



STGIPL14K60

600 V, 14 A SDIP 38L molded
IGBT intelligent power module

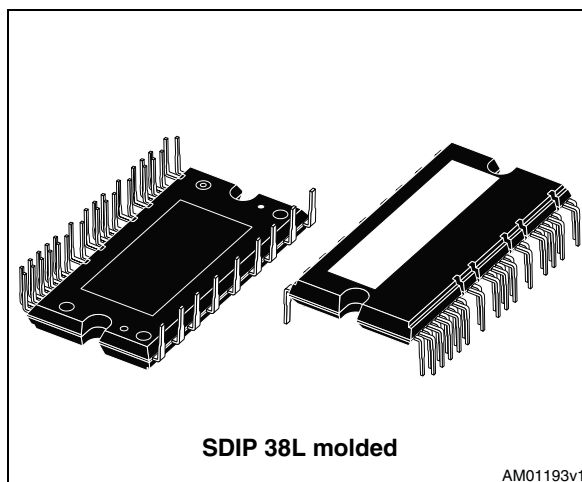
Preliminary data

Features

- 600 V, 14 A 3-phase IGBT inverter bridge including control ICs for gate driving and free-wheeling diodes
- 3.3 V, 5 V, 15 V CMOS/TTL inputs comparators with hysteresis
- Internal bootstrap diode
- Dead time and interlocking function
- 5 k Ω NTC for temperature control
- $V_{CE(sat)}$ negative temperature coefficient
- Short-circuit rugged IGBT
- Under-voltage lockout
- DBC fully isolated package
- Isolation rating of 2500 Vrms/min
- Smart shut down function
- Op-amps for advanced current sensing
- Comparators for fault protection against over current and short-circuit

Applications

- 3-phase inverters for motor drives
- Home appliances, such as washing machines, refrigerators, air conditioners



Description

The new intelligent power module developed by STMicroelectronics provides a compact, high performance AC motor drive for a simple and rugged design. It mainly targets low power inverters for applications such as home appliances and air conditioners. It combines ST proprietary control ICs with the most advanced short circuit rugged IGBT system technology.

Table 1. Device summary

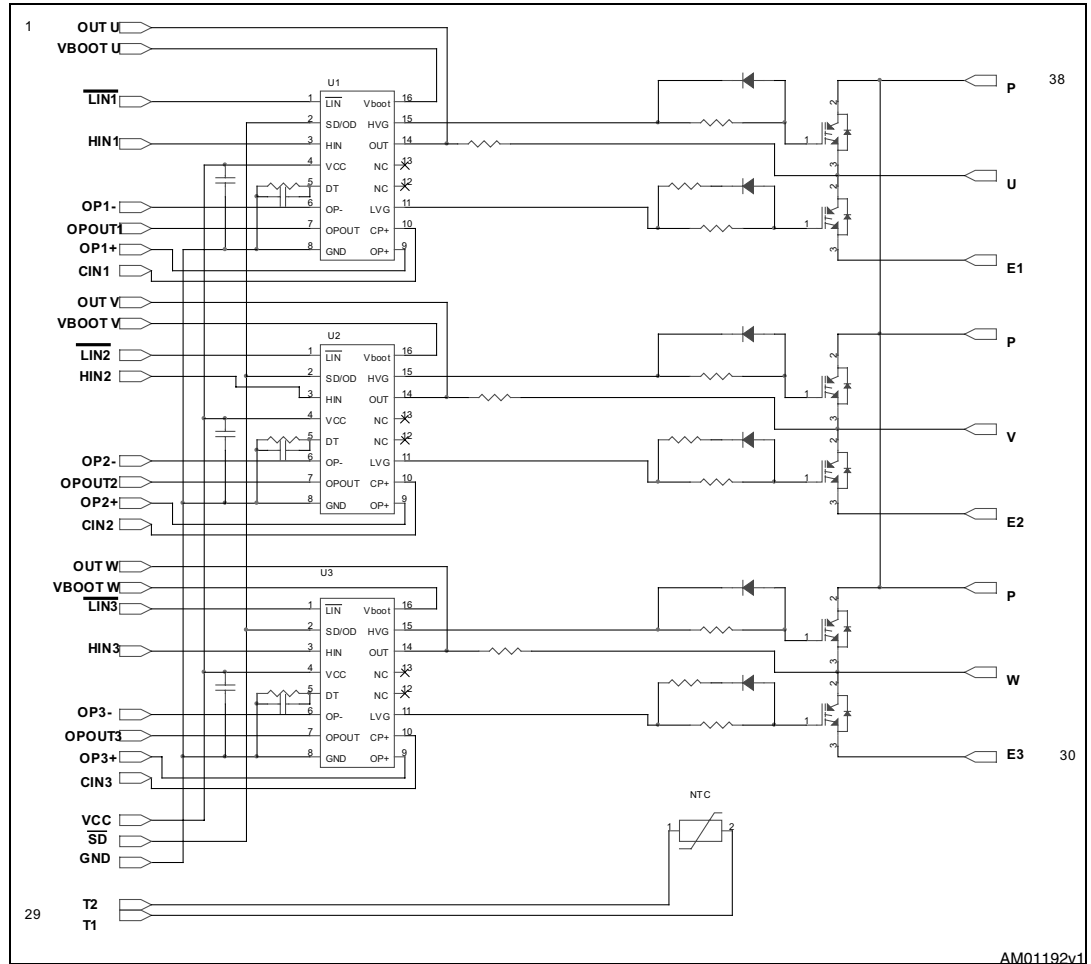
Order code	Marking	Package	Packaging
STGIPL14K60	GIPL14K60	SDIP 38L molded	Tube

Contents

1	Internal block diagram and pin configuration	3
2	Electrical ratings	5
3	Electrical characteristics	7
3.1	Control part	9
4	Applications information	13
4.1	Recommendations	14
5	Package mechanical data	15
6	Revision history	17

1 Internal block diagram and pin configuration

Figure 1. Internal block diagram

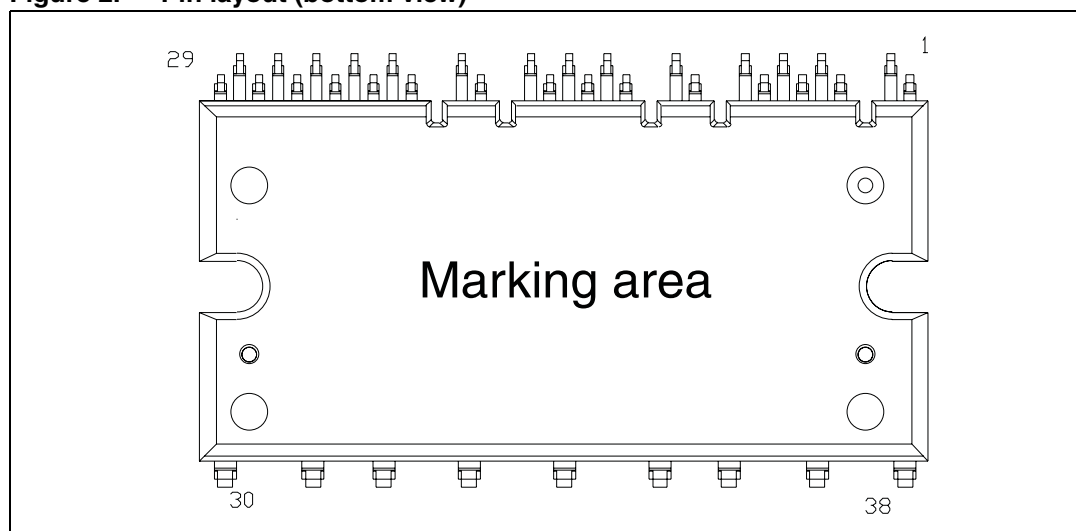


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Table 2. Pins description

Pin no.	Pin name	Pin no.	Pin name
1	OUT U	20	HIN3
2	Vboot U	21	OP3-
3	$\overline{\text{LIN1}}$	22	OPOUT3
4	HIN1	23	OP3+
5	OP1-	24	CIN3
6	OPOUT1	25	V _{CC}
7	OP1+	26	$\overline{\text{SD}}$
8	CIN1	27	GND
9	OUT V	28	T1
10	Vboot V	29	T2
11	$\overline{\text{LIN2}}$	30	E3
12	HIN2	31	W
13	OP2-	32	P
14	OPOUT2	33	E2
15	OP2+	34	V
16	CIN2	35	P
17	OUT W	36	E1
18	Vboot W	37	U
19	$\overline{\text{LIN3}}$	38	P

Figure 2. Pin layout (bottom view)



2 Electrical ratings

Table 3. Absolute maximum ratings: inverter part

Symbol	Parameter	Value	Unit
V_{PE}	Supply voltage (applied between P-E1, E2, E3)	450	V
$V_{PE(surge)}$	Supply voltage (surge) (applied between P-E1, E2, E3))	500	V
V_{CES}	Collector emitter voltage ($HIN = 0, \overline{LIN} = 1$)	600	V
$\pm I_C^{(1)}$	Each IGBT continuous collector current at $T_C = 25^\circ\text{C}$	14	A
$\pm I_{CP}^{(2)}$	Each IGBT pulsed collector current	30	A
P_{TOT}	Each IGBT total dissipation at $T_C = 25^\circ\text{C}$	35	W
t_{scw}	Short circuit withstand time, $V_{CE} = 0.5 V_{(BR)CES}$ $T_j = 125^\circ\text{C}, V_{CC} = V_{boot} = 15\text{ V}, V_i^{(3)} = 5\text{ V}$	5	μs

1. Calculated according to the iterative formula:

$$I_C(T_C) = \frac{T_{j(max)} - T_C}{R_{thj-c} \times V_{CE(sat)(max)}(T_{j(max)}, I_C(T_C))}$$

- Pulse width limited by max junction temperature
- Applied between HIN_i (LIN_i) - G_{NDi} for $i=1,2,3$

Table 4. Absolute maximum ratings: control part

Symbol	Parameter	Value	Unit
V_{OUT}	Output voltage	$V_{boot} - 21$ to $V_{boot} + 0.3$	V
V_{CC}	Supply voltage	-0.3 to +21	V
V_{op+}	Opamp non-inverting input	-0.3 to $V_{CC} + 0.3$	V
V_{op-}	Opamp inverting input	-0.3 to $V_{CC} + 0.3$	V
V_{cp+}	Comparator input voltage	-0.3 to $V_{CC} + 0.3$	V
V_{boot}	Floating supply voltage	$V_{CC} - 0.3$ to 620	V
V_I	Logic input voltage	-0.3 to 15	V
V_{od}	Open drain voltage	-0.3 to 15	V
dV_{out}/dt	Allowed output slew rate	50	V/ns

Table 5. Absolute maximum ratings: total system

Symbol	Parameter	Value	Unit
V_{OUT}	Output voltage (pins OUT U, V, W)	450	V
$V_{CC\ 1,2,3}$	Supply voltage (pins 3, 11, 19)	17	V
T_j	Operating junction temperature	-40 to 125	°C
V_{INS}	Insulation withstand voltage applied between each pin and heatsink plate (AC voltage, $t = 60\text{sec.}$)	2500	V

Table 6. Thermal data

Symbol	Parameter	Value	Unit
$R_{th(j-c)}$	Thermal resistance junction-case single IGBT	2.8	°C/W
	Thermal resistance junction-case single diode	5	°C/W

3 Electrical characteristics

($T_j = 25\text{ °C}$ unless otherwise specified)

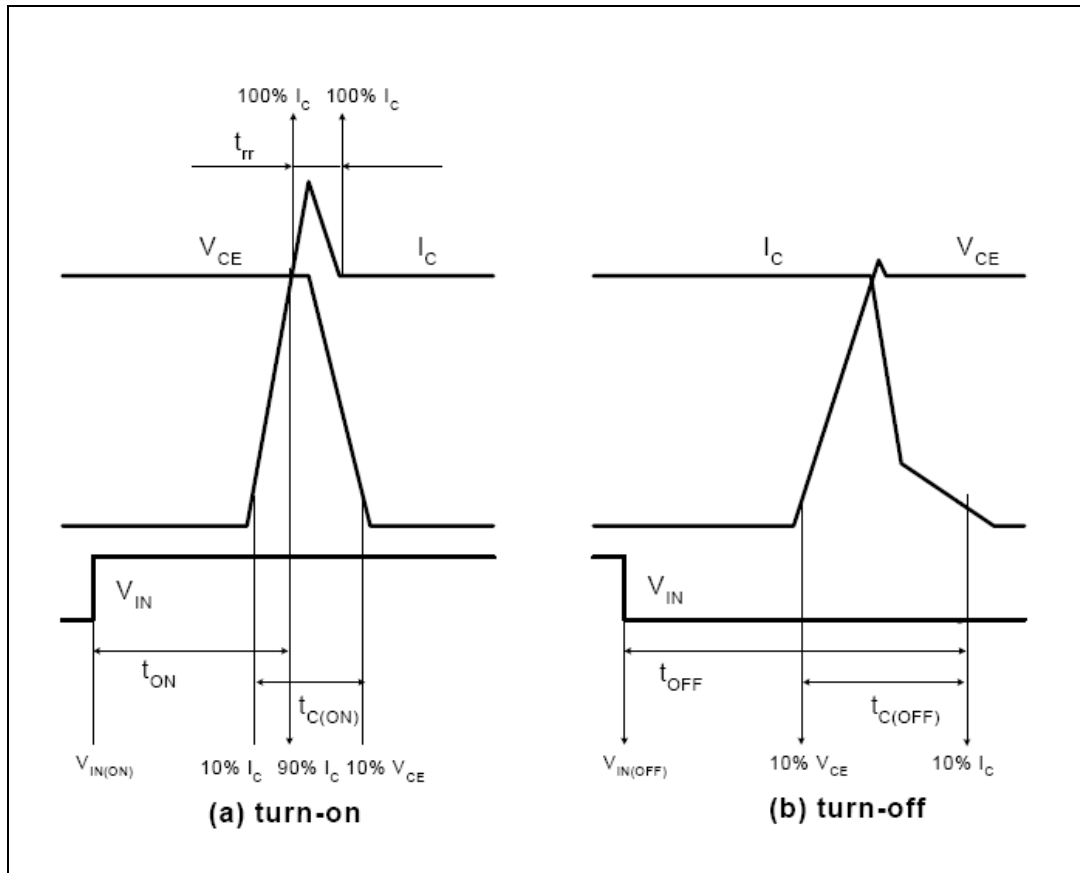
Table 7. Inverter part

Symbol	Parameter	Condition	Value			Unit
			Min.	Typ.	Max.	
$V_{CE(sat)}$	Collector-emitter saturation voltage	$V_{CC} = V_{Boot} = 15\text{ V}$, $V_I^{(1)} = 5\text{ V}$, $I_C = 7\text{ A}$	-	2.1		V
		$V_{CC} = V_{Boot} = 15\text{ V}$, $V_I^{(1)} = 5\text{ V}$, $I_C = 7\text{ A}$, $T_j = 125\text{ °C}$	-	1.8		
I_{CES}	Collector-cut off current ($V_{IN}^{(1)} = 0$)	$V_{CE} = 600\text{ V}$	-		100	μA
V_F	Diode forward voltage	($HIN = 0$, $\overline{LIN} = 1$), $I_C = 5\text{ A}$	-		2.2	V
High side inductive load						
t_{on}	Turn-on time	$V_{PN} = 300\text{ V}$, $V_{CC} = V_{boot} = 15\text{ V}$, $V_{IN}^{(1)} = 0 \leftrightarrow 5\text{ V}$, $I_C = 7\text{ A}$ (see Figure 3)	-	270		ns
$t_{c(on)}$	Crossover time (on)		-	130		
t_{off}	Turn-off time		-	320		
$t_{c(off)}$	Crossover time (off)		-	105		
t_{rr}	Reverse recovery time		-	150		μJ
E_{on}	Turn-on switching losses		-	170		
E_{off}	Turn-off switching losses		-	85		
Low side inductive load						
t_{on}	Turn-on time	$V_{PN} = 300\text{ V}$, $V_{CC} = V_{boot} = 15\text{ V}$, $V_{IN}^{(1)} = 0 \leftrightarrow 5\text{ V}$, $I_C = 5\text{ A}$ (see Figure 3)	-	240		ns
$t_{c(on)}$	Crossover time (on)		-	110		
t_{off}	Turn-off time		-	220		
$t_{c(off)}$	Crossover time (off)		-	220		
t_{rr}	Reverse recovery time		-	110		μJ
E_{on}	Turn-on switching losses		-	140		
E_{off}	Turn-off switching losses		-	90		

1. V_I : applied between HIN / LIN and GND

Note: t_{on} and t_{off} include the propagation delay time of the internal drive. $t_{c(ON)}$ and $t_{c(OFF)}$ are the switching time of IGBT itself under the internally given gate driving condition

Figure 3. Switching time definition



3.1 Control part

Table 8. Control part ($V_{CC} = 15\text{ V}$)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
Low supply voltage section						
V_{CC_hys}	V_{CC} UV hysteresis		1.2	1.5		V
V_{CC_thON}	V_{CC} UV turn ON threshold		11.5	12.0		V
V_{CC_thOFF}	V_{CC} UV turn OFF threshold		10	10.5		V
I_{qccu}	Undervoltage quiescent supply current	$V_{CC} = 10\text{ V}$ $\overline{SD} = 5\text{ V}$; $\overline{LIN} = 5\text{ V}$; and $HIN = GND$; $R_{DT} = 150\ \Omega$; $CP+=OP+=GND$; $OP-=-5\text{ V}$		350	450	μA
I_{qcc}	Quiescent current	$V_{CC} = 15\text{ V}$ $\overline{SD} = 5\text{ V}$; $\overline{LIN} = 5\text{ V}$; and $HIN = GND$; $R_{DT} = 150\ \Omega$; $CP+=OP+=GND$; $OP-=-5\text{ V}$		2	3.5	mA
V_{ref}	Internal reference voltage		0.5	0.54	0.58	mV
Bootstrapped supply voltage section						
V_{BS_hys}	V_{BS} UV hysteresis		1.2	1.5		V
V_{BS_thON}	V_{BS} UV turn ON threshold		10.6	11.5		V
V_{BS_thOFF}	V_{BS} UV turn OFF threshold		9.0	10.0		V
I_{QBSU}	Undervoltage V_{BS} quiescent current	$V_{BS} = 10\text{ V}$ $\overline{SD} = 5\text{ V}$; \overline{LIN} and $HIN = 5\text{ V}$; $R_{DT} = 150\ \Omega$; $CP+=OP+=GND$; $OP-=-5\text{ V}$		70	110	μA
I_{QBS}	V_{BS} quiescent current	$V_{BS} = 15\text{ V}$ $\overline{SD} = 5\text{ V}$; \overline{LIN} and $HIN = 5\text{ V}$; $R_{DT} = 150\ \Omega$; $CP+=OP+=GND$; $OP-=-5\text{ V}$		150	210	μA
I_{LK}	High voltage leakage current	$V_{hvg} = V_{out} = V_{boot} = 600\text{ V}$			10	μA
$R_{DS(on)}$	Bootstrap driver on resistance	LVG ON		120		Ω
Logic inputs						
V_{il}	Low logic level voltage				0.83	V
V_{ih}	High logic level voltage		2.21			V
I_{HINh}	HIN logic "1" input bias current	$HIN = 15\text{ V}$		175	260	μA
I_{HINl}	HIN logic "0" input bias current	$HIN = 0\text{ V}$			1	μA

Table 8. Control part ($V_{CC} = 15\text{ V}$) (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
I_{LINI}	\overline{LIN} logic "0" input bias current	$\overline{LIN} = 0\text{ V}$		6	40	μA
I_{LINh}	\overline{LIN} logic "1" input bias current	$\overline{LIN} = 15\text{ V}$			1	μA
I_{SDh}	\overline{SD} logic "1" input bias current	$\overline{SD} = 15\text{ V}$		30	100	μA
I_{SDl}	\overline{SD} logic "0" input bias current	$\overline{SD} = 0\text{ V}$			1	μA
Dt	Dead time	see Figure 5		320		ns

Table 9. OPAMP characteristics ($V_{CC} = 15\text{ V}$)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
V_{io}	Input offset voltage	$V_O = \text{TBD}$; $0 < V_{icm} < V_{CC} - \text{TBD}$			3	mV
I_{ib}	Input bias current ⁽¹⁾			100	200	nA
V_{icm}	Input common mode voltage range		0		$V_{CC} - \text{TBD}$	V
V_{OL}	Low level output voltage - low level	$I_{sink} = 3.5\text{ mA}$, $R_L = 2\text{ k}\Omega$		180	360	mV
V_{OH}	High level output voltage - high level	$I_{source} = 3.5\text{ mA}$, $R_L = 2\text{ k}\Omega$	13.5	14.3		V
I_o	Output short circuit current	Source, $V_{id} = \pm 1\text{ V}$; $V_o = 0\text{ V}$	16	30		mA
		Sink, $V_{id} = \pm 1$; $V_o = 0\text{ V}$	50	80		mA
SR	Slew rate	$V_i = 1 \div 4\text{ V}$; $R_L = 2\text{ k}\Omega$; $C_L = 100\text{ pF}$; unity gain	2.5	3.8		V/ μs
GBWP	Gain bandwidth product	$V_o = 7.5\text{ V}$; $R_L = 2\text{ k}\Omega$		12		MHz
A_{vd}	Large signal voltage gain			85		dB
SVR	Supply voltage rejection ratio			70		dB
CMRR	Common mode rejection ratio			70		dB

1. The direction of input current is out of the IC.

Table 10. Sense comparator characteristics ($V_{CC} = 15\text{ V}$)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
I_{io}	Input bias current	$V_{CP+} = 1\text{ V}$	-		1	μA
V_{ol}	Open drain low level output voltage	$I_{od} = -3\text{ mA}$	-		0.5	V
t_{d_comp}	Comparator delay	\overline{SD}/OD pulled to 5 V through 100 k Ω resistor	-	90	130	ns
SR	Slew rate	$C_L = 180\text{ pF}$; $R_{pu} = 5\text{ k}\Omega$	-	60		V/ μsec

Table 11. NTC thermistor

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit.
R ₂₅	Resistance	T _C = 25°C		5		kΩ
R ₁₂₅	Resistance	T _C = 125°C		300		Ω
B	B-constant	T _C = 25°C		3435		k
T	Operating temperature		-40		125	°C

Equation 1: Resistance variation vs temperature

$$R(T) = R_{25} \cdot e^{B\left(\frac{1}{T} - \frac{1}{298k}\right)}$$

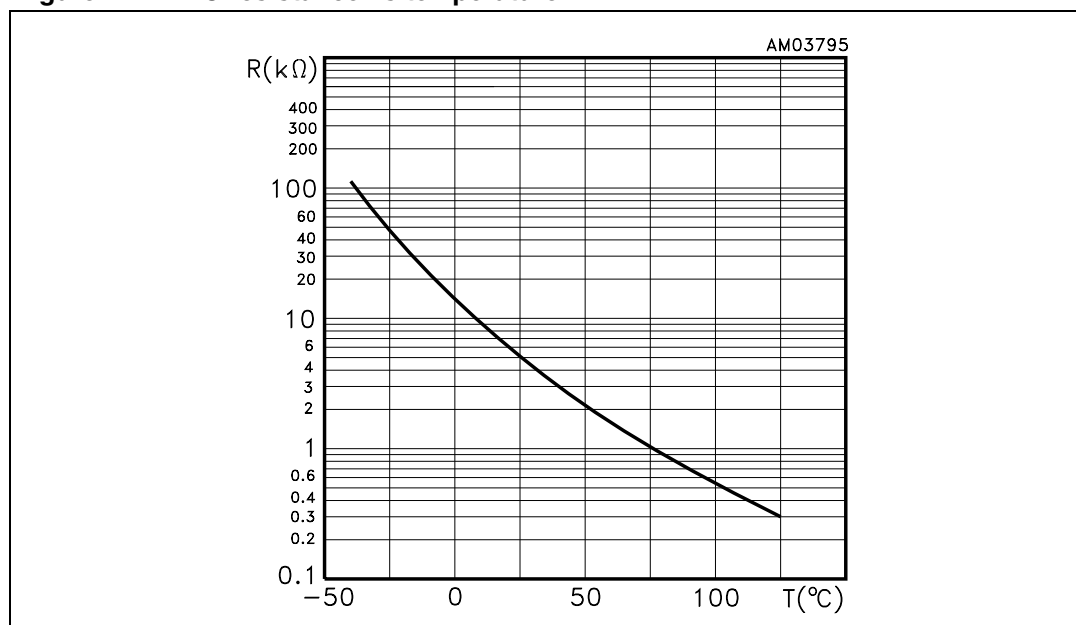
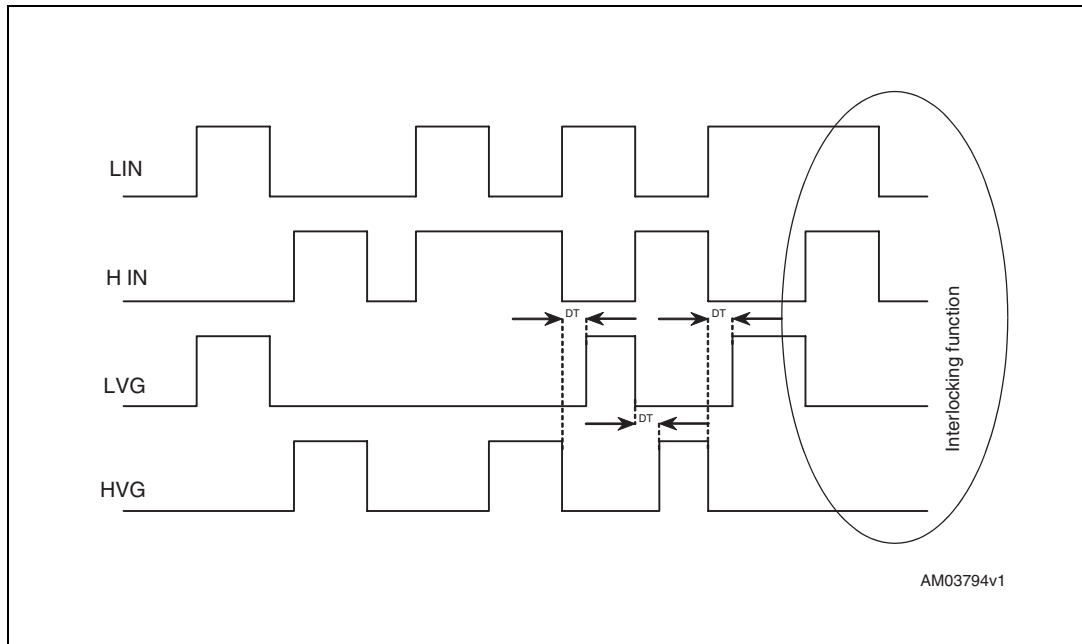
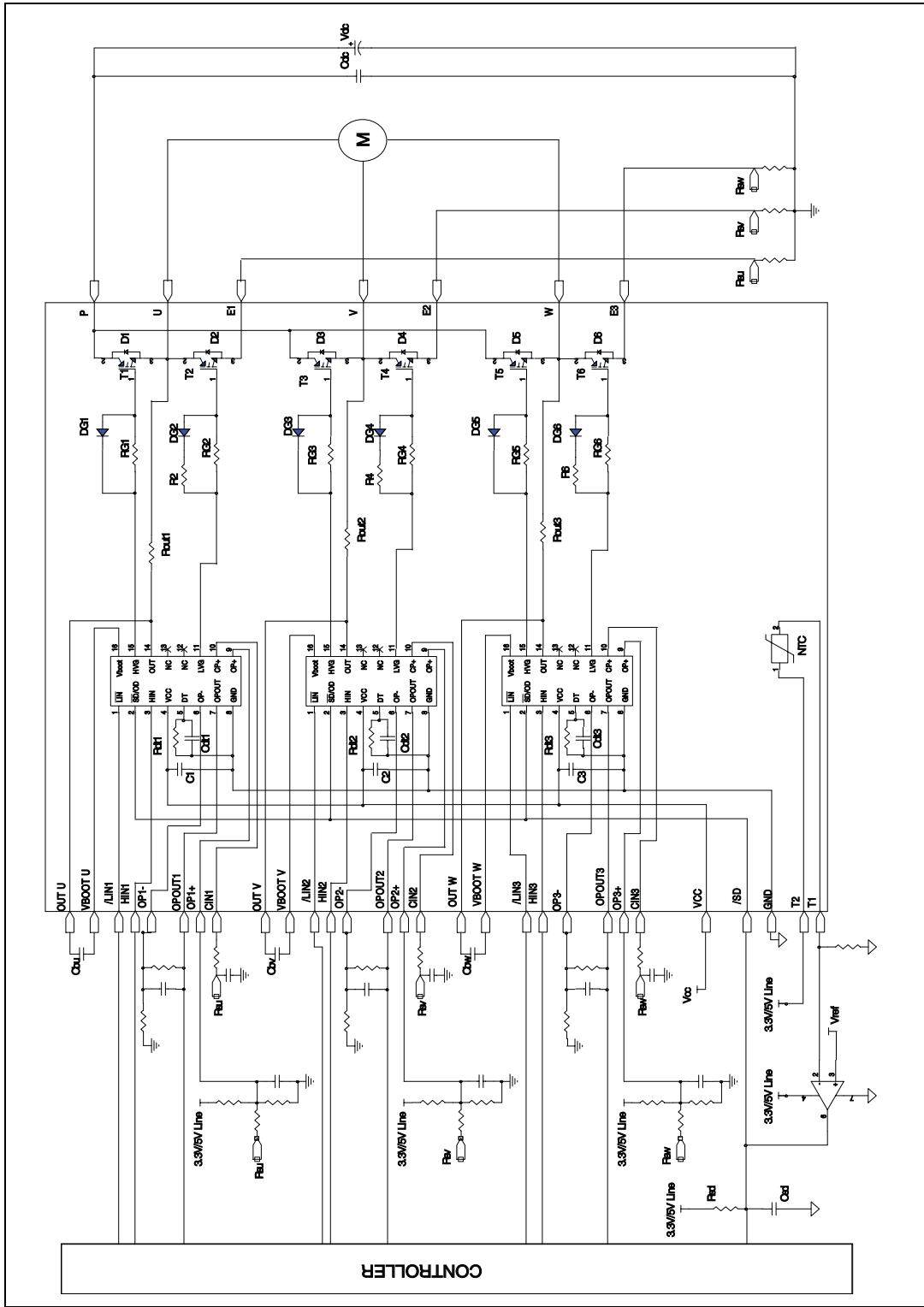
Figure 4. NTC resistance vs temperature

Figure 5. Dead time waveforms definition



4 Applications information

Figure 6. Typical IPM application circuit example



4.1 Recommendations

- To prevent the input signals oscillation, the wiring of each input should be as short as possible.
- By integrating an application specific type HVIC inside the module, direct coupling to MCU terminals without any opto-coupler is possible.
- Each capacitor should be located as nearby the pins of IPM as possible.
- Low inductance shunt resistors should be used for phase leg current sensing.
- Electrolytic bus capacitors should be mounted as close to the module bus terminals as possible. Additional high frequency ceramic capacitor mounted close to the module pins will further improve performance.

5 Package mechanical data

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

Table 12. SDIP 38L molded mechanical data

Dimensions	mm		
	Min.	Typ.	Max.
A	49.1		50.1
A1	44.1		45.1
A2	1.37		1.47
A3	1.23		2.23
B	24		25
B1	27.1		28.1
B2	28.6		29.6
B3	12.05		13.25
B4	11.25		12.45
C	5		6
C1	6.4		7.4
C2	10.41		11.41
e	1.1		1.5
e1	3.2		3.6
e2	5.8		6.2
e3	4.6		5
e4	5.6		6
e5	6.3		6.7
e6	4.5		4.9
F	0.8		1.2
F1	0.35		0.65
R1	2.3		2.7
T1	0.45		0.65

Figure 7. SDIP 38L molded drawing dimensions

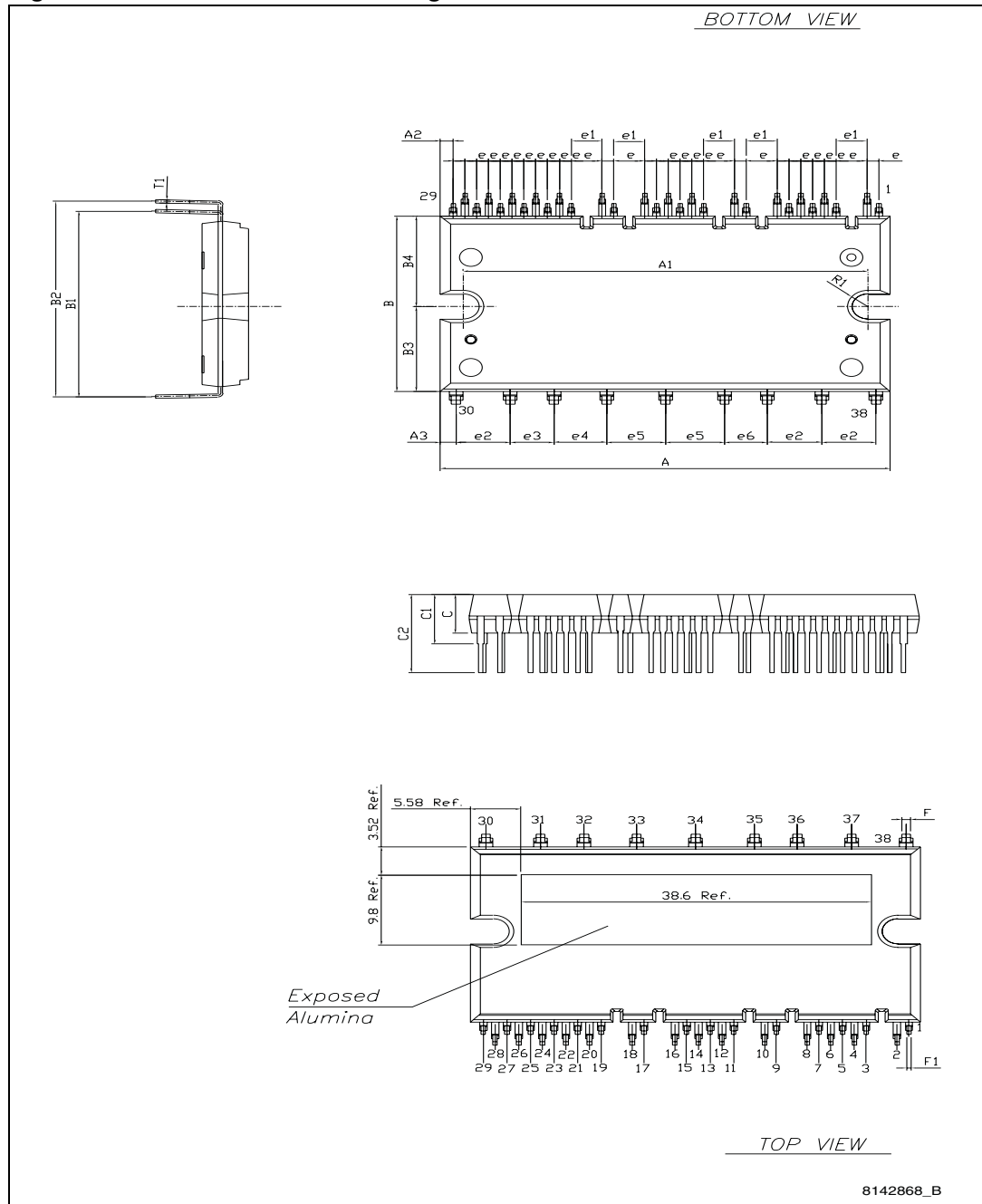


Table 13. Mechanical characteristics and ratings

Parameter	Limits			Unit
	Min.	Typ.	Max.	
Mounting torque (M3 screw)	0.59	--	0.78	N•m
Device flatness	0	--	100	μm
Weight	--	17	--	g

6 Revision history

Table 14. Document revision history

Date	Revision	Changes
16-Apr-2009	1	Initial release

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