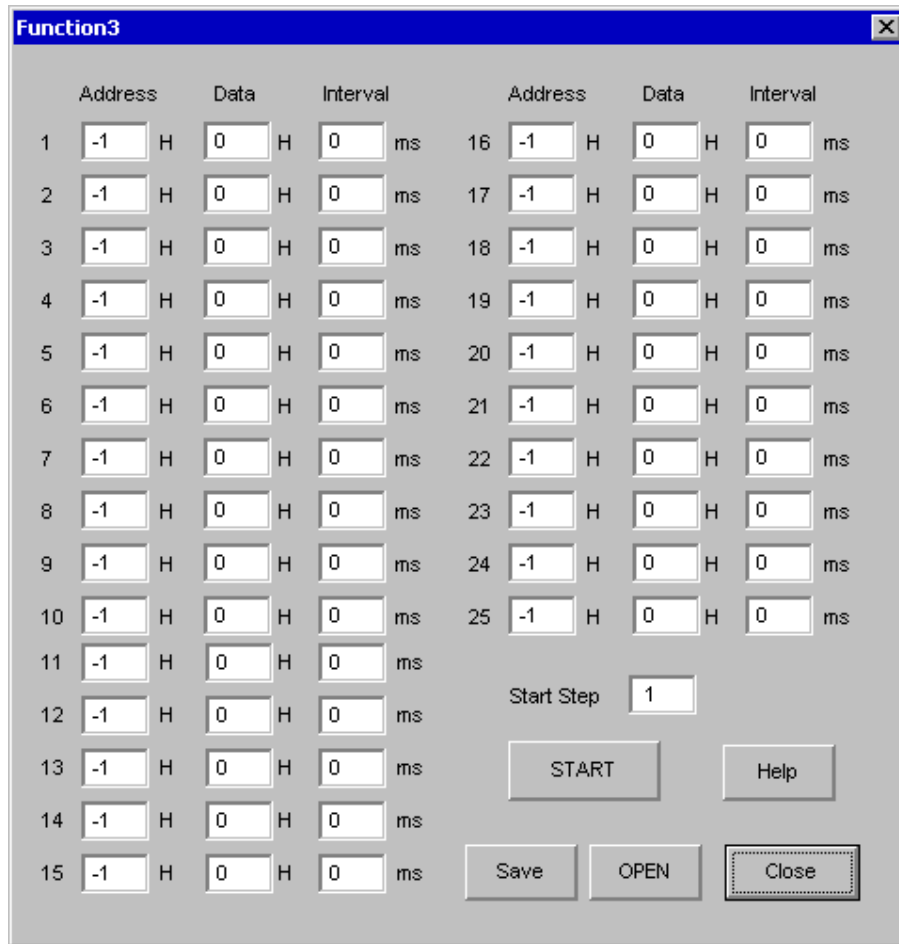


Figure 1. Window of [F3]

6. [Function4 Dialog]

The sequence that is created on [Function3] can be assigned to buttons and executed. When [F4] button is clicked, the window as shown in Figure 2 opens.

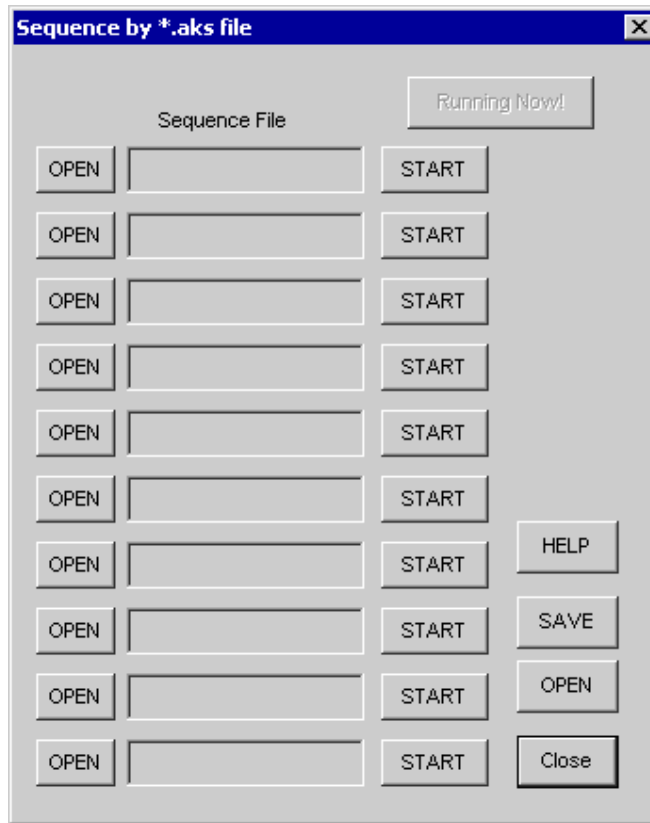


Figure 2. [F4] window

6-1. [OPEN] buttons on left side and [START] buttons

(1) Click [OPEN] button and select the sequence file (*.aks).

The sequence file name is displayed as shown in Figure 3.

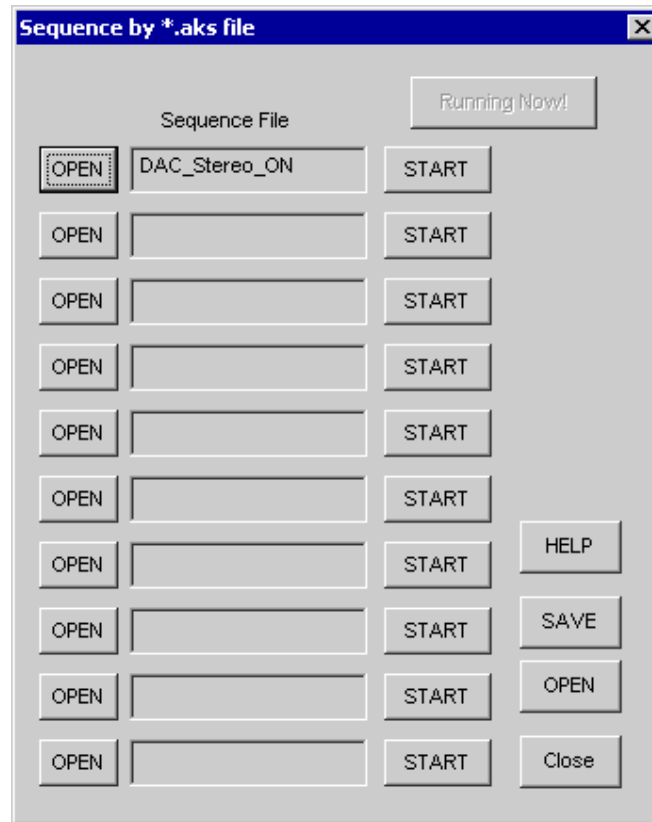


Figure 3. [F4] window(2)

(2) Click [START] button, then the sequence is executed.

6-2. [SAVE] and [OPEN] buttons on right side

[SAVE]: The sequence file names can assign be saved. The file name is *.ak4.

[OPEN]: The sequence file names assign that are saved in *.ak4 are loaded.

6-3. Note

(1) [Function4] doesn't support the pause function of sequence function.

(2) All files need to be in same folder used by [SAVE] and [OPEN] function on right side.

(3) When the sequence is changed in [Function3], the file should be loaded again in order to reflect the change.

7. [Function5 Dialog]

The register setting that is created by [SAVE] function on main window can be assigned to buttons and executed. When [F5] button is clicked, the following window as shown in Figure 4 opens.

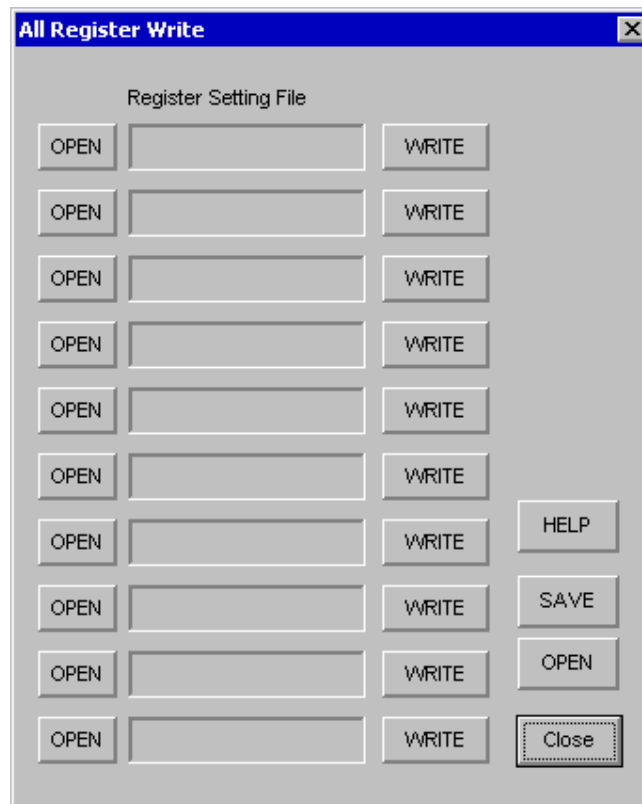


Figure 4. [F5] window

7-1. [OPEN] buttons on left side and [WRITE] button

- (1) Click [OPEN] button and select the register setting file (*.akr).
- (2) Click [WRITE] button, then the register setting is executed.

7-2. [SAVE] and [OPEN] buttons on right side

[SAVE]: The register setting file names assign can be saved. The file name is *.ak5.

[OPEN]: The register setting file names assign that are saved in *.ak5 are loaded.

7-3. Note

- (1) All files need to be in same folder used by [SAVE] and [OPEN] function on right side.
- (2) When the register setting is changed by [Save] Button in main window, the file should be loaded again in order to reflect the change.

Measure Result

1) ADC part

[Measurement condition]

- Measurement unit: Audio Precision
- MCLK : 256fs (fs=48kHz, 96kHz)
- BICK : 64fs
- fs : 48kHz, 96kHz
- BW : 20Hz~20kHz (fs=48kHz), 20Hz~40kHz (fs=96kHz)
- Bit : 24bit
- Power Supply : AVDD1=AVDD2=DVDD=PVDD= TVDD=HVDD =5V,
- Interface : Internal DIT (fs=48kHz, 96kHz)
- Temperature : Room Temp

fs=48kHz

Parameter	Input signal	Measurement filter	Results
S/(N+D)	1kHz, -0.5dB	20kLPF	91.5 dB
DR	1kHz, -60dB	20kLPF	98.9 dB
DR	1kHz, -60dB	20kLPF, A-weighted	101.6 dB
S/N	No signal	20kLPF	99.0 dB
S/N	No signal	20kLPF, A-weighted	101.9 dB

fs=96kHz

Parameter	Input signal	Measurement filter	Results
S/(N+D)	1kHz, -0.5dB	fs/2	92.9 dB
DR	1kHz, -60dB	fs/2	98.0 dB
DR	1kHz, -60dB	20kLPF, A-weighted	103.1 dB
S/N	No signal	fs/2	98.0 dB
S/N	No signal	20kLPF, A-weighted	103.1 dB

2) DAC part

[Measurement condition]

- Measurement unit: Audio Precision
- MCLK : 256fs (fs=48kHz, 96kHz), 128fs (fs=192kHz)
- BICK : 64fs
- fs : 48kHz, 96kHz, 192kHz
- BW : 20Hz~20kHz (fs=48kHz), 20Hz~40kHz (fs=96kHz), 20Hz~40kHz (fs=192kHz)
- Resolution : 24bit
- Power Supply : AVDD1=AVDD2=DVDD=PVDD= TVDD=HVDD=5V
- Interface : Internal DIR (48kHz, 96kHz, 192kHz)
- Temperature : Room Temp

fs=48kHz

Parameter	Input signal	Measurement filter	Results
S/(N+D)	1kHz, 0dB	20kLPF	98.0 dB
DR	1kHz, -60dB	20kLPF	103.7 dB
DR	1kHz, -60dB	22kLPF, A-weighted	105.8 dB
S/N	“0” data	20kLPF	103.4 dB
S/N	“0” data	22kLPF, A-weighted	106.0 dB

fs=96kHz

Parameter	Input signal	Measurement filter	Results
S/(N+D)	1kHz, 0dB	40kLPF	96.5 dB
DR	1kHz, -60dB	40kLPF	102.0 dB
DR	1kHz, -60dB	22kLPF, A-weighted	105.8 dB
S/N	“0” data	40kLPF	101.0 dB
S/N	“0” data	22kLPF, A-weighted	106.0 dB

fs=192kHz

Parameter	Input signal	Measurement filter	Results
S/(N+D)	1kHz, 0dB	40kLPF	96.8 dB
DR	1kHz, -60dB	40kLPF	102.5 dB
DR	1kHz, -60dB	22kLPF, A-weighted	105.8 dB
S/N	“0” data	40kLPF	101.2 dB
S/N	“0” data	22kLPF, A-weighted	105.8 dB

1.ADC

(ADC fs=48kHz)

AK4683 FFT fs=48kHz, -0.5dB input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

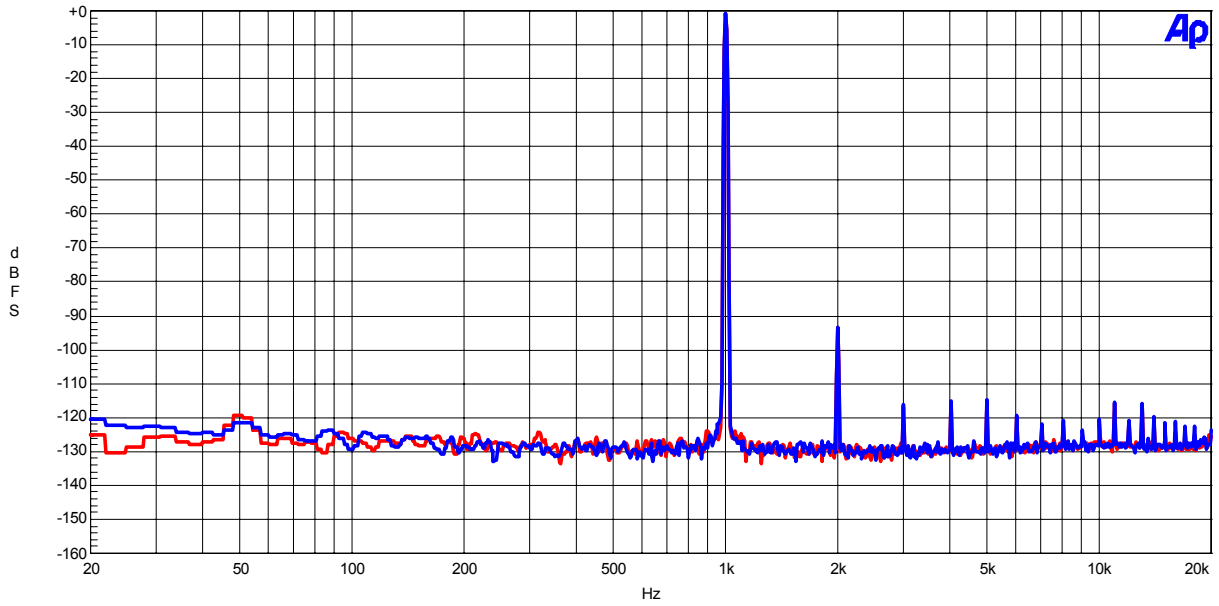


Figure 10. FFT(Input Frequency =1kHz,Input Level=-0.5dBFS)

AK4683 FFT fs=48kHz, -60dB input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

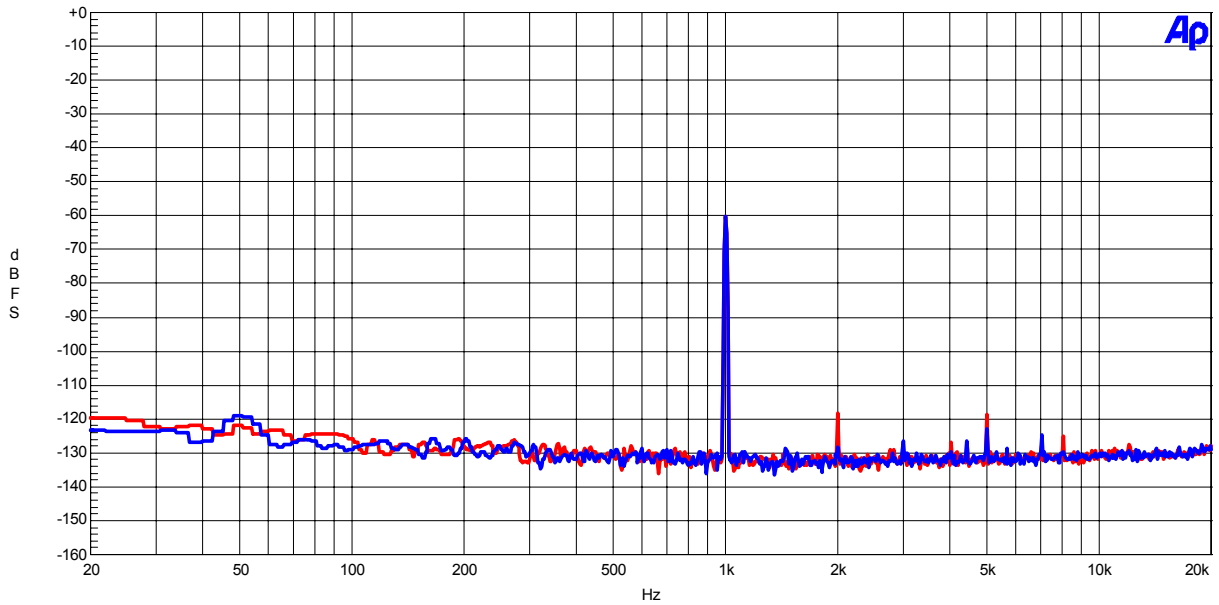


Figure 11. FFT(Input Frequency =1kHz,Input Level=-60dBFS)

(ADC fs=48kHz)

AK4683 FFT fs=48kHz, No signal input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

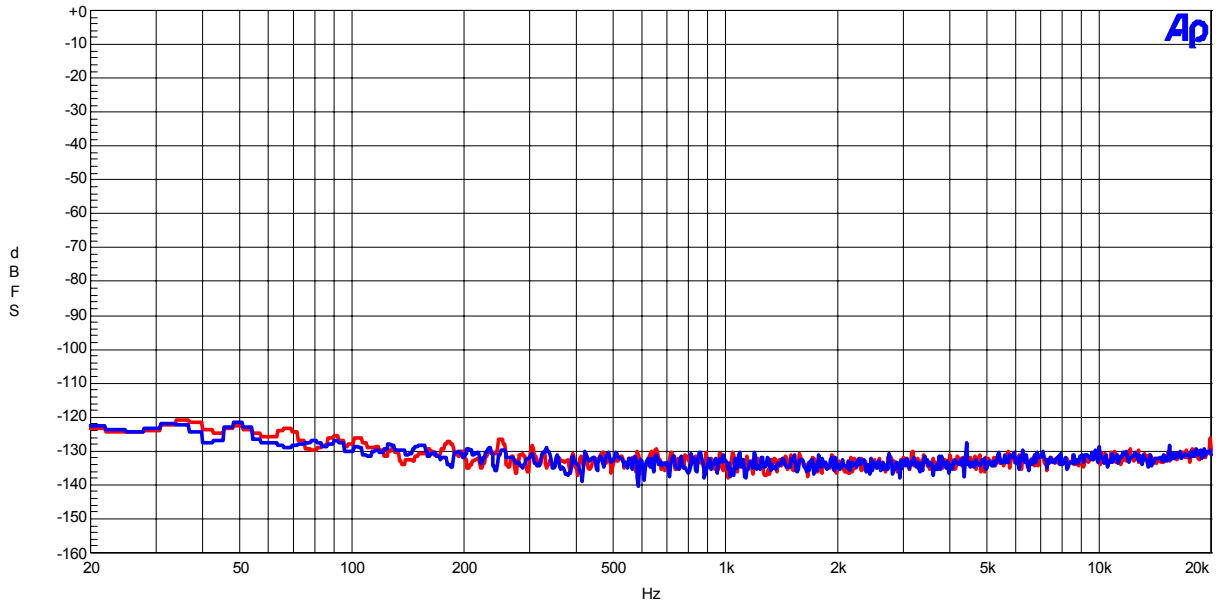


Figure 12. FFT(noise floor)

AK4683 THD+N vs Input Level fs=48kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

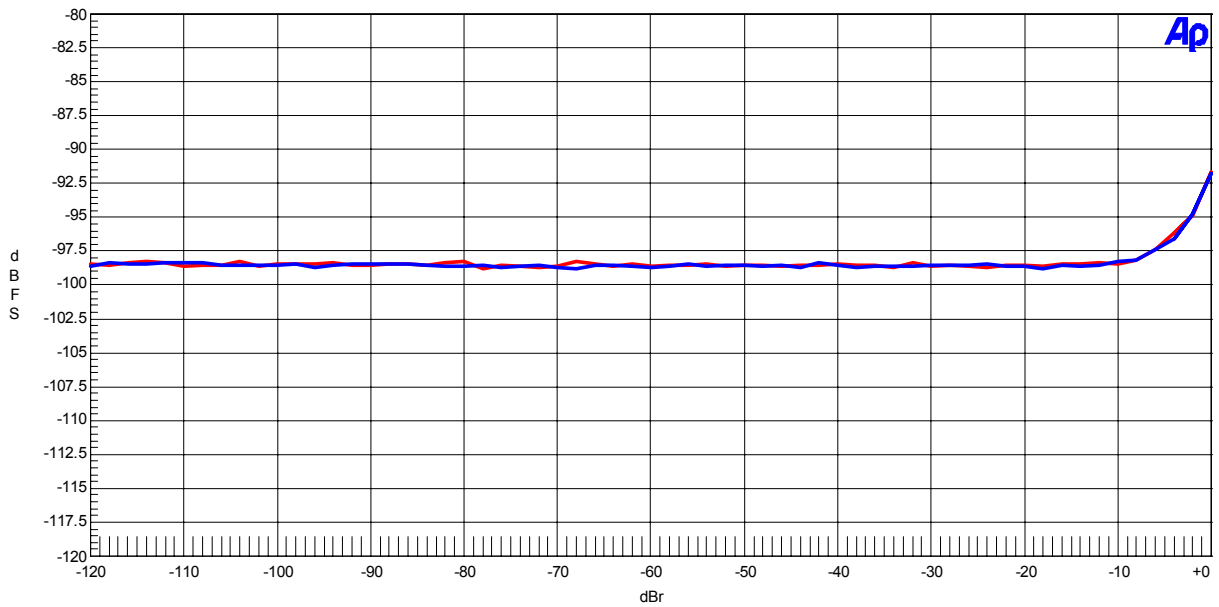


Figure 13. THD + N vs Input Level (Input Frequency =1kHz)

(ADC fs=48kHz)

AK4683 THD+N vs Input Frequency fs=48kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

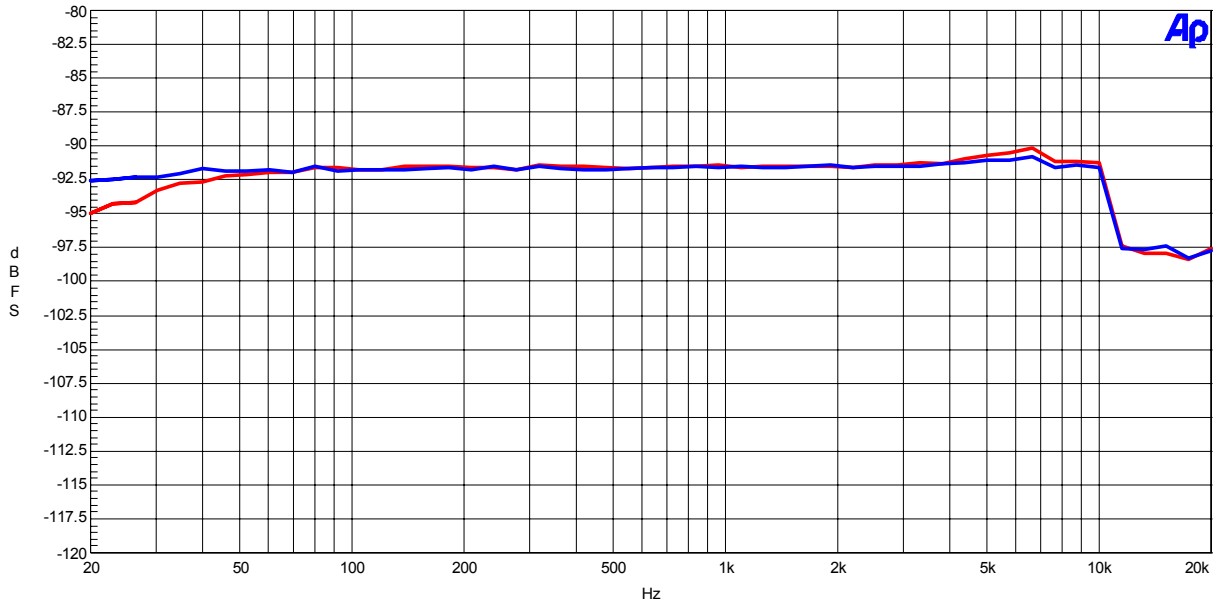


Figure 14. THD + N vs Input Frequency (Input Level=-0.5dBFS)

AK4683 Linearity fs=48kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

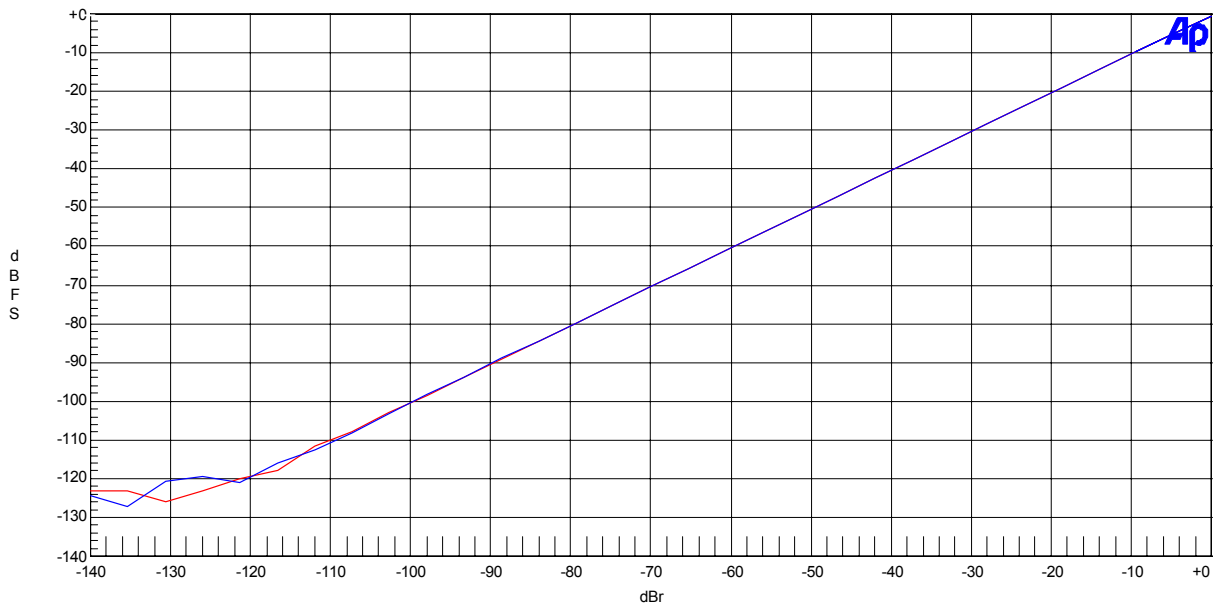


Figure 15. Linearity (Input Frequency =1kHz)

(ADC fs=48kHz)

AK4683 Frequency Respons fs=48kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

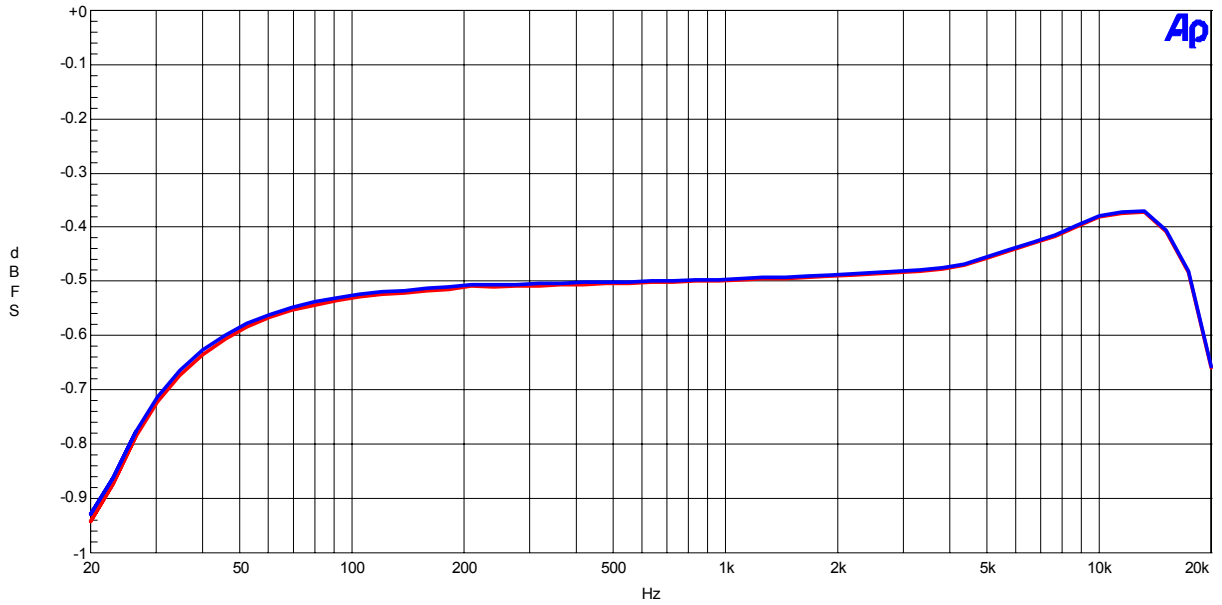


Figure 16. Frequency Response (Input Level=-0.5dBFS)

AK4683 Crosstalk fs=48kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

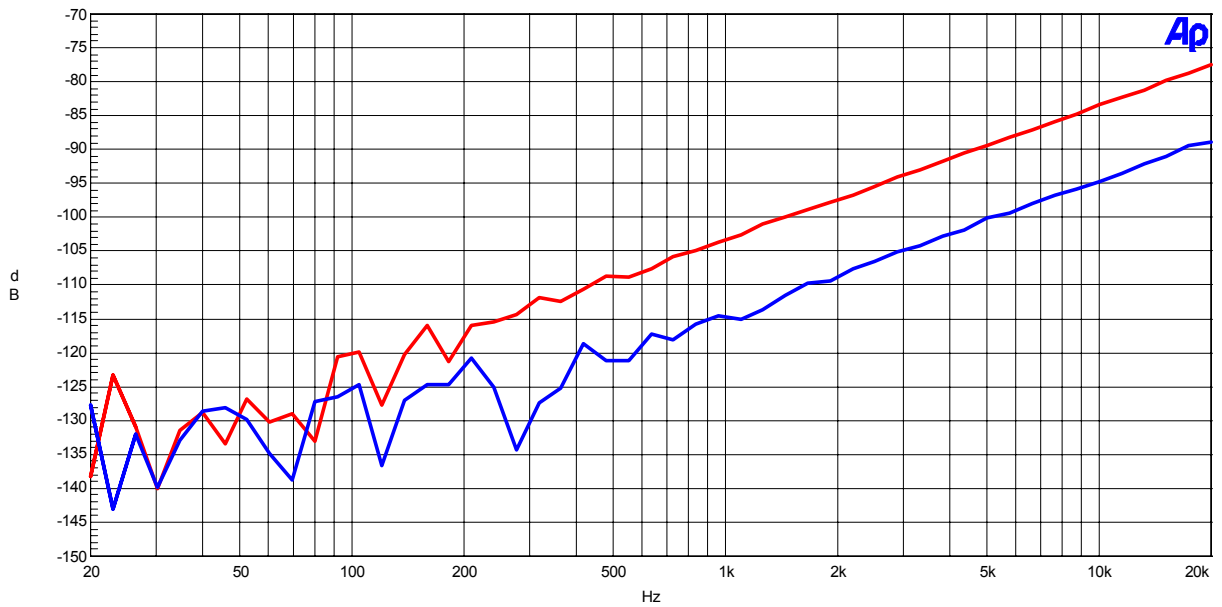


Figure 17. Crosstalk (Input Level=-0.5dBFS)

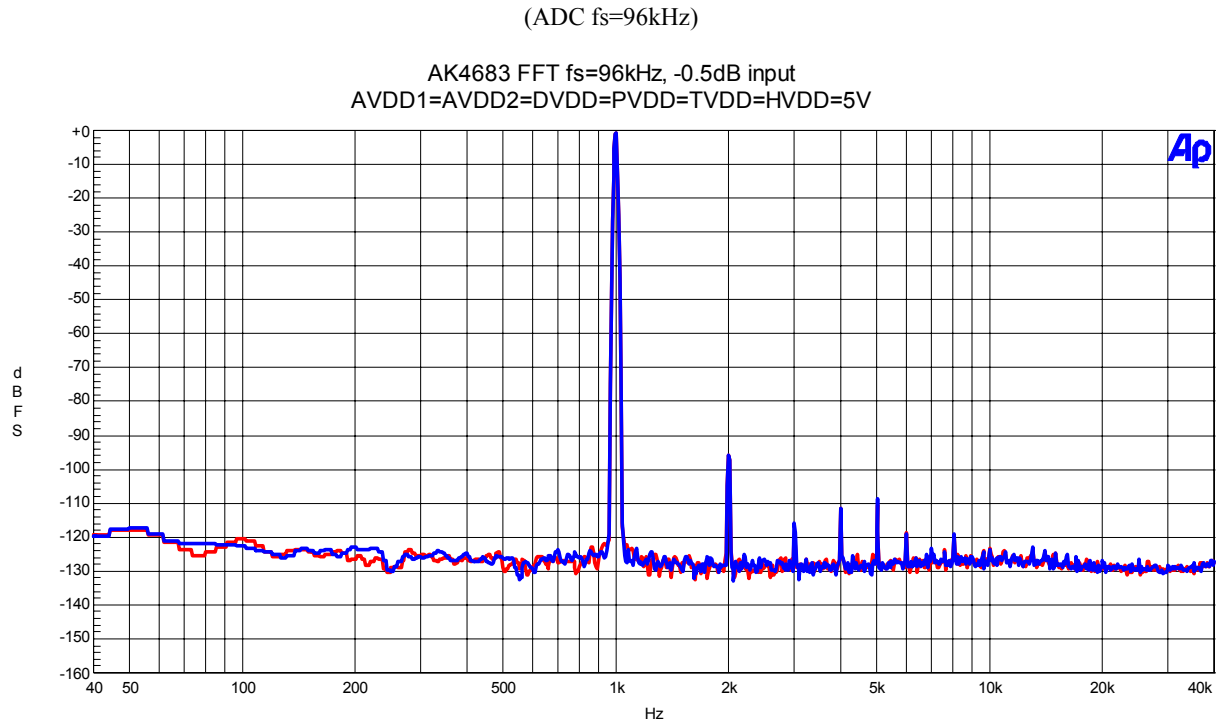


Figure 18. FFT(Input Frequency =1kHz,Input Level=-0.5dBFS)

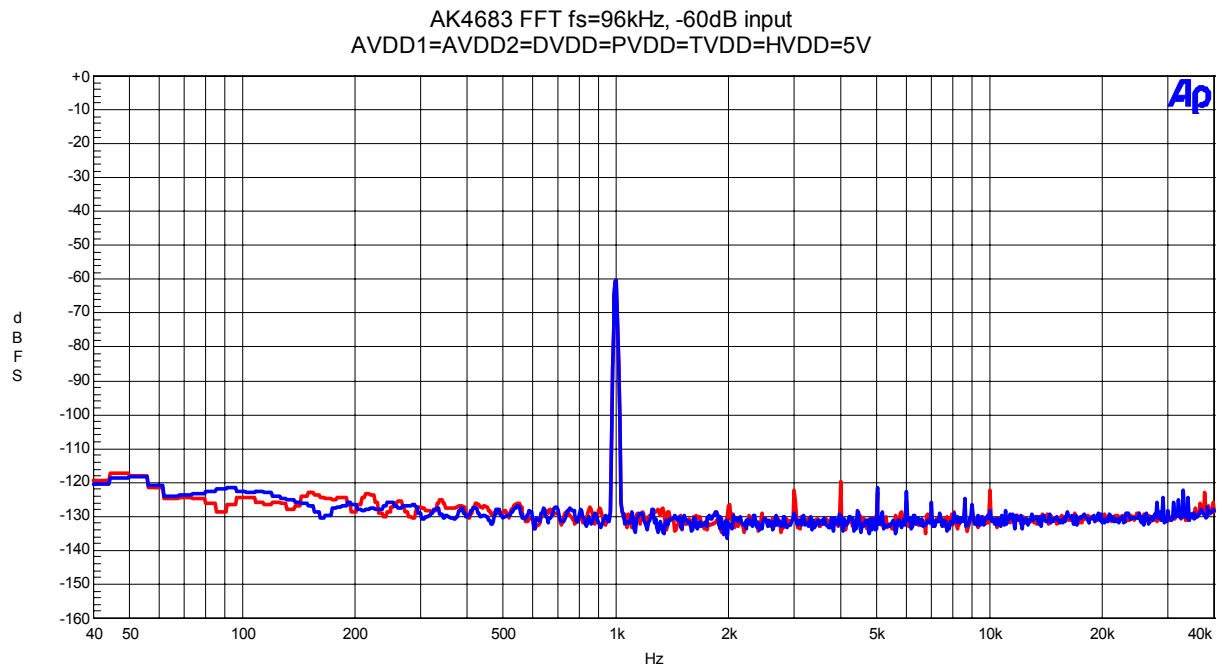


Figure 19. FFT(Input Frequency =1kHz,Input Level=-60dBFS)

(ADC fs=96kHz)

AK4683 FFT fs=96kHz, No input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

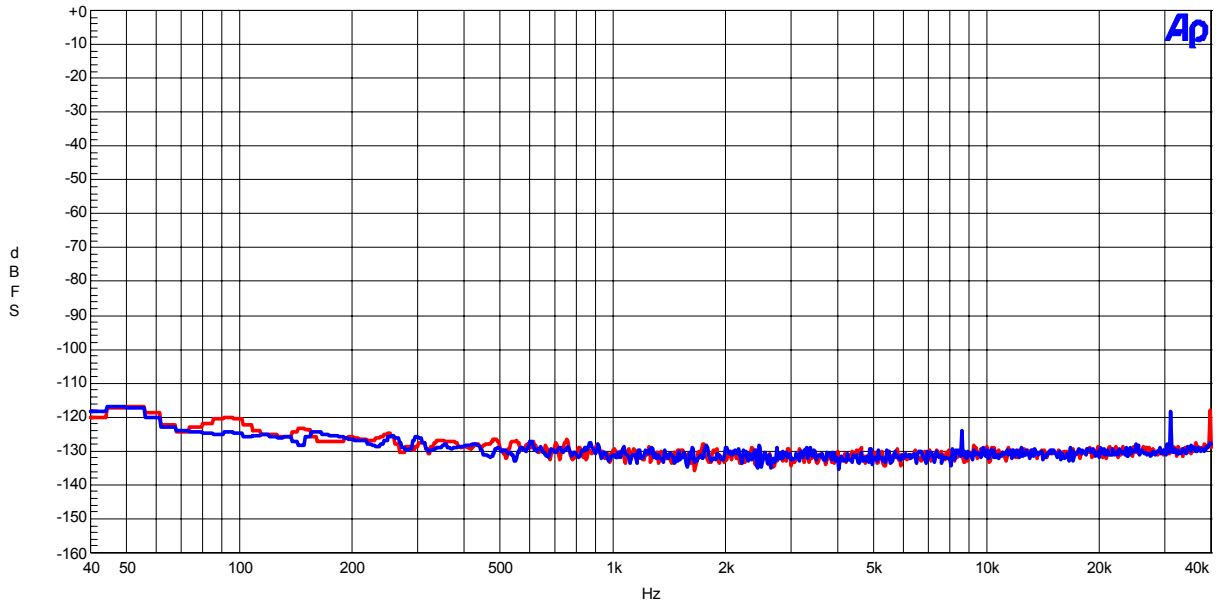


Figure 20. FFT(Noise floor)

AK4683 THD+N vs Input Level fs=96kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

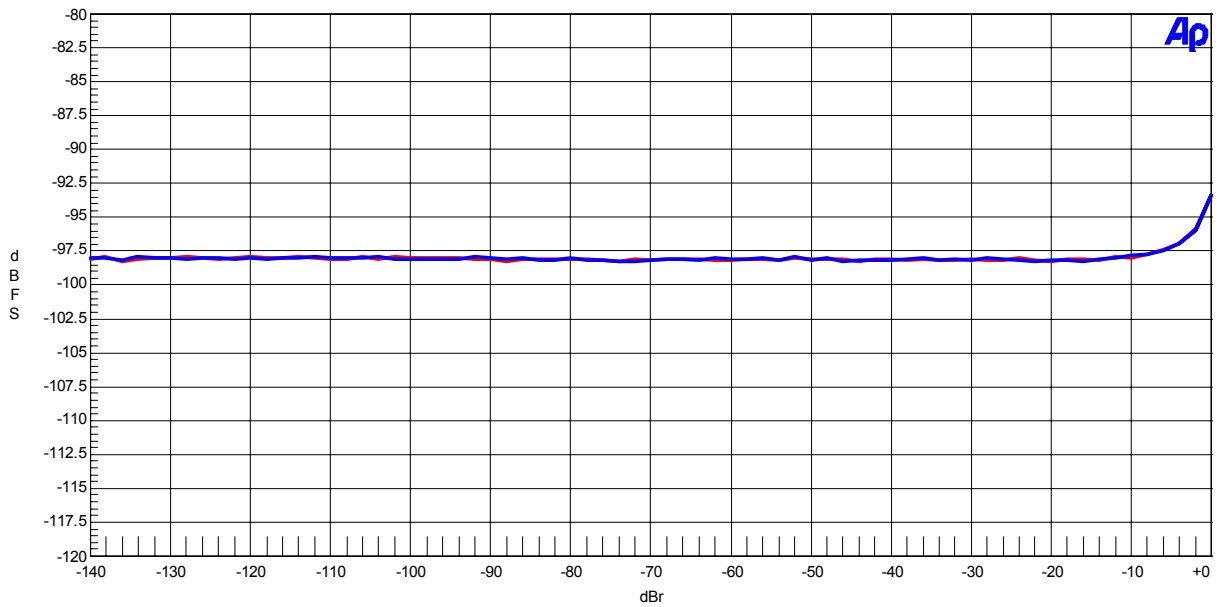


Figure 21. THD + N vs Input Level (Input Frequency =1kHz)

(ADC fs=96kHz)

AK4683 THD+N vs Input Frequency fs=96kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

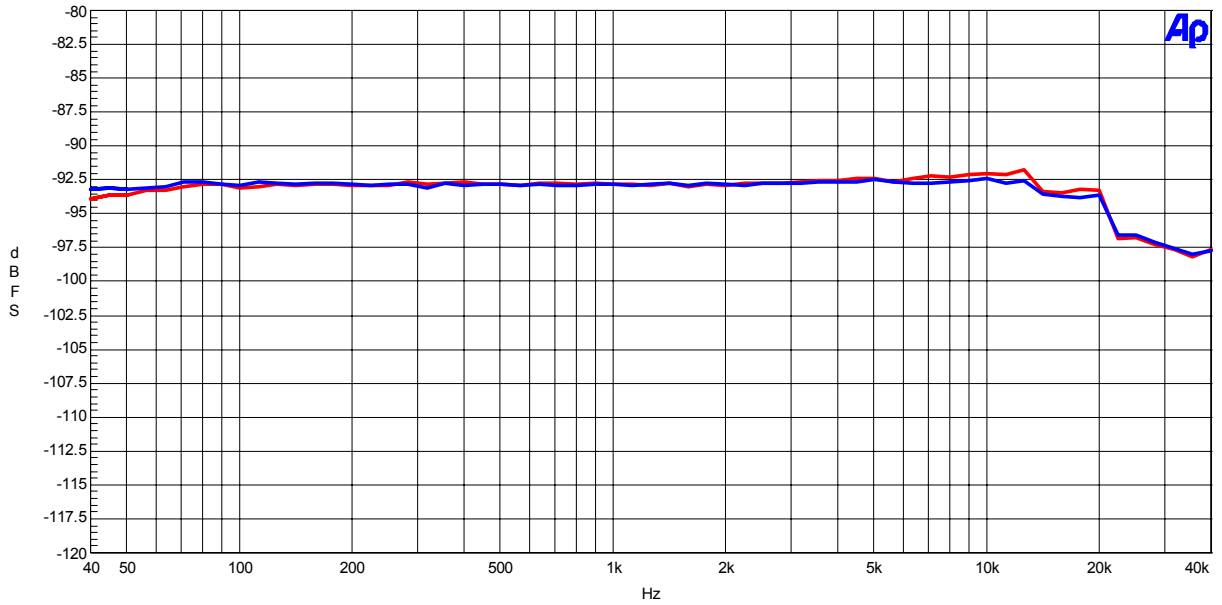


Figure 22. THD + N vs Input Frequency (Input Level=-0.5dBFS)

AK4683 Linearity fs=96kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

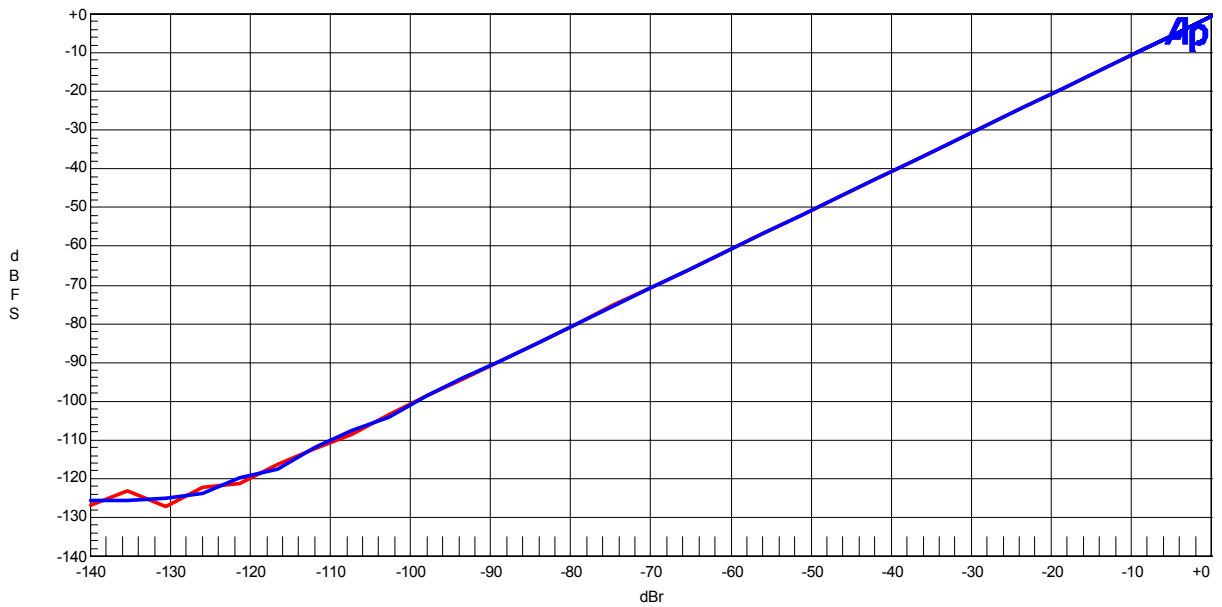


Figure 23. Linearity (Input Frequency =1kHz)

(ADC fs=96kHz)

AK4683 Frequency Respons fs=96kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

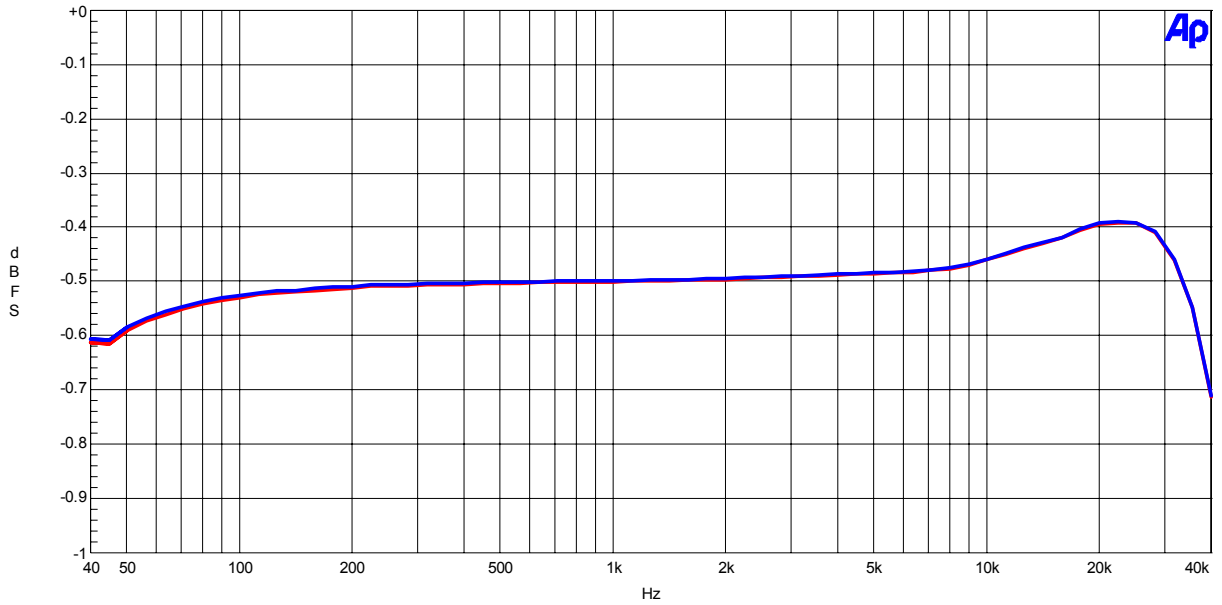


Figure 24. Frequency Response (Input Level=-0.5dBFS)

AK4683 Crosstalk fs=96kHz
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

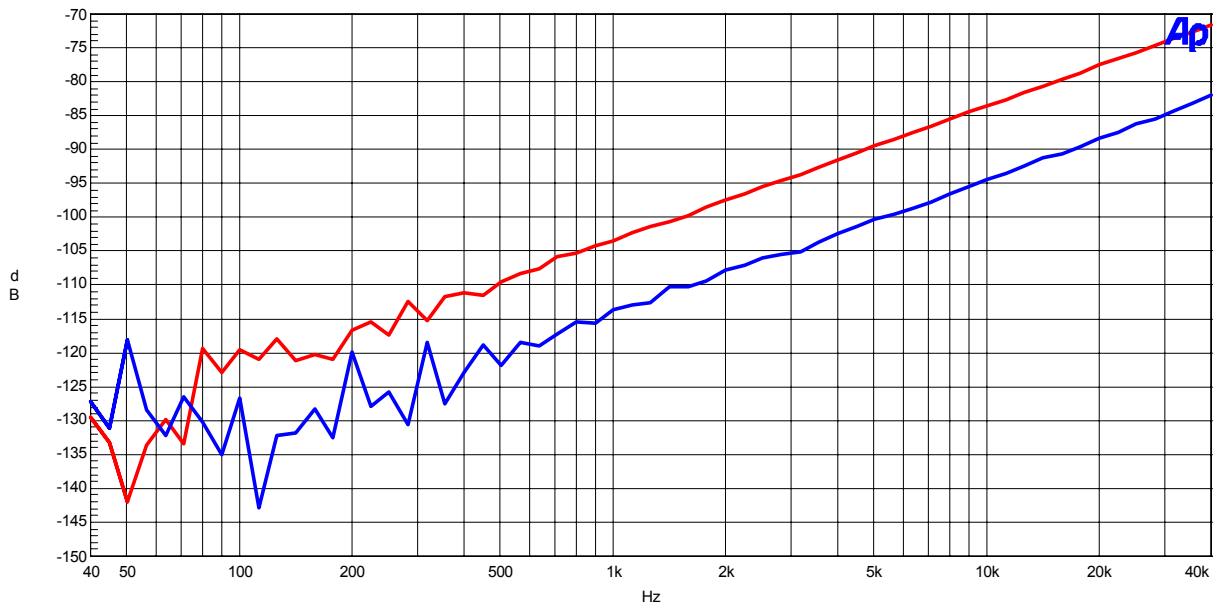


Figure 25. Crosstalk (Input Level=-0.5dBFS)

2.DAC部

(DAC fs=48kHz)

AK4683 FFT fs=48kHz, 0dBFS input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

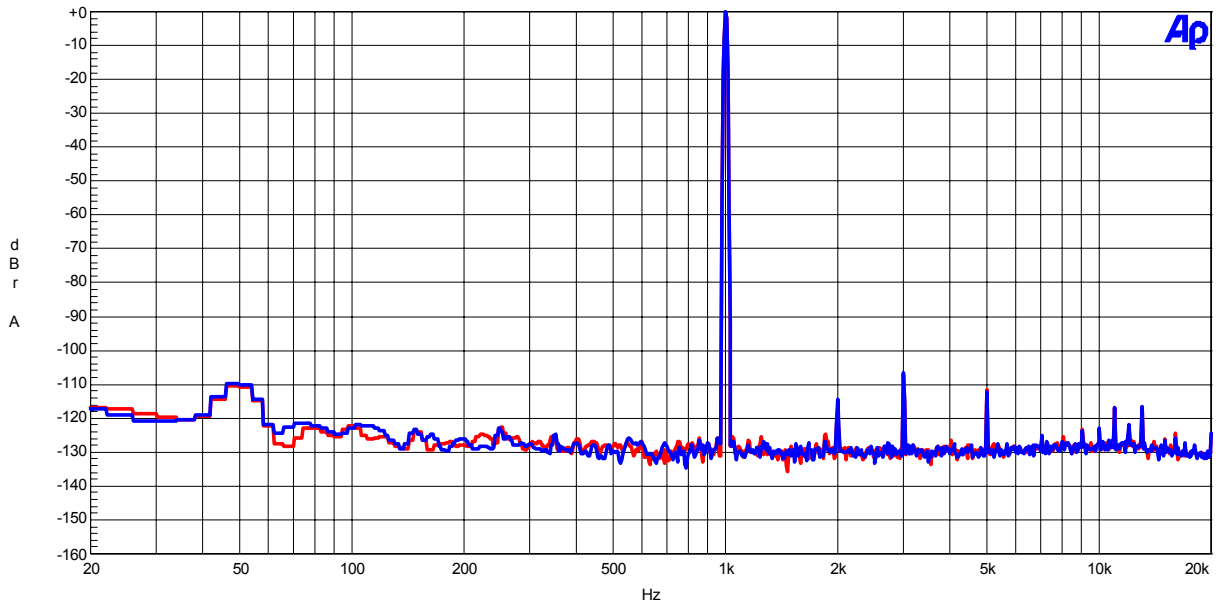


Figure 26. FFT(Input Frequency =1kHz, Input Level=0dBFS)

AK4683 FFT fs=48kHz, -60dB input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

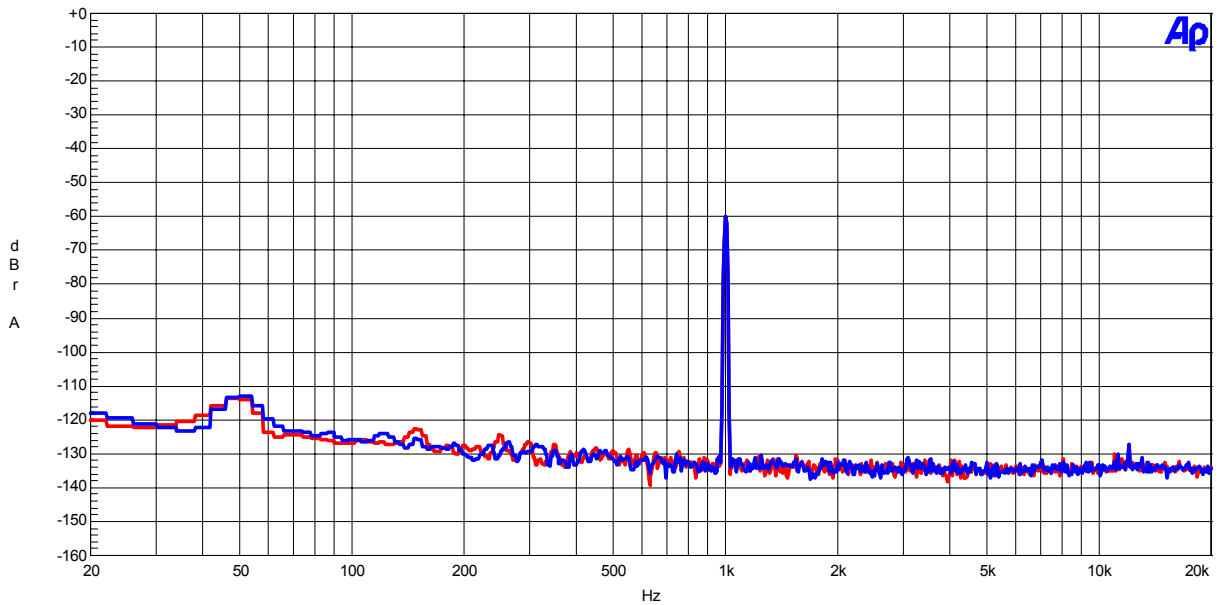


Figure 27. FFT(Input Frequency =1kHz, Input Level=-60dBFS)

(DAC fs=48kHz)

AK4683 FFT fs=48kHz, No signal input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

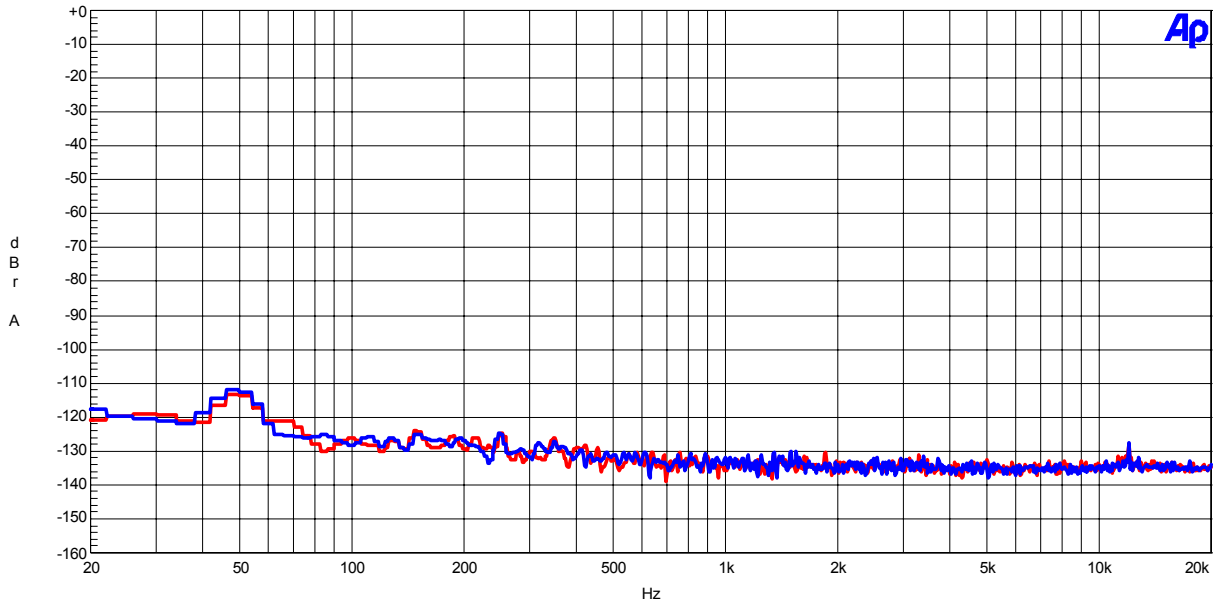


Figure 28. FFT(noise floor)

AK4683 FFT (Out of Band Noise) fs=48kHz, -60dB input
AVDD1=AVDD2=DVDD=PVDD=TVDD=HVDD=5V

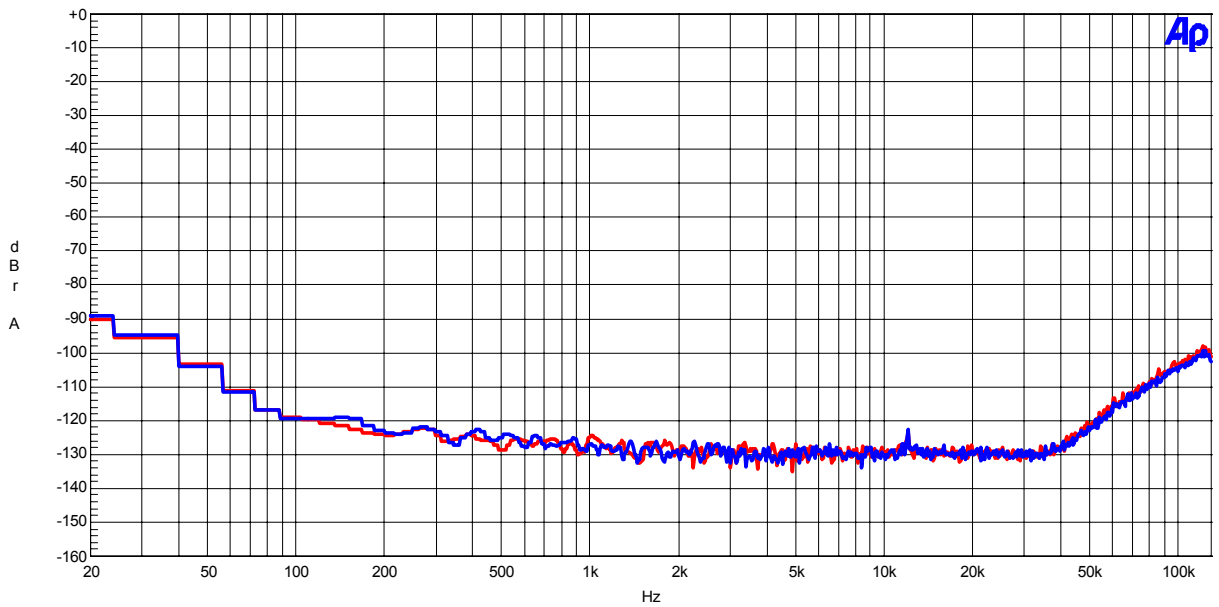


Figure 29. FFT(out-of-band noise)

(DAC fs=48kHz)

AK4683 THD+N vs Input Level fs=48kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

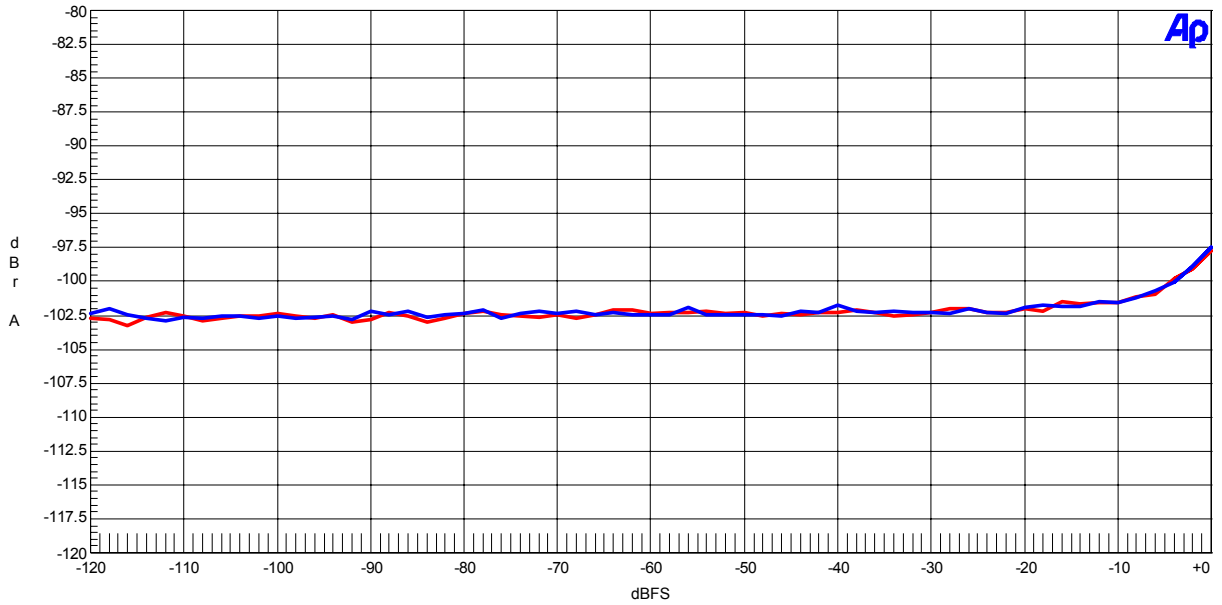


Figure 30. THD+N vs Input Level (Input Frequency =1kHz)

AK4683 THD+N vs Input Frequency fs=48kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

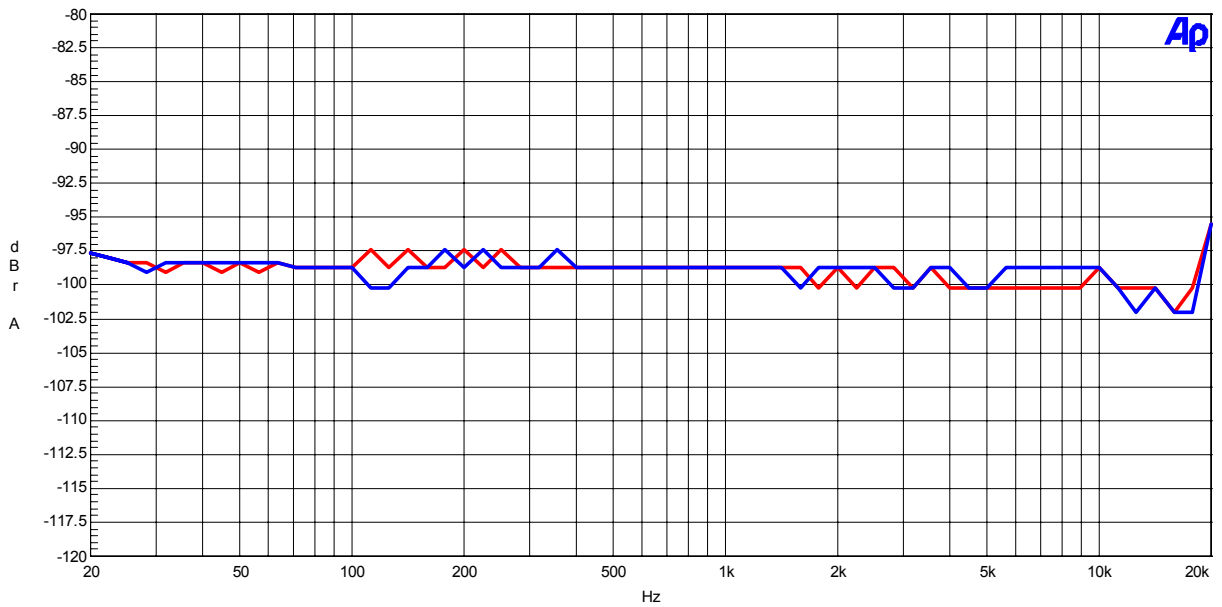


Figure 31. THD+N vs Input Frequency (Input Level=0dBFS)

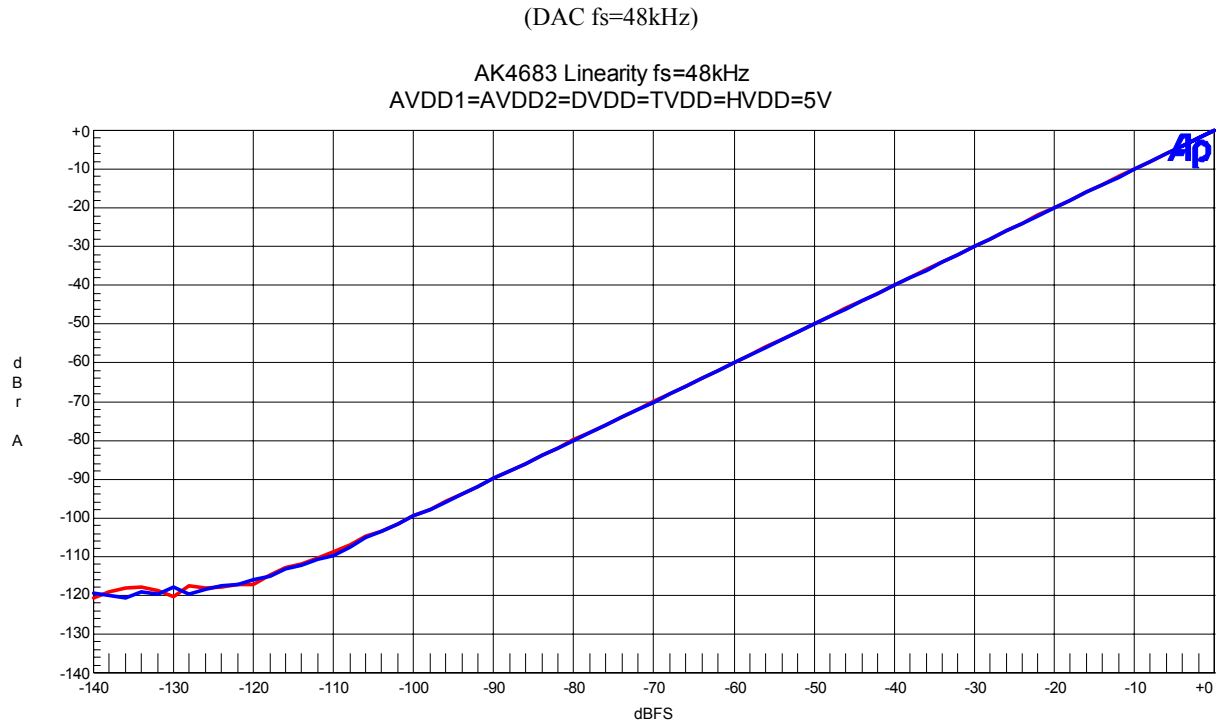


Figure 32. Linearity (Input Frequency =1kHz)

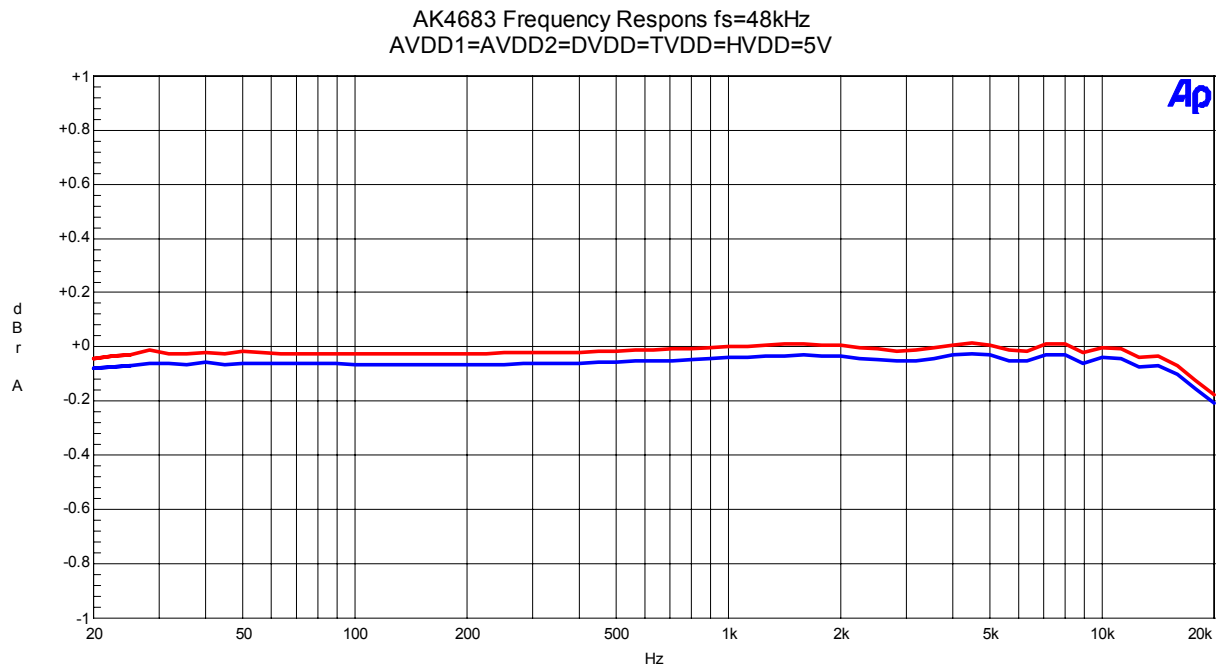


Figure 33. Frequency Response (Input Level=0dBFS)

(DAC fs=48kHz)

AK4683 Crosstalk fs=48kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

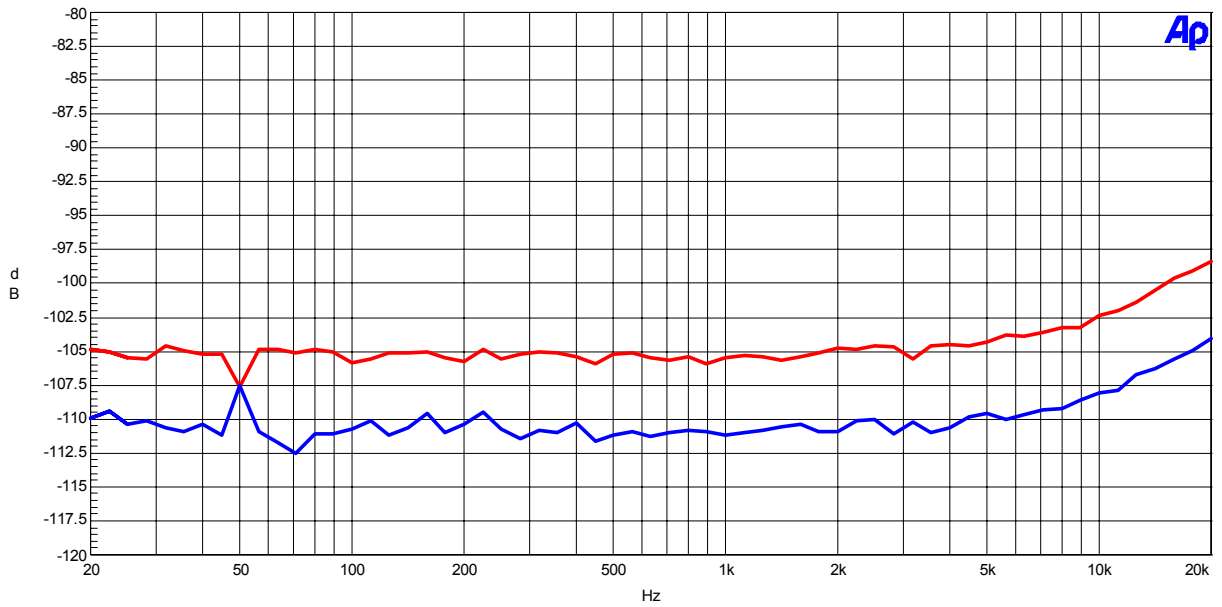


Figure 34. Cross-talk (Input Level=0dBFS)

(DAC fs=96kHz)

AK4683 FFT fs=96kHz, 0dB input
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

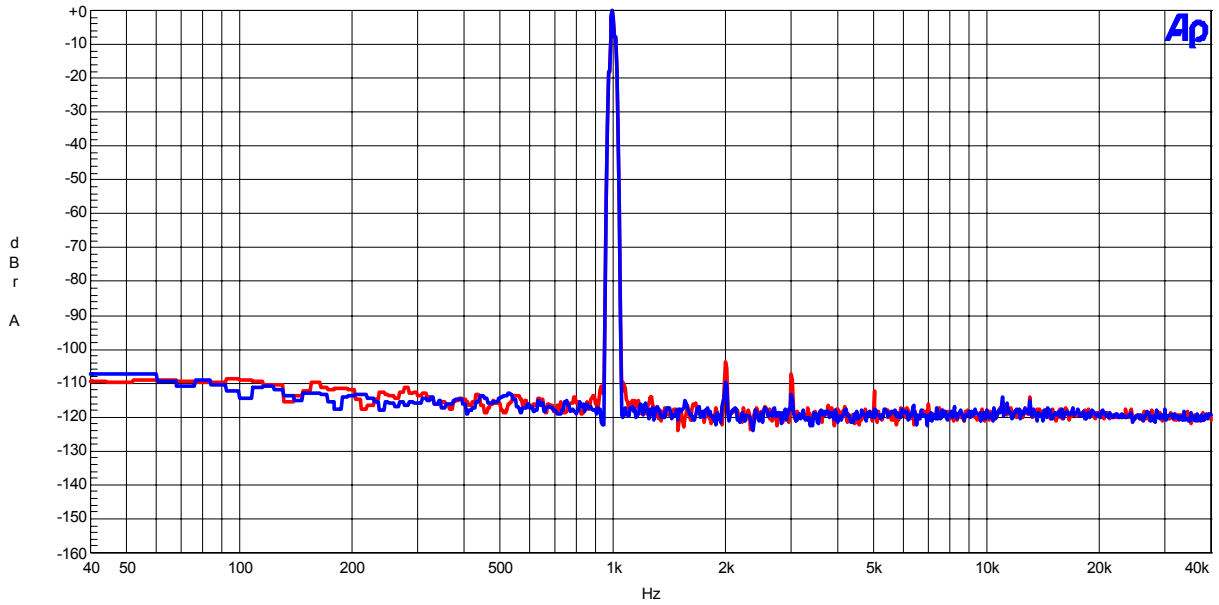


Figure 35. FFT(Input Frequency =1kHz, Input Level=0dBFS)

AK4683 FFT (Notch) fs=96kHz, 0dB input
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

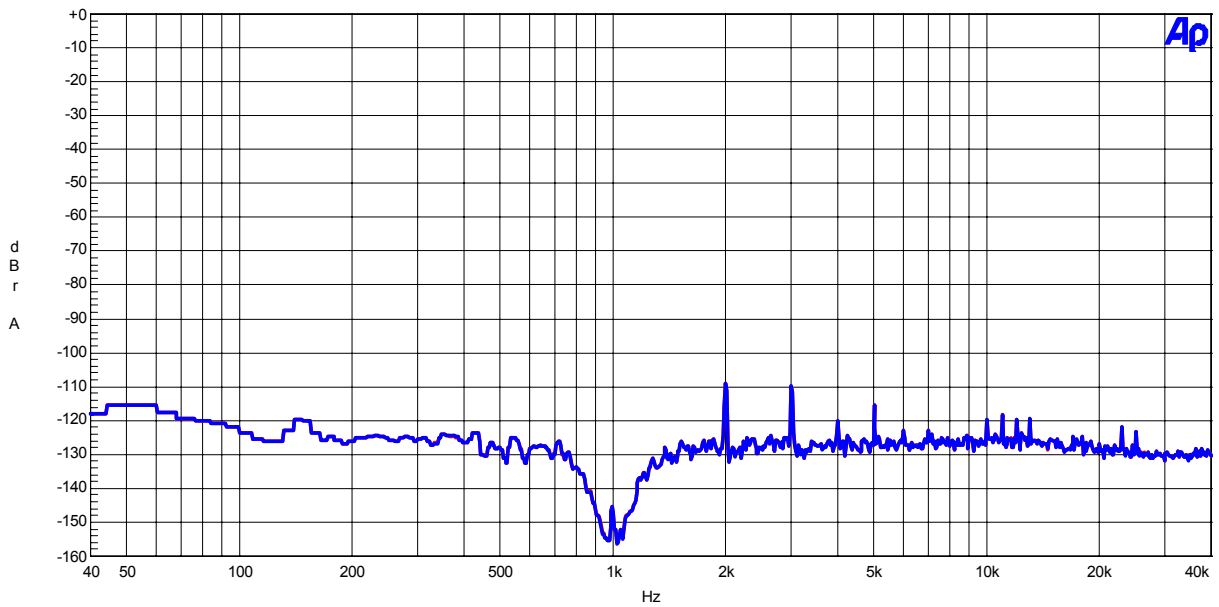


Figure 36. FFT(Input Frequency =1kHz, Input Level=0dBFS,Notch-on)

(DAC fs=96kHz)

AK4683 FFT fs=96kHz, -60dB input
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

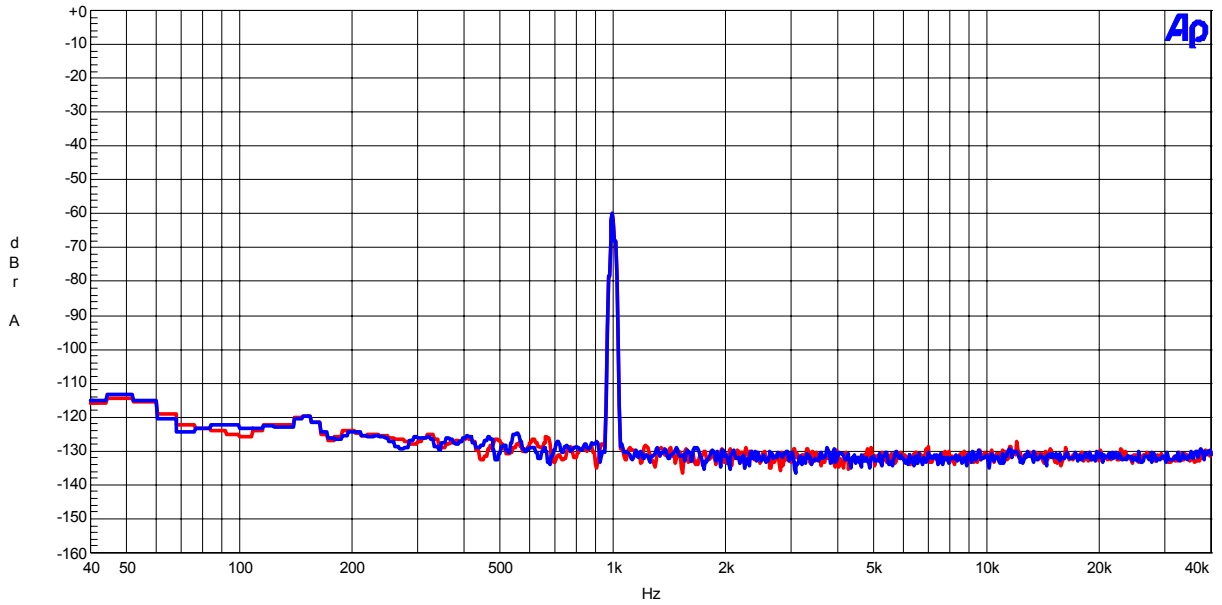


Figure 37. FFT(Input Frequency =1kHz, Input Level=-60dBFS)

AK4683 FFT fs=96kHz, No signal input
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

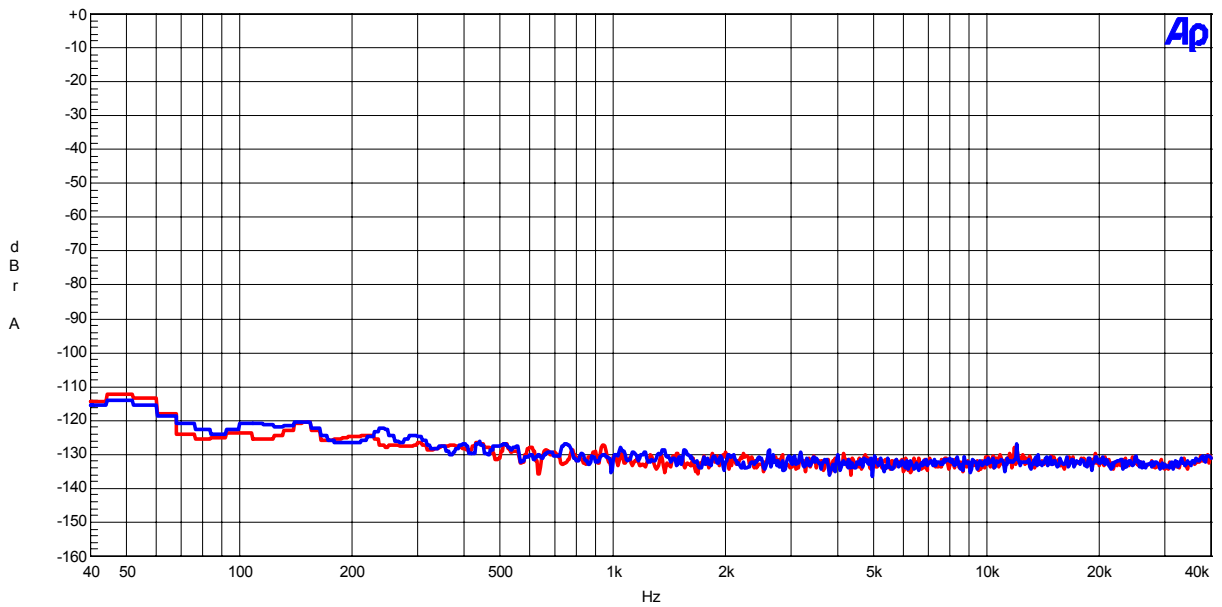
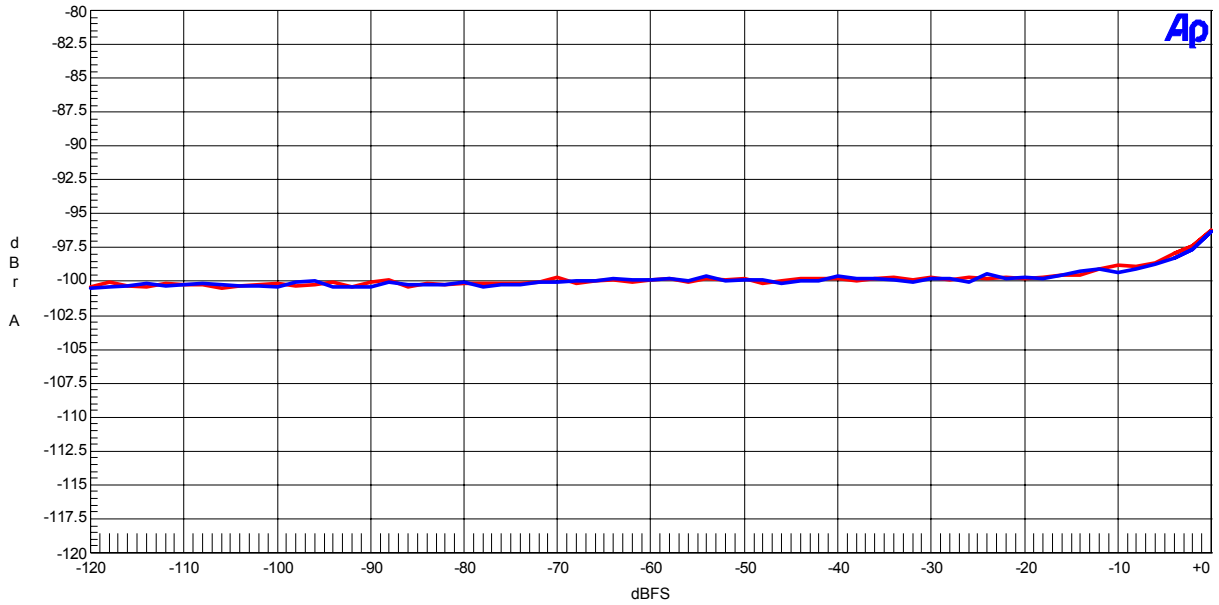


Figure 38. FFT(noise floor)

(DAC fs=96kHz)

AK4683 THD+N vs Input Level fs=96kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V



FigureFigure 39. THD+N vs Input Level (Input Frequency =1kHz)

AK4683 THD+N vs Input Frequency fs=96kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

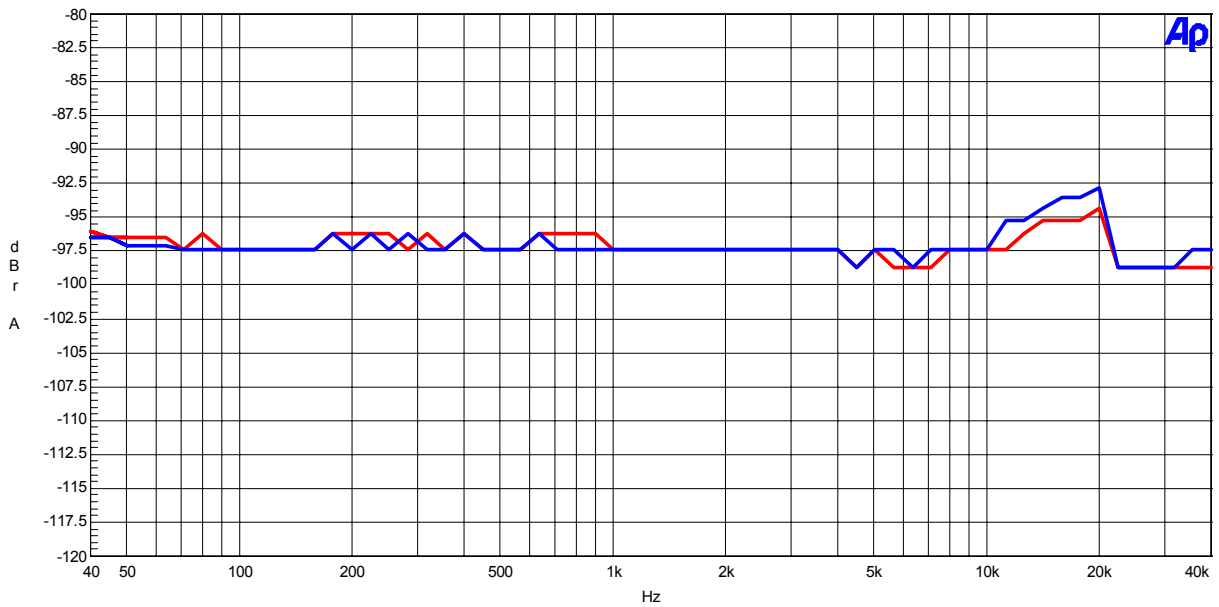


Figure 40. THD+N vs fin (Input Level=0dBFS)

(DAC fs=96kHz)

AK4683 Linearity fs=96kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

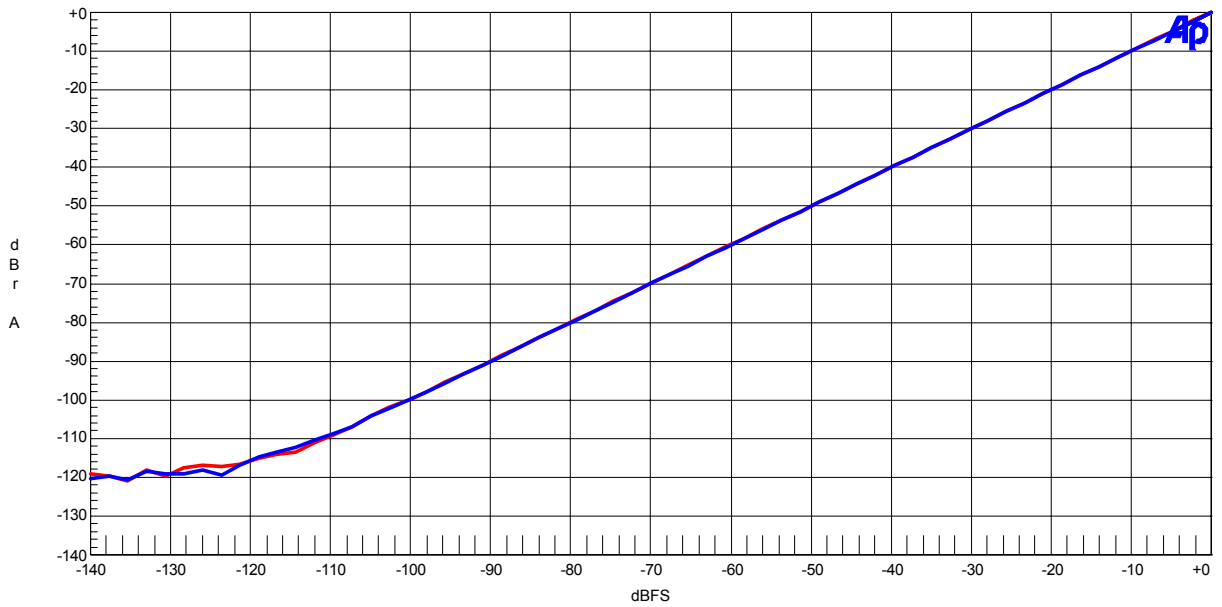


Figure 41. Linearity (Input Frequency =1kHz)

AK4683 Frequency Respons fs=96kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

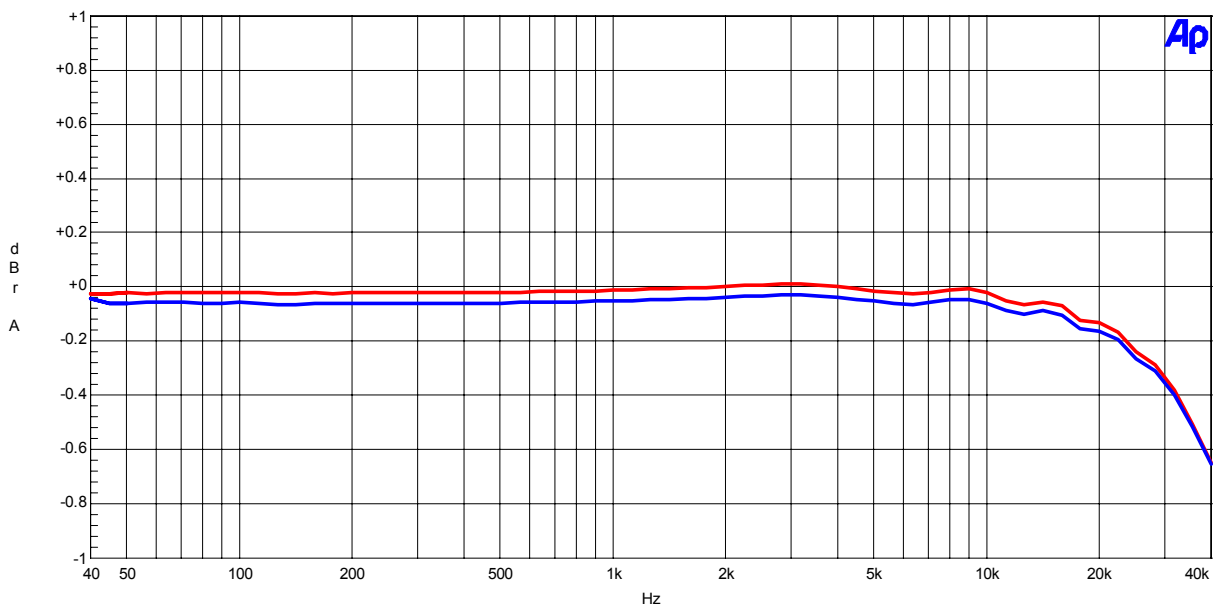


Figure 42. Frequency Response (Input Level=0dBFS)

(DAC fs=96kHz)

AK4683 Crosstalk fs=96kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

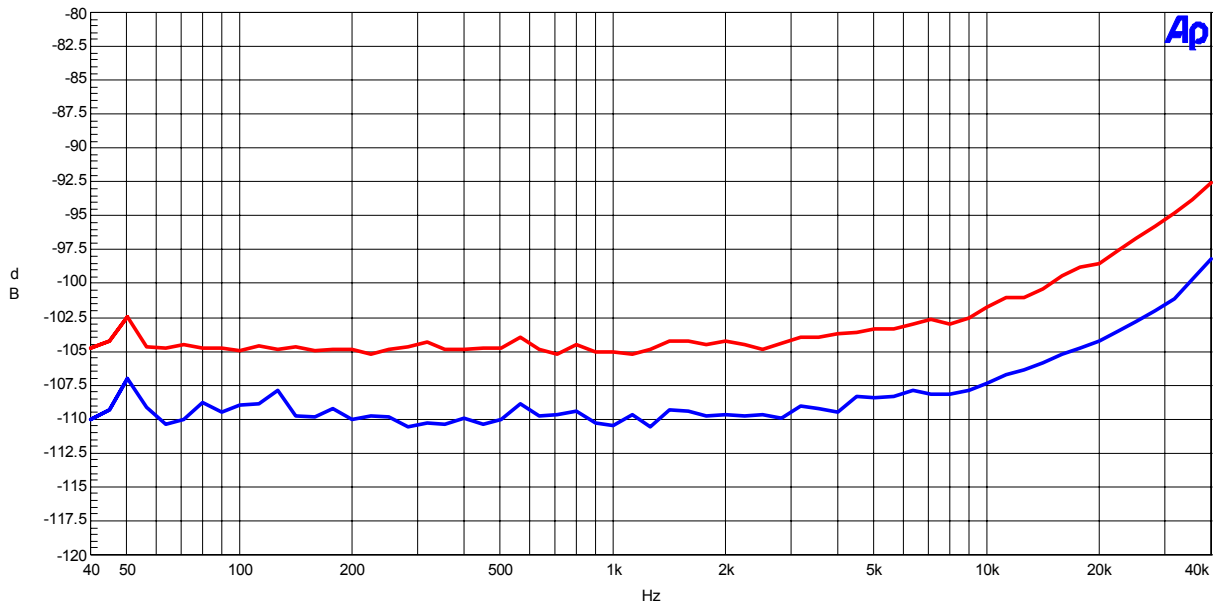


Figure 43. Cross-talk (Input Level=0dBFS)

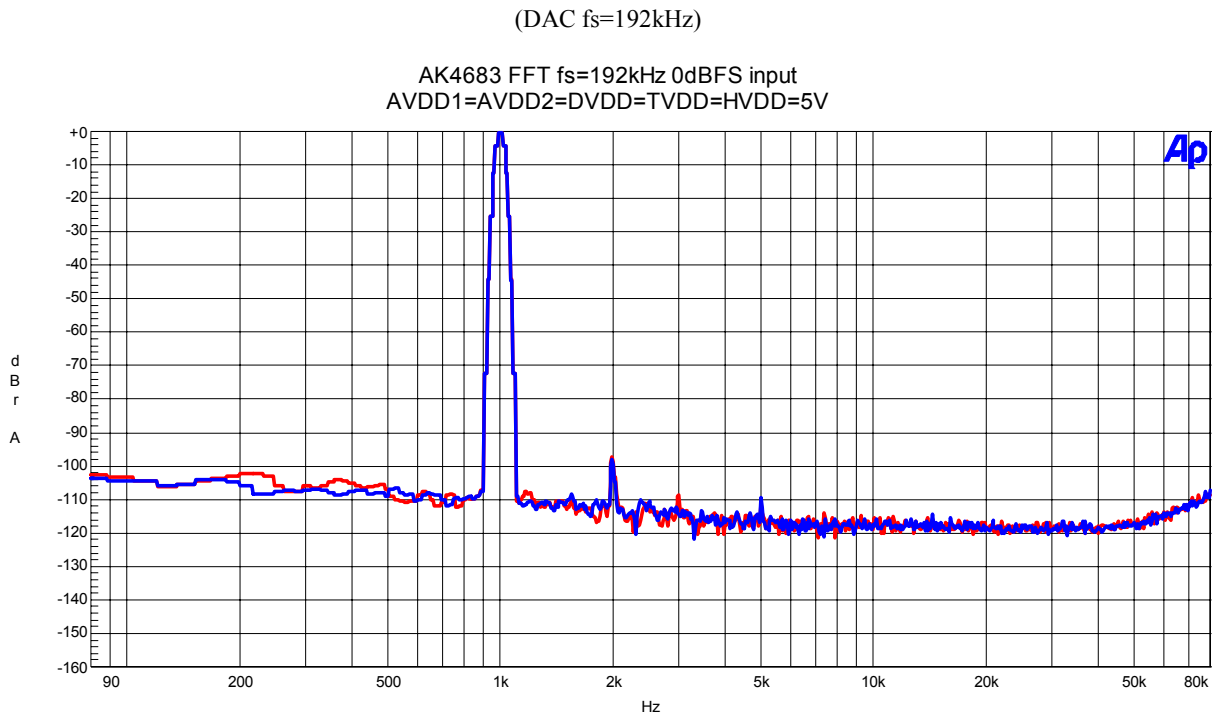


Figure 44. FFT(Input Frequency =1kHz, Input Level=0dBFS)

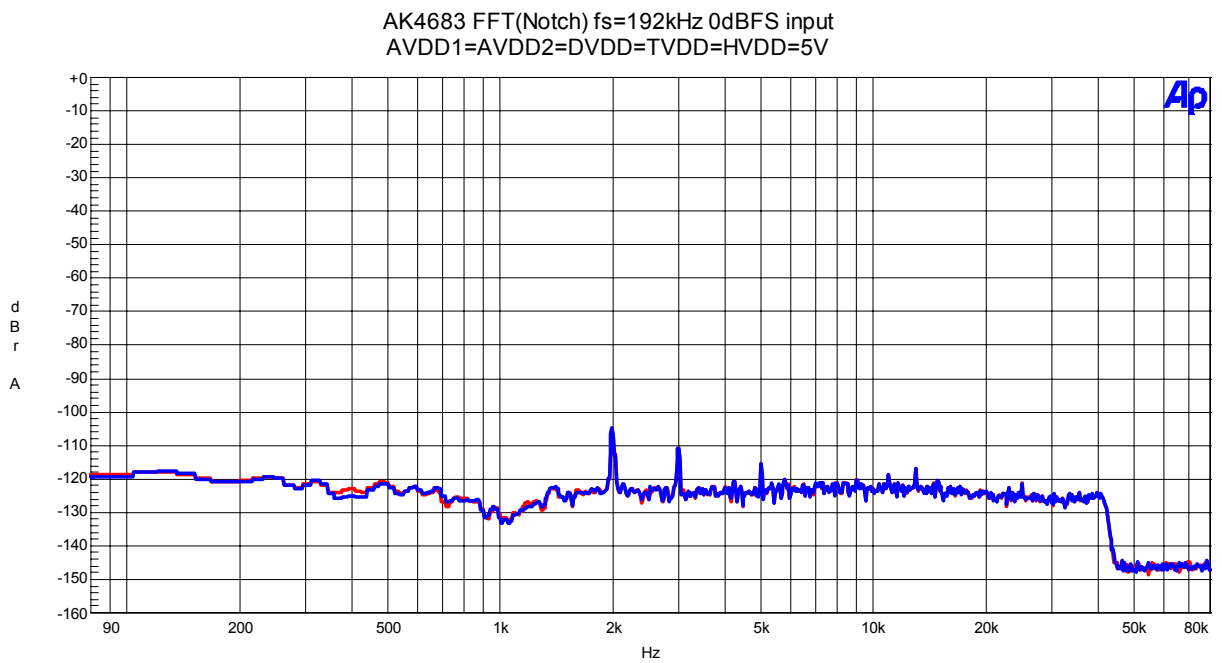


Figure 45. FFT(Input Frequency =1kHz, Input Level=0dBFS,Notch-on)

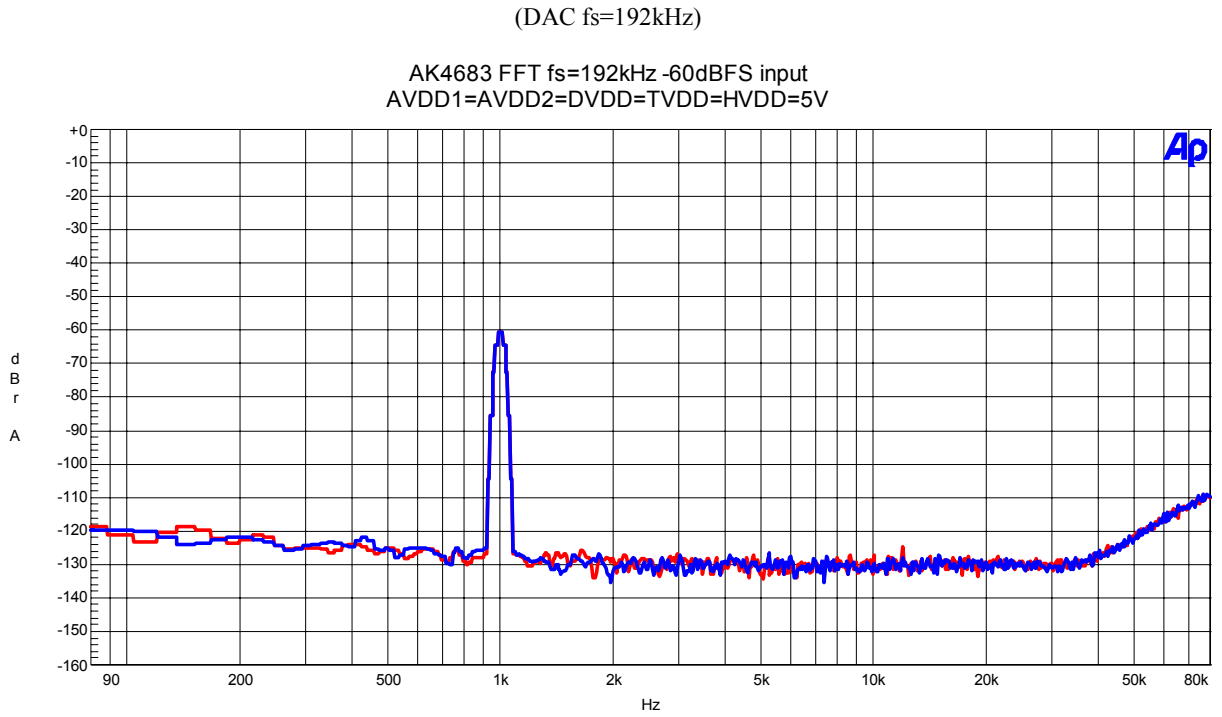


Figure 46. FFT(Input Frequency =1kHz, Input Level=-60dBFS)

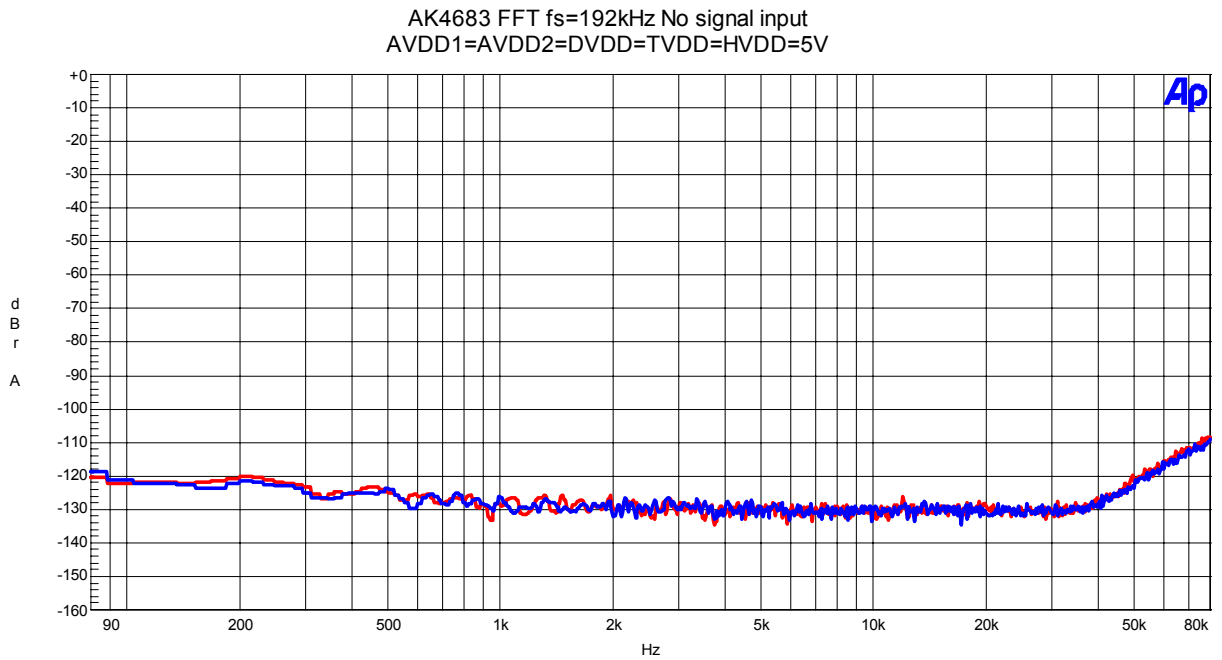


Figure 47. FFT(noise floor)

(DAC fs=192kHz)

AK4683 THD+N vs Input Level fs=192kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

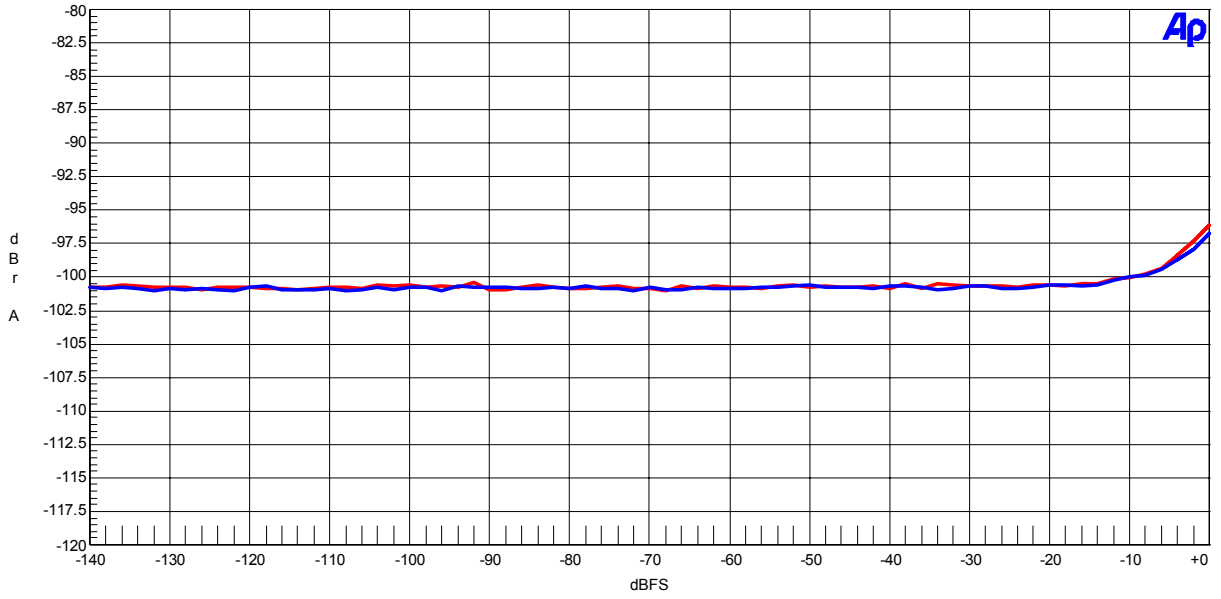


Figure 48. THD+N vs Input Level (Input Frequency =1kHz)

AK4683 THD+N vs Input Frequency fs=192kHz
AVDD1=AVDD2=DVDD=TVDD=HVDD=5V

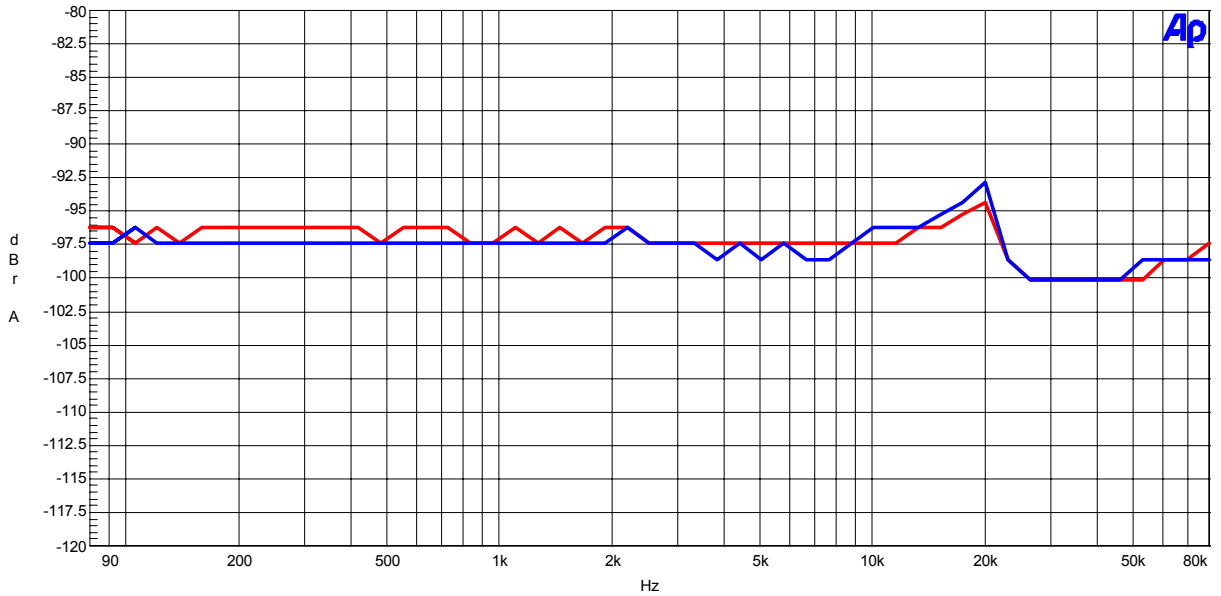


Figure 49. THD+N vs Input Frequency (Input Level=0dBFS)

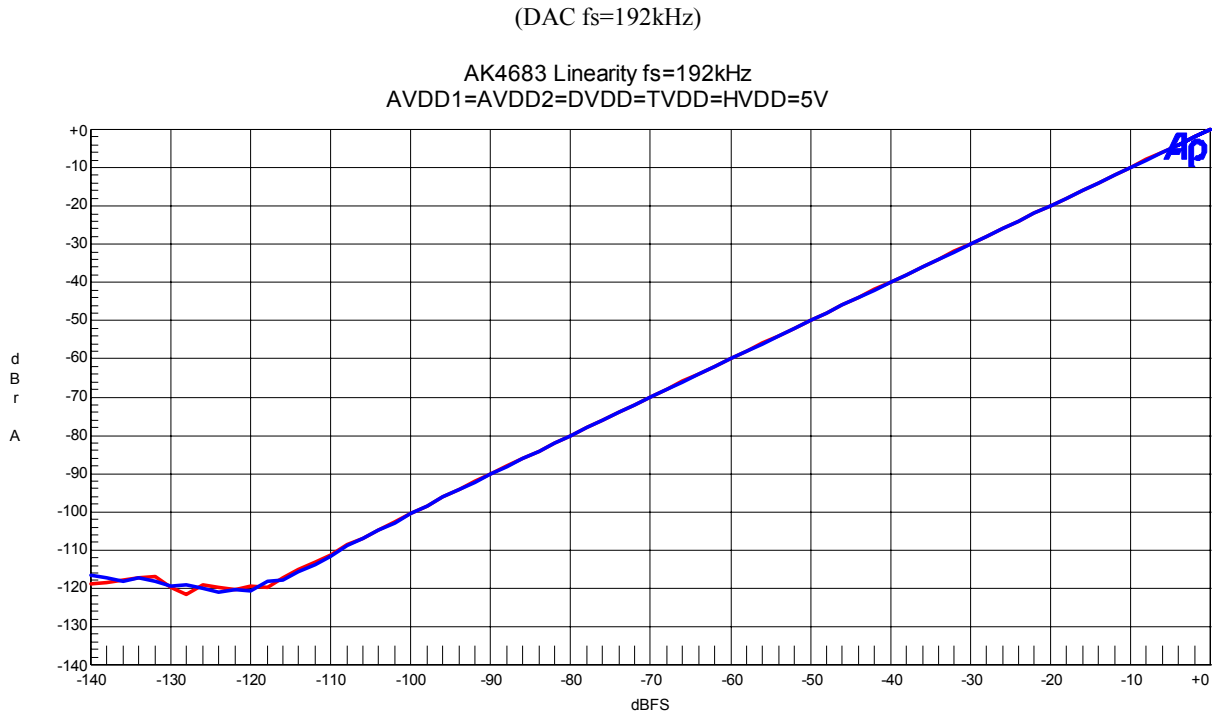


Figure 50. Linearity (f Input Frequency =1kHz)

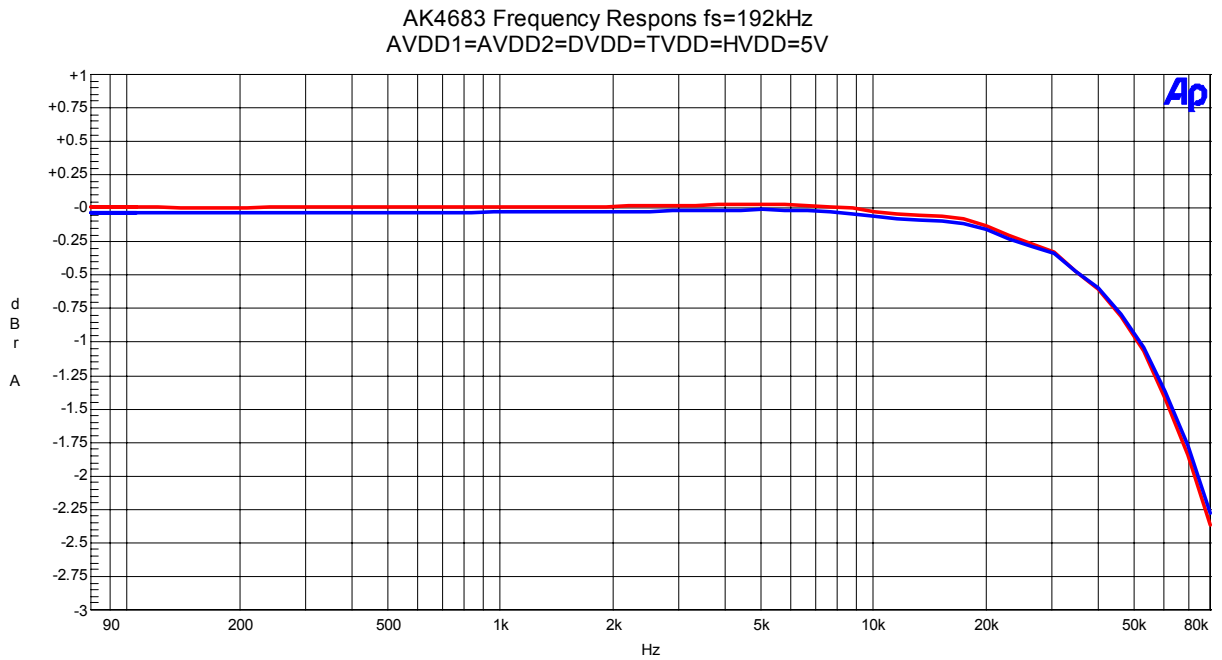


Figure 51. Frequency Response (Input Level=0dBFS)

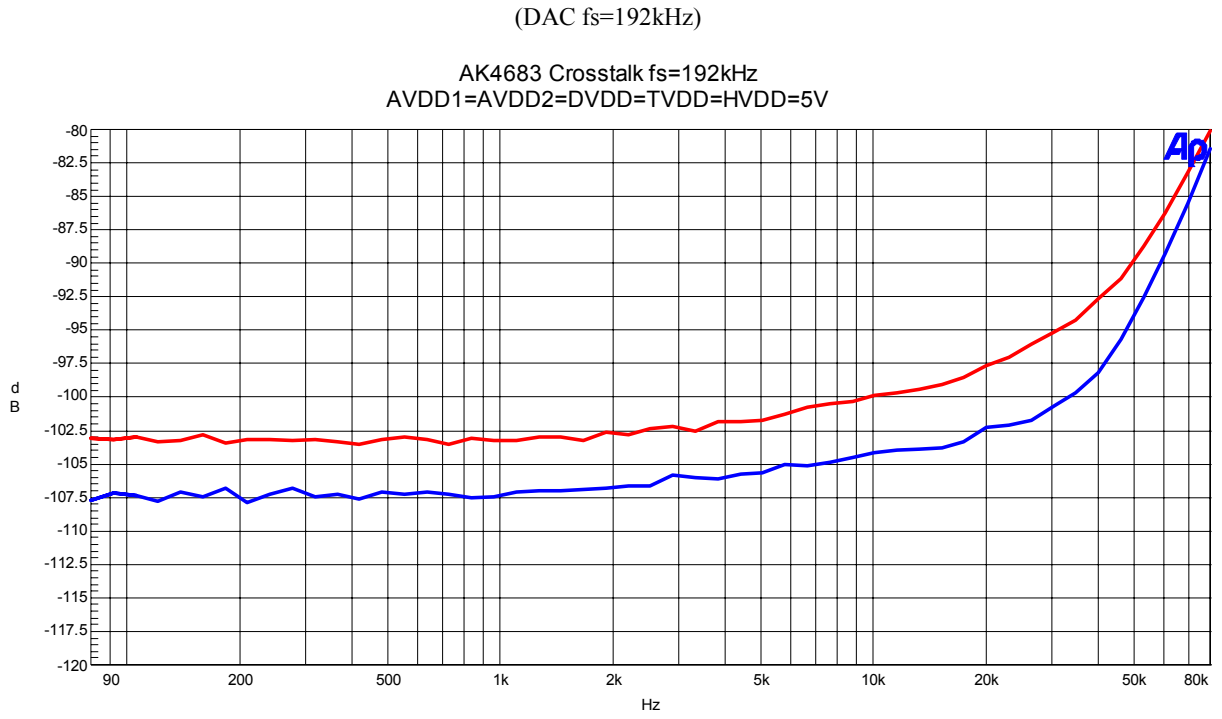


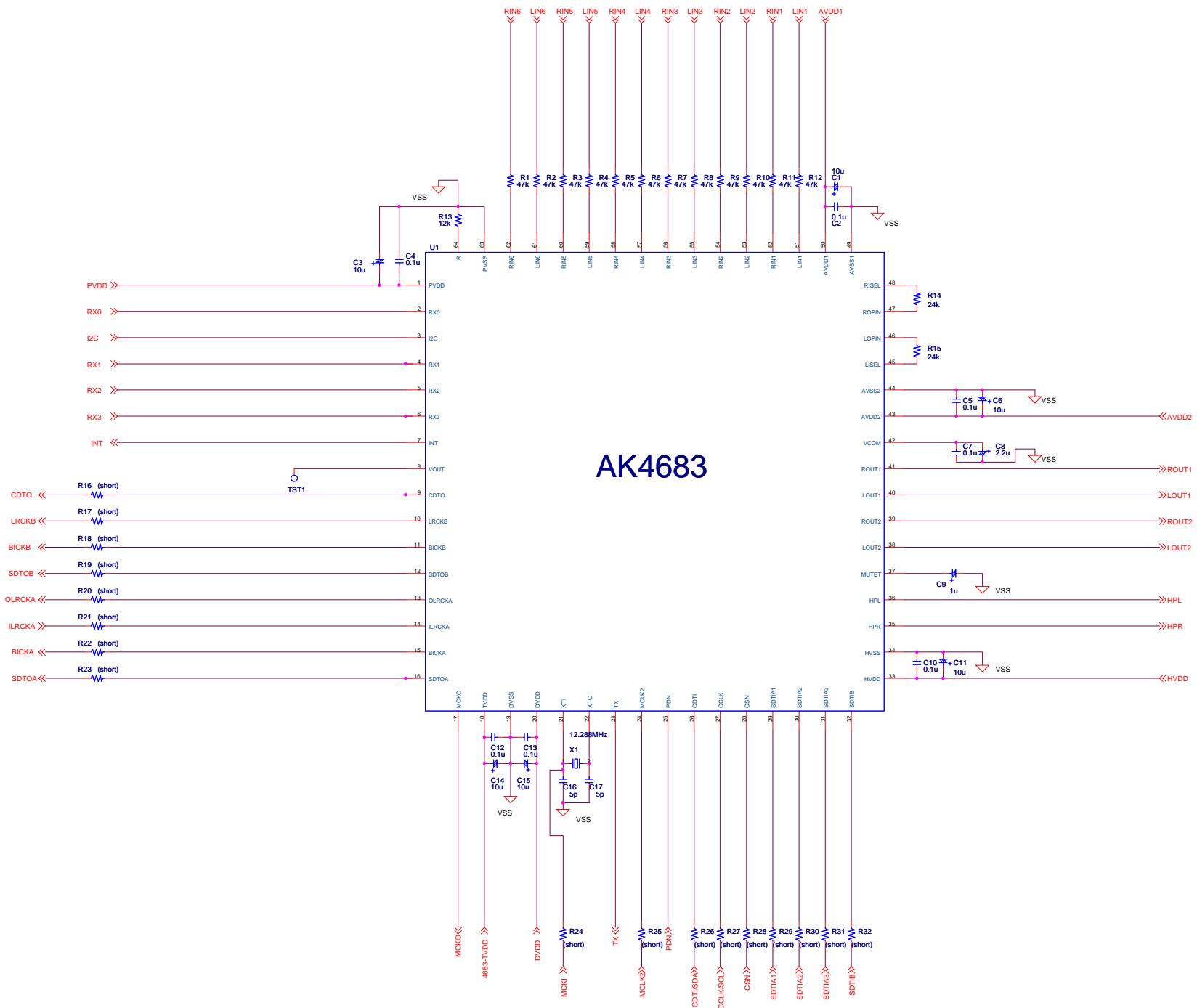
Figure 52. Cross-talk (Input Level=0dBFS)

Revision History

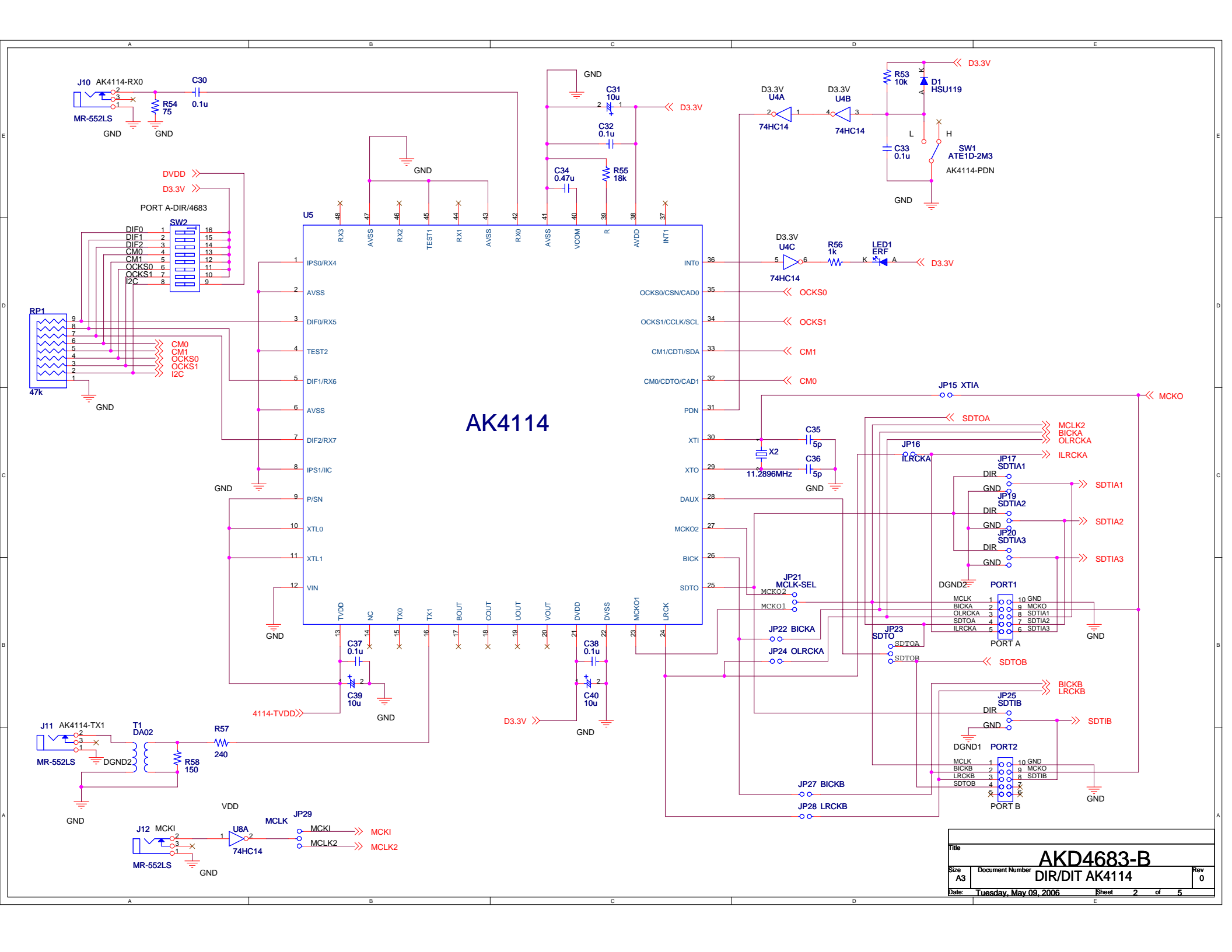
Date (YY/MM/DD)	Manual Revision	Board Revision	Reason	Contents
06/05/12	KM080900	0	First Edition	
06/05/25	KM080901	0	Error Correct	P.3. (3) DAC with external DIR 2. Setting of jumper pin Add (Default input of PORTA is SDTIA1.) JP16 (ILRCK)→JP16 (ILRCKA) JP19(SDTIA2) : PORTA: DIR→GND JP20(SDTIA3) : PORTA: DIR→GND Add column of JP23 (SDTO) 4. Setting of DIP switch P.4. (4) ADC with external DIT 2. Setting of jumper pin JP16 (ILRCK)→JP16 (ILRCKA) Add column of JP23 (SDTO) 4. Setting of DIP switch SW2 (PORT-DIR/4683)→SW2 (PORTA-DIR/4683) P.7. Set up Jumper pins JP15 (XTIA) : Evaluation Mode 4 : Open→Short JP16 (ILRCKA) : Evaluation Mode 4 : Short → Open JP19(SDTIA2) : Evaluation Mode 3: DIR→GND JP20(SDTIA3) : Evaluation Mode 3: DIR→GND JP21(MCLK-SEL) : Evaluation Mode 1, 2, 4, 5 : MCKO1→Open JP24 (OLRCK)→JP24 (OLRCKA) JP24 (OLRCKA) : Evaluation Mode 4 : Open → Short JP25 (SDTIB) : Evaluation Mode 3 : DIR → GND JP27 (BICKB) : Evaluation Mode 1, 2, 3, 4, 5 : Short → Open JP28 (LRCKB) : Evaluation Mode 1, 2, 3, 4, 5 : Short → Open JP29(MCLK) : Evaluation Mode 1, 2, 3, 4, 5 : MCKI→Open

IMPORTANT NOTICE

- These products and their specifications are subject to change without notice. Before considering any use or application, consult the Asahi Kasei Microsystems Co., Ltd. (AKM) sales office or authorized distributor concerning their current status.
- AKM assumes no liability for infringement of any patent, intellectual property, or other right in the application or use of any information contained herein.
- Any export of these products, or devices or systems containing them, may require an export license or other official approval under the law and regulations of the country of export pertaining to customs and tariffs, currency exchange, or strategic materials.
- AKM products are neither intended nor authorized for use as critical components in any safety, life support, or other hazard related device or system, and AKM assumes no responsibility relating to any such use, except with the express written consent of the Representative Director of AKM. As used here:
 - (a) A hazard related device or system is one designed or intended for life support or maintenance of safety or for applications in medicine, aerospace, nuclear energy, or other fields, in which its failure to function or perform may reasonably be expected to result in loss of life or in significant injury or damage to person or property.
 - (b) A critical component is one whose failure to function or perform may reasonably be expected to result, whether directly or indirectly, in the loss of the safety or effectiveness of the device or system containing it, and which must therefore meet very high standards of performance and reliability.
- It is the responsibility of the buyer or distributor of an AKM product who distributes, disposes of, or otherwise places the product with a third party to notify that party in advance of the above content and conditions, and the buyer or distributor agrees to assume any and all responsibility and liability for and hold AKM harmless from any and all claims arising from the use of said product in the absence of such notification.

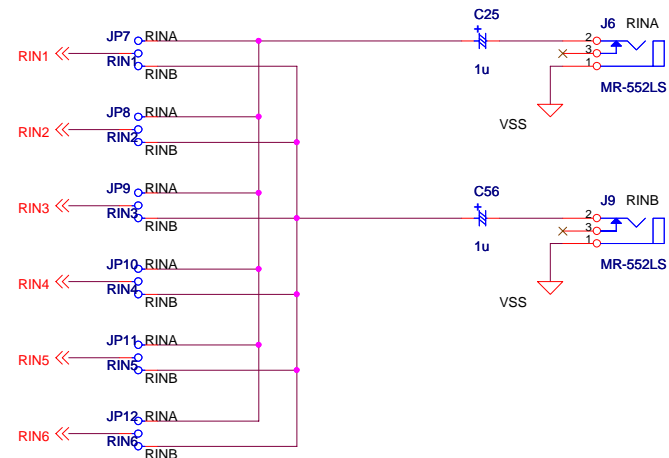
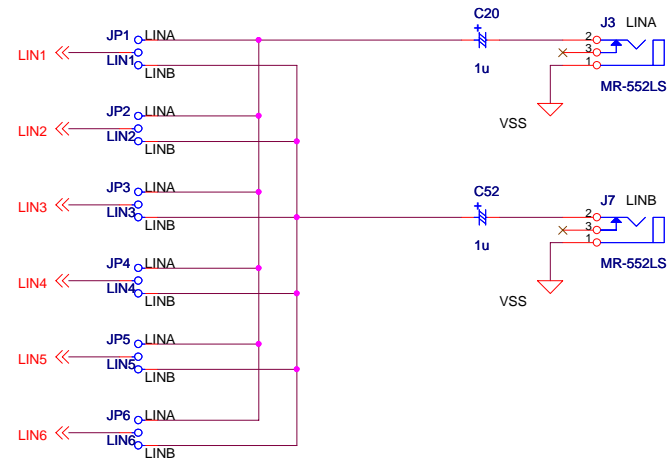
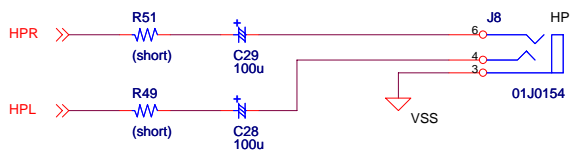
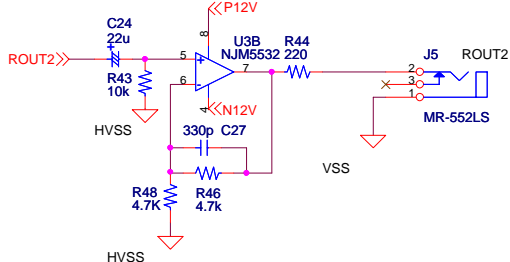
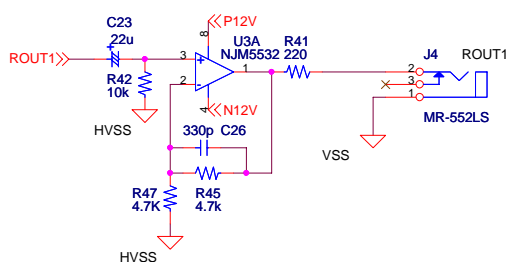
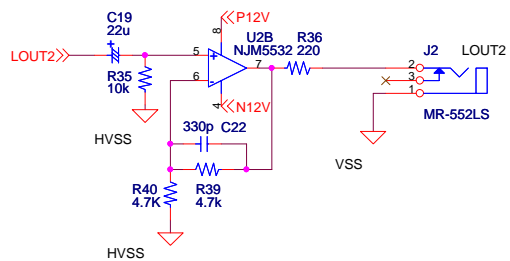
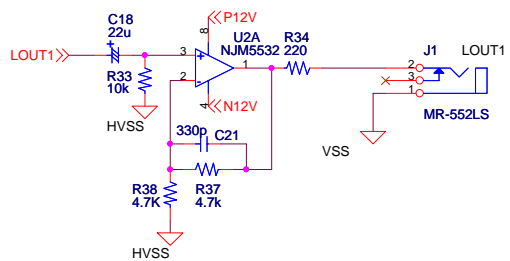


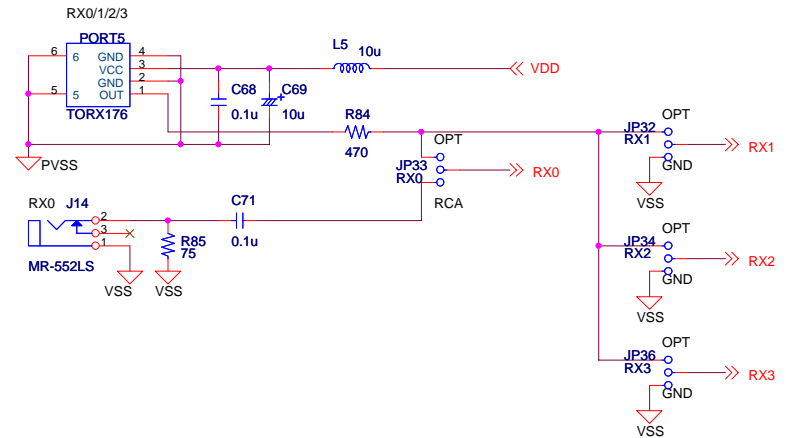
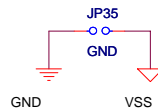
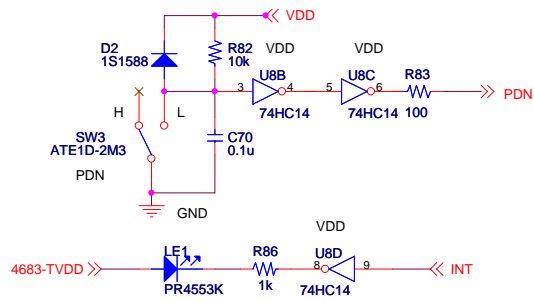
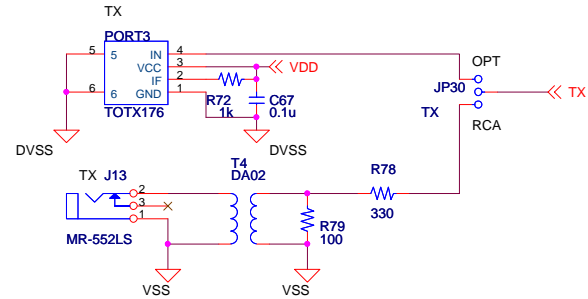
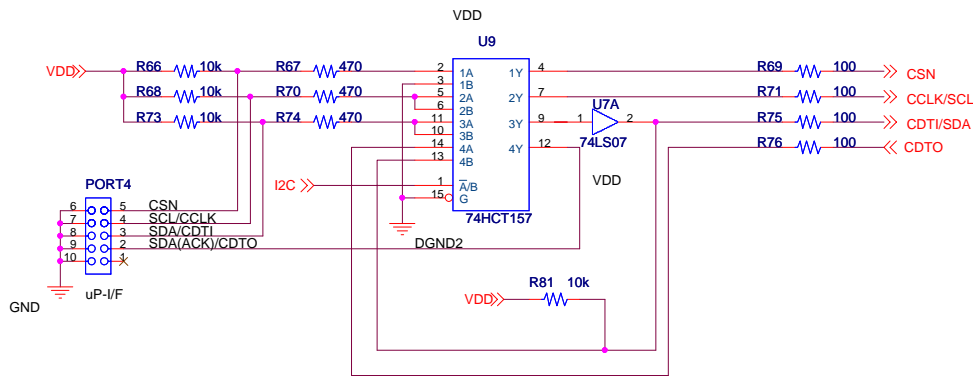
AK4683



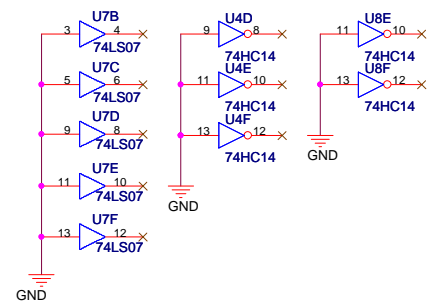
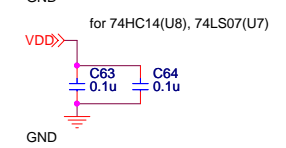
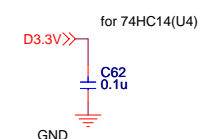
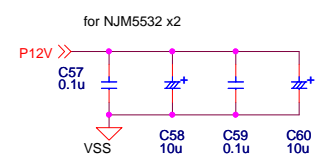
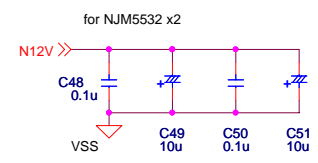
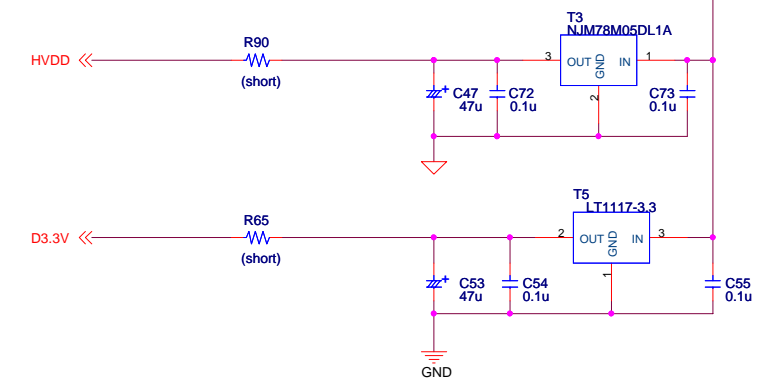
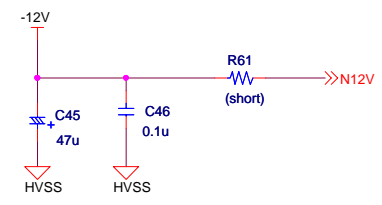
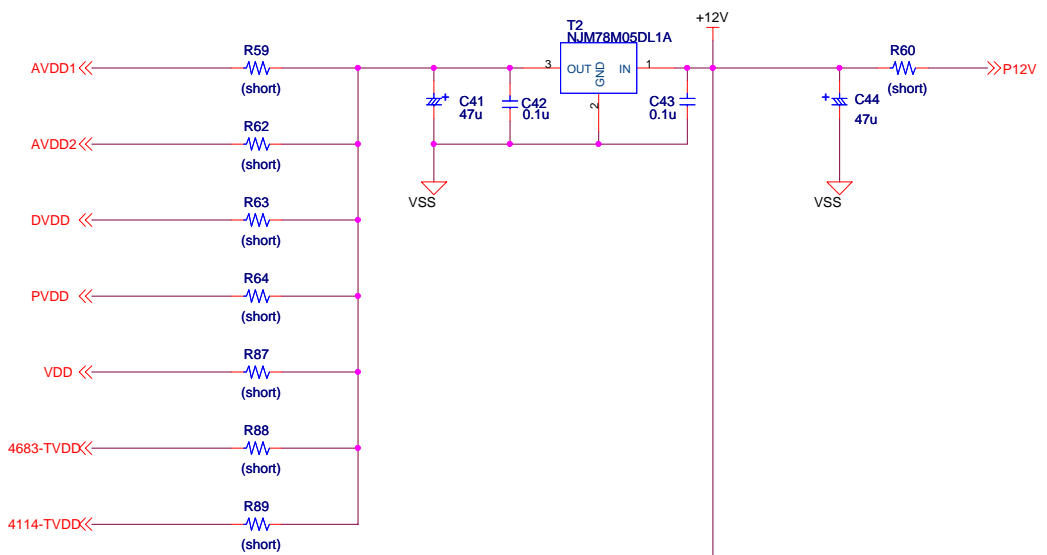
AK4114

Title	AKD4683-B		Rev	0
Size	A3	Document Number	DIR/DIT AK4114	
Date:	Tuesday, May 09, 2006		Sheet	2 of 5

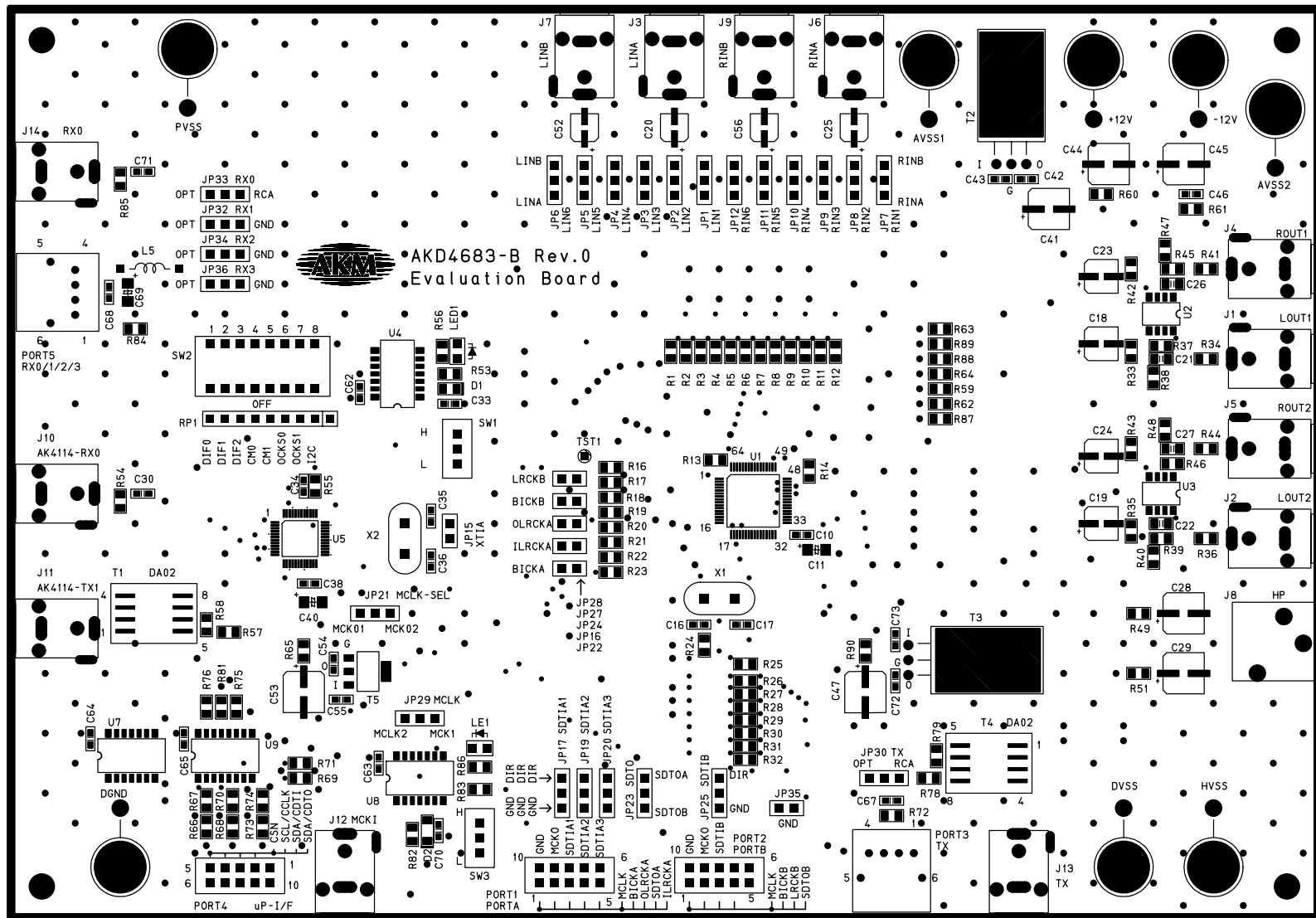




Title			AKD4683-B		
Size	Document Number				Rev
A3	INPUT/OUTPUT DIGITAL				0
Date:	Tuesday, May 09, 2006	Sheet	4	of	5

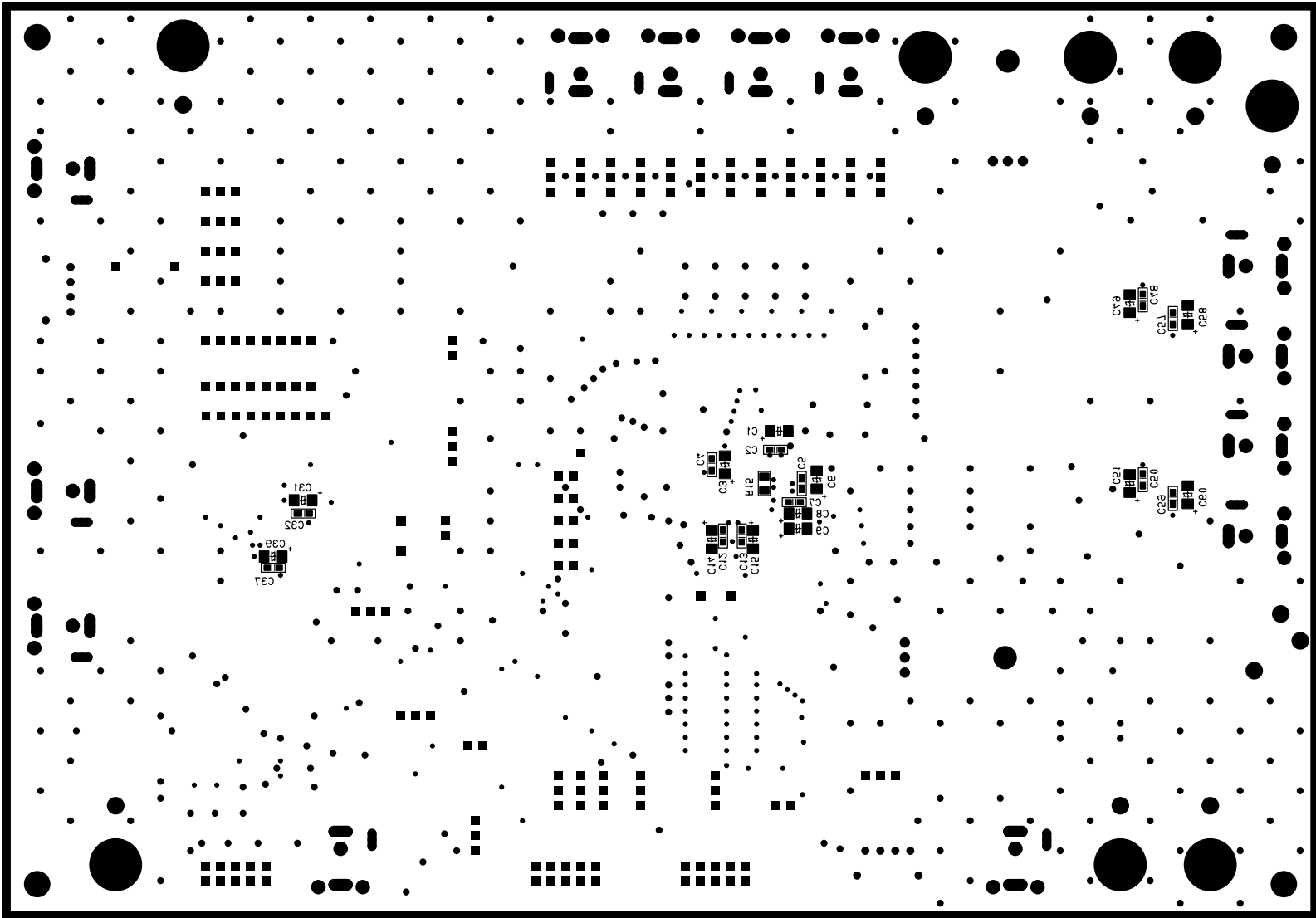


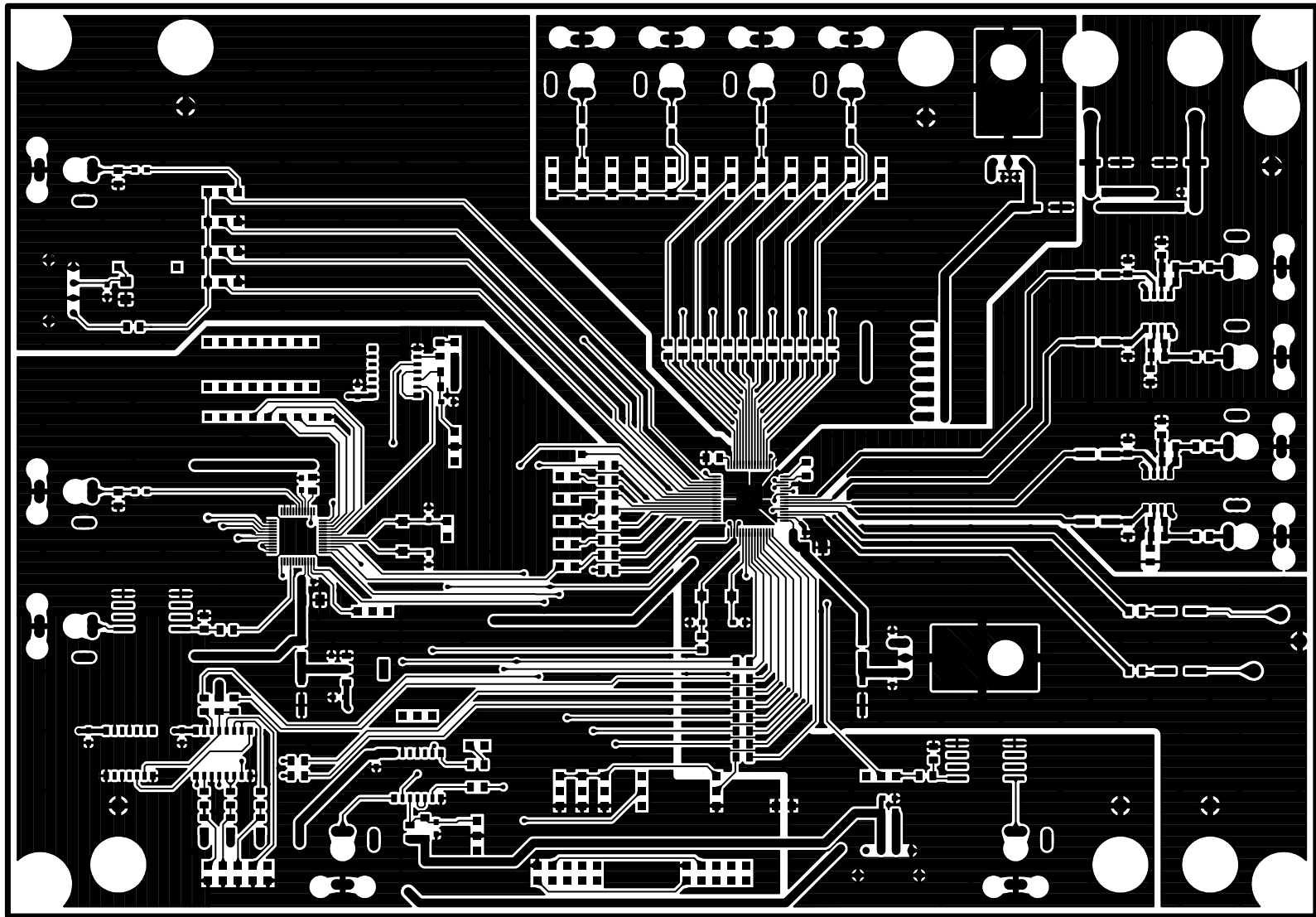
Title		AKD4683-B	
Size	Document Number	Power Supply	
A3		Date: Tuesday, May 09, 2006	Sheet 5 of 5
			Rev 0



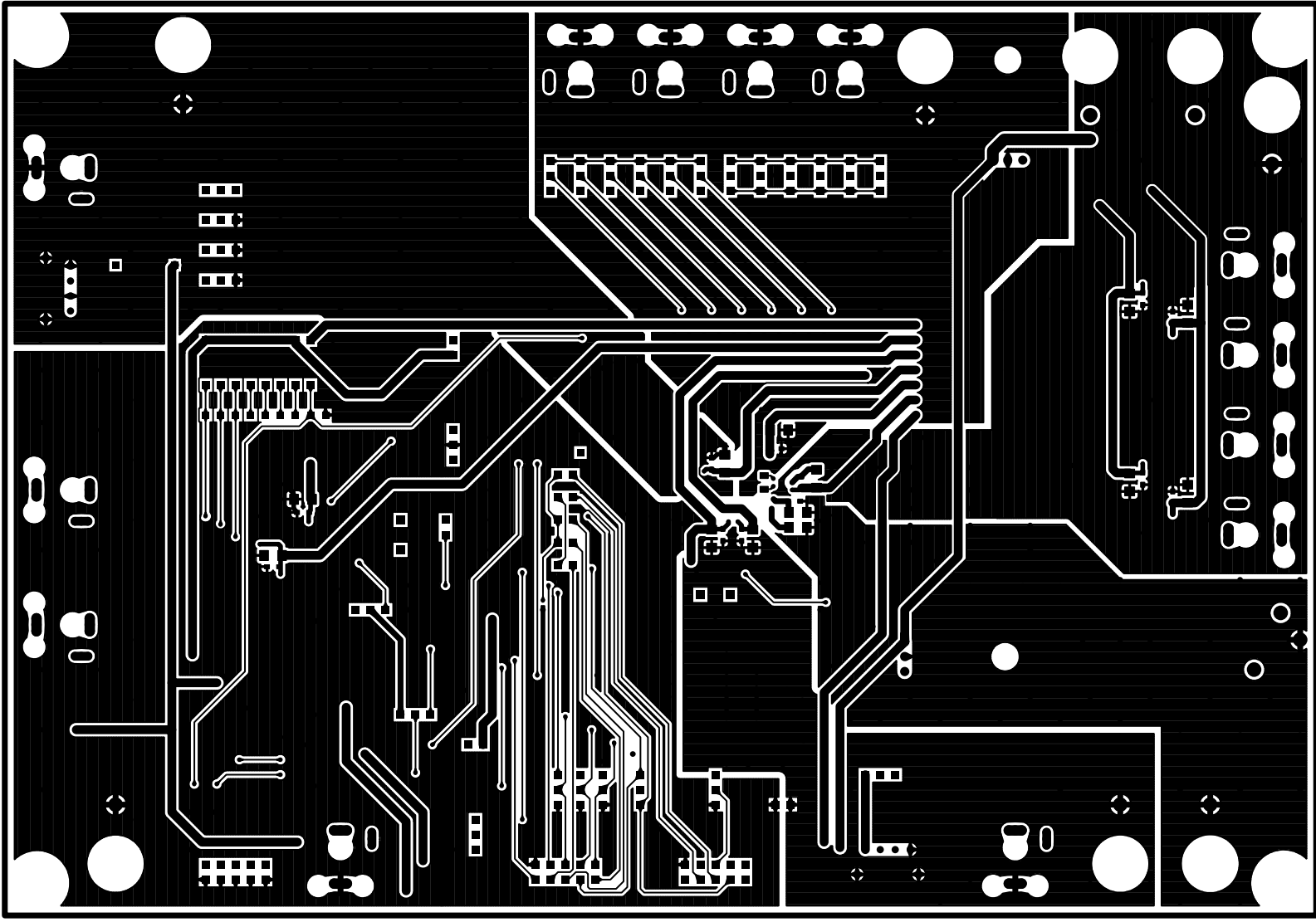
AKD4683-B L1 SILK

AKD4E83-B L3 SILK





AKD4683-B L1



AKD+E83-B L3