

Section 22 Electrical Specifications

22.1 Absolute Maximum Ratings

Table 22-1 lists the absolute maximum ratings.

Table 22-1 Absolute Maximum Ratings

Item	Symbol	Rating	Unit
Supply voltage	V_{cc}	-0.3 to +7.0	V
Flash memory programming voltage	FV_{pp}	-0.3 to +13.0	V
Programming voltage	V_{pp}	-0.3 to +13.5	V
Input voltage	V_{in} Ports 7, MD ₁	-0.3 to $V_{cc} + 0.3$	V
	Port 7	V_{in}	-0.3 to $AV_{cc} + 0.3$
	MD ₁	V_{in}	F-ZTAT version: -0.3 to +13.0 Other versions: -0.3 to $V_{cc} + 0.3$
Analog supply voltage	AV_{cc}	-0.3 to +7.0	V
Analog input voltage	V_{AN}	-0.3 to $AV_{cc} + 0.3$	V
Operating temperature	$T_{op,r}$	Regular specifications: -20 to +75 Wide-range specifications: -40 to +85	°C
Storage temperature	T_{stg}	-55 to +125	°C

Note: Exceeding the absolute maximum ratings shown in table 20-1 can permanently destroy the chip.*

* FV_{pp} must not exceed 13 V and V_{pp} must not exceed 13.5 V, including peak overshoot. In the F-ZTAT version, MD₁ must not exceed 13 V, including peak overshoot.

22.2 Electrical Characteristics

22.2.1 DC Characteristics

Table 22-2 lists the DC characteristics of the 5-V version. Table 22-3 lists the DC characteristics of 4-V version. Table 22-4 lists the DC characteristics of the 3-V version. Table 22-5 gives the allowable current output values of the 5-V and 4-V versions. Table 22-6 gives the allowable current output values of the 3-V version. Bus drive characteristics common to 5 V, 4 V and 3 V versions are listed in table 22-7.

Table 22-2 DC Characteristics (5-V Version)

Conditions: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $AV_{CC} = 5.0 \text{ V} \pm 10\%^{*1}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Item		Symbol	Min	Typ	Max	Unit	Test Conditions
Schmitt trigger input voltage	P6, ₁ to P6, ₄ , \overline{IRQ}_2 to \overline{IRQ}_5 , \overline{IRQ}_7 to \overline{IRQ}_3 ,	(1) V_T	1.0	—	—	V	
		VT+	—	—	$V_{CC} \times 0.7$		
		0.4 $V_+ - VT_-$	0.4	—	—		
Input high voltage	RES, STBY, MD, ₁ , MD, ₀ , EXTAL, NMI	(2) V_{IH}	$V_{CC} - 0.7$	—	$V_{CC} + 0.3$	V	
	SCL, SDA		$V_{CC} \times 0.7$	—	$V_{CC} + 0.3$		
	P7, ₁ to P7, ₀		2.0	—	$AV_{CC} + 0.3$		
	All input pins other than (1) and (2) above		2.0	—	$V_{CC} + 0.3$		
Input low voltage	RES, STBY, MD, ₁ , MD, ₀	(3) V_{IL}	-0.3	—	0.5	V	
	SCL, SDA		-0.3	—	1.0		
	All input pins other than (1) and (3) above		-0.3	—	0.8		
Output high voltage	All output pins ⁶	V_{OH}	$V_{CC} - 0.5$	—	—	V	$I_{OH} = -200 \mu\text{A}$
			3.5	—	—	V	$I_{OH} = -1.0\text{m}$

Table 22-2 DC Characteristics (5-V Version) (cont)

Conditions: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $AV_{CC} = 5.0 \text{ V} \pm 10\%^{*1}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Item		Symbol	Min	Typ	Max	Unit	Test Conditions
Output low voltage	All output pins ^{*6}	V_{OL}	—	—	0.4	V	$I_{OL} = 1.6 \text{ mA}$
	P1, to P1 _o , P2, to P2 _o		—	—	1.0		$I_{OL} = 10.0 \text{ mA}$
Input leakage current	RES, STBY	$ I_{in} $	—	—	10.0	μA	$V_{in} = 0.5 \text{ V}$ to $V_{cc} - 0.5 \text{ V}$
	NMI, MD ₁ , MD ₀		—	—	1.0		
	P7, to P7 _o		—	—	1.0		$V_{in} = 0.5 \text{ V}$ to $AV_{cc} - 0.5 \text{ V}$
Leakage current in three-state (off state)	Ports 1 to 6, 8, current in 9,	$ I_{TSI} $	—	—	1.0	μA	$V_{in} = 0.5 \text{ V}$ to $V_{cc} - 0.5 \text{ V}$
Input pull-up MOS current	Ports 1 to 3	$-I_p$	30	—	250	μA	$V_{in} = 0 \text{ V}$
	Ports 6		60	—	500		
Input capacitance	STBY (F-ZTAT (4) version)	C_{in}	—	—	120	pF	$V_{in} = 0 \text{ V}$, $f = 1 \text{ MHz}$, $T_a = 25^\circ\text{C}$
	RES, STBY (except F-ZTAT version)		—	—	60		
	NMI, MD ₁		—	—	50		
	P9 ₁ , P8 ₀		—	—	20		
	All input pins other than (4)		—	—	15		
Current dissipation ^{*2}	Normal operation	I_{cc}	—	27	45	mA	$f = 12 \text{ MHz}$
	Sleep mode		—	36	60		$f = 16 \text{ MHz}$
			—	18	30		$f = 12 \text{ MHz}$
			—	24	40		$f = 16 \text{ MHz}$
	Standby modes ^{*3}		—	0.01	5.0	μA	$T_a \leq 50^\circ\text{C}$
			—	—	20.0		$50^\circ\text{C} < T_a$

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Table 22-2 DC Characteristics (5-V Version) (cont)

Conditions: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $AV_{CC} = 5.0 \text{ V} \pm 10\%^{*1}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Item	Symbol	Min	Typ	Max	Unit	Test Conditions
Analog supply current	During A/D conversion	AI_{cc}	—	2.0	5.0	mA
	During A/D and D/A conversion		—	2.0	5.0	
	A/D and D/A conversion idle		—	0.01	5.0	μA $AV_{cc} = 2.0 \text{ V to } 5.5 \text{ V}$
Analog supply voltage ^{**}	AV_{cc}	4.5	—	5.5	V	During operation
		2.0	—	5.5		While idle or when not in use
RAM standby voltage	V_{RAM}	2.0	—	—	V	

- Notes:
1. Even when the A/D and D/A converters are not used, connect AV_{cc} to power supply V_{cc} and keep the applied voltage between 2.0 V and 5.5 V.
 2. Current dissipation values assume that $V_{IH\ min} = V_{cc} - 0.5 \text{ V}$, $V_{IL\ max} = 0.5 \text{ V}$, all output pins are in the no-load state, and all input pull-up transistors are off.
 3. For these values it is assumed that $V_{RAM} \cdot V_{cc} < 4.5 \text{ V}$ and $V_{IH\ min} = V_{cc} \times 0.9$, $V_{IL\ max} = 0.3 \text{ V}$.
 4. P6₇ to P6₀ include supporting module inputs multiplexed with them.
 5. \overline{TRQ}_2 includes \overline{ADTRG} multiplexed with it.
 6. Applies when IICE = 0. The output low level is determined separately when the bus drive function is selected.

Table 22-3 DC Characteristics (4-V Version)

Conditions: $V_{CC} = 4.0$ V to 5.5 V, $AV_{CC} = 4.0$ V to 5.5 V, $V_{SS} = AV_{SS} = 0$ V, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Item		Symbol	Min	Typ	Max	Unit	Test Conditions
Schmitt trigger input voltage	P ₆ , to P _{6_o} ⁴ , (1) \overline{TRQ}_2 to \overline{TRQ}_5 ⁵ , \overline{TRQ}_7 to \overline{TRQ}_3	V_T^-	1.0	—	—	V	$V_{CC} = 4.5$ V to 5.5 V
		V_T^+	—	—	$V_{CC} \times 0.7$		
		$V_T^+ - V_T^-$	0.4	—	—		
		V_T^-	0.8	—	—		$V_{CC} = 4.0$ V to 4.5 V
		V_T^+	—	—	$V_{CC} \times 0.7$		
		$V_T^+ - V_T^-$	0.3	—	—		
Input high voltage	RES, STBY, MD ₁ , MD ₀ , EXTAL, NMI	V_{IH}	$V_{CC} - 0.7$	—	$V_{CC} + 0.3$	V	
	SCL, SDA		$V_{CC} \times 0.7$	—	$V_{CC} + 0.3$		
	P ₇ , to P _{7_o}		2.0	—	$AV_{CC} + 0.3$		
	All input pins other than (1) and (2) above		2.0	—	$V_{CC} + 0.3$		
Input low voltage	RES, STBY, MD ₁ , MD ₀	V_{IL}	-0.3	—	0.5	V	
	SCL, SDA		-0.3	—	1.0		$V_{CC} = 4.5$ V to 5.5 V
			-0.3	—	0.8		$V_{CC} = 4.0$ V to 4.5 V
	All input pins other than (1) and (3) above		-0.3	—	0.8		$V_{CC} = 4.5$ V to 5.5 V
			-0.3	—	0.6		$V_{CC} = 4.0$ V to 4.5 V
Output high voltage	All output pins	V_{OH}	$V_{CC} - 0.5$	—	—	V	$I_{OH} = -200$ μ A
			3.5	—	—		$I_{OH} = -1.0$ mA, $V_{CC} = 4.5$ V to

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Item	Symbol	Min	Typ	Max	Unit	Test Conditions	
		2.8	—	—	V	5.5 V	
						$I_{OH} = -1.0$ mA, $V_{cc} = 4.0$ V to 4.5 V	
Output low voltage	All output pins	V_{OL}	—	—	0.4	V	$I_{OL} = 1.6$ mA
	P1 ₇ to P1 ₀ , P2 ₇ to P2 ₀		—	—	1.0		$I_{OL} = 10.0$ mA
Input leakage current	RES, STBY	$ I_{in} $	—	—	10.0	μA	$V_{in} = 0.5$ V to $V_{cc} - 0.5$ V
	NMI, MD ₁ , MD ₀		—	—	1.0		
	P7 ₇ to P7 ₀		—	—	1.0		$V_{in} = 0.5$ V to $V_{cc} - 0.5$ V
Leakage current in three-state(off state)	Ports 1 to 6, 8, 9,	$ I_{tsl} $	—	—	1.0	μA	$V_{in} = 0.5$ V to $V_{cc} - 0.5$ V,
Input pull-up MOS current	Ports 1 to 3	$-I_p$	30	—	250	μA	$V_{in} = 0$ V, $V_{CC} = 4.5$ V to 5.5 V
	Ports 6		60	—	500		
	Ports 1 to 3		20	—	200		$V_{in} = 0$ V, $V_{CC} = 4.0$ V to 4.5 V
	Ports 6		40	—	400		
Input capacitance	STBY (F-ZTAT (4) version)	C_{in}	—	—	120	pF	$V_{in} = 0$ V, $f = 1$ MHz, $T_a = 25^\circ C$
	RES, STBY (except F-ZTAT version)		—	—	60		
	NMI, MD ₁ ,		—	—	50		
	P9 ₇ , P8 ₆		—	—	20		
	All input pins other than (4) above		—	—	15		

Item		Symbol	Min	Typ	Max	Unit	Test Conditions
Current dissipation*2	Normal operation	I _{cc}	—	27	45	mA	f = 12 MHz
			—	36	60		f = 16 MHz, V _{cc} = 4.5 V to 5.5 V
	Sleep mode		—	18	30		f = 12 MHz
			—	24	40		f = 16 MHz, V _{cc} = 4.5 V to 5.5 V
	Standby modes ³		—	0.01	5.0	µA	T _a ≤ 50°C
			—	—	20.0		50°C < T _a
Analog supply current	During A/D conversion	AI _{cc}	—	2.0	5.0	mA	
	During A/D and D/A conversion		—	2.0	5.0		
	A/D and D/A conversion idle		—	0.01	5.0	µA	A _{V_{cc}} = 2.0 V to 5.5 V
Analog supply voltage ¹		A _{V_{cc}}	4.0	—	5.5	V	During operation
			2.0	—	5.5		While idle or when not in use
RAM standby voltage		V _{RAM}	2.0	—	—	V	

- Notes:
- Even when the A/D and D/A converters are not used, connect A_{V_{cc}} to power supply V_{cc} and keep the applied voltage between 2.0 V and 5.5 V.
 - Current dissipation values assume that V_{IH min} = V_{cc} - 0.5 V, V_{IL max} = 0.5 V, all output pins are in the no-load state, and all input pull-up transistors are off.
 - For these values it is assumed that V_{RAM} • V_{cc} < 4.0 V and V_{IH min} = V_{cc} × 0.9, V_{IL max} = 0.3 V.
 - P6_o to P6_o include supporting module inputs multiplexed with them.
 - IRQ₂ includes ADTRG multiplexed with it.
 - Applies when IICE = 0. The output low level is determined separately when the bus drive function is selected.

Table 22-4 DC Characteristics (3-V Version)

Conditions: $V_{CC} = 2.7 \text{ V to } 5.5 \text{ V}$, $AV_{CC} = 2.7 \text{ V to } 5.5 \text{ V}^*$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$

Item		Symbol	Min	Typ	Max	Unit	Test Conditions
Schmitt trigger input voltage	P6 _z to P6 _o [*] , IRQ ₂ to IRQ0 [*] 5, IRQ _z to IRQ _o	(1) V_T^-	$V_{CC} \times 0.15$	—	—	V	
		V_T^+	—	—	$V_{CC} \times 0.7$		
		$V_T^+ - V_T^-$	0.2	—	—		
Input high voltage	RES, STBY, MD ₁ , MD _o , EXTAL, NMI	(2) V_H	$V_{CC} \times 0.9$	—	$V_{CC} + 0.3 \text{ V}$		
	SCL, SDA		$V_{CC} \times 0.7$	—	$V_{CC} + 0.3$		
	P7 _z to P7 _o		$V_{CC} \times 0.7$	—	$AV_{CC} + 0.3$		
	All input pins other than (1) and (2) above		$V_{CC} \times 0.7$	—	$V_{CC} + 0.3$		
Input low voltage [*]	RES, STBY, MD ₁ , MD _o	(3) V_L	-0.3	—	$V_{CC} \times 0.1 \text{ V}$		
	SCL, SDA		-0.3	—	$V_{CC} \times 0.15$		
	All input pins other than (1) and (3) above		-0.3	—	$V_{CC} \times 0.15$		
Output high voltage	All output pins [*]	V_{OH}	$V_{CC} - 0.5$	—	—	V	$I_{OH} = -200 \mu\text{A}$
			$V_{CC} - 1.0$	—	—		$I_{OH} = -1 \text{ mA}$
Output low voltage	All output pins [*]	V_{OL}	—	—	0.4	V	$I_{OL} = 0.8 \text{ mA}$
	P17 to P10, P2 _z to P2 _o		—	—	0.4		$I_{OL} = 1.6 \text{ mA}$
Input leakage	RES, STBY	$ I_{in} $	—	—	10.0	μA	$V_{in} = 0.5 \text{ V to } V_{CC} - 0.5 \text{ V}$

Item	Symbol	Min	Typ	Max	Unit	Test Conditions	
current		—	—	1.0			
<u>NMI, MD₁, MD₀</u>		—	—	1.0			
<u>P7₇ to P7₀</u>		—	—	1.0		V _{in} = 0.5 V to AV _{cc} - 0.5 V	
Leakage current in three-state(off state)	Ports 1 to 6, 8, 9	I _{TSI}	—	—	1.0	μA	V _{in} = 0.5 V to V _{cc} - 0.5 V,
Input pull-up MOS current	Ports 1 to 3	-I _p	3	—	120	μA	V _{in} = 0 V, V _{cc} = 2.7 V to 3.6 V
	6		30	—	250		
Input capacitance	STBY (F-ZTAT (4) version)	C _{in}	—	—	120	pF	V _{in} = 0 V, f = 1MHz, Ta = 25°C
	RES, STBY (except F-ZTAT version)		—	—	60		
	<u>NMI, MD₁,</u>		—	—	50		
	<u>P9₇, P8₆</u>		—	—	20		
	All input pins other than (4) above		—	—	15		
Current dissipation ²	Normal operation	I _{cc}	—	7	—	mA	f = 6 MHz, V _{cc} = 2.7 V to 3.6 V
			—	12	22		f = 10 MHz, V _{cc} = 2.7 V to 3.6 V
			—	25	—		f = 10 MHz, V _{cc} = 4.0 V to 5.5 V
	Sleep mode		—	5	—		f = 6 MHz, V _{cc} = 2.7 V to 3.6 V
			—	9	16		f = 10 MHz, V _{cc} = 2.7 V to 3.6 V

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Item	Symbol	Min	Typ	Max	Unit	Test Conditions
		—	18	—		$f = 10 \text{ MHz}$, $V_{cc} = 4.0 \text{ V to}$ 5.5 V
Standby modes ³		—	0.01	5.0	μA	$T_a \leq 50^\circ\text{C}$
Analog supply current	During A/D conversion	I_{Icc}	—	2.0	5.0	mA
	During A/D and D/A conversion		—	2.0	5.0	
	A/D and D/A conversion idle		—	0.01	5.0	μA $AV_{cc} = 2.0 \text{ V to } 5.5 \text{ V}$
Analog supply voltage ¹	AV_{cc}	2.7	—	5.5	V	During operation
		2.0	—	5.5		While idle or when not in use
RAM standby voltage	V_{RAM}	2.0	—	—	V	

- Notes:
1. Even when the A/D and D/A converters are not used, connect AV_{cc} to power supply V_{cc} and keep the applied voltage between 2.0 V and 5.5 V.
 2. Current dissipation values assume that $V_{IH\min} = V_{cc} - 0.5 \text{ V}$, $V_{IL\max} = 0.5 \text{ V}$, all output pins are in the no-load state, and all input pull-up transistors are off.
 3. For these values it is assumed that $V_{RAM} \cdot V_{cc} < 2.7 \text{ V}$ and $V_{IH\min} = V_{cc} \times 0.9$, $V_{IL\max} = 0.3 \text{ V}$.
 4. P6_o to P6_o include supporting module inputs multiplexed with them.
 5. IRQ₂ includes ADTRG multiplexed with it.
 6. Applies when IICE = 0. The output low level is determined separately when the bus drive function is selected.

Table 22-5 Allowable Output Current Values (5-V and 4-V Versions)

Conditions: $V_{CC} = 4.0$ V to 5.5 V, $AV_{CC} = 4.0$ V to 5.5 V, $V_{SS} = AV_{SS} = 0$ V, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Item		Symbol	Min	Typ	Max	Unit
Allowable output low current (per pin)	SCL, SDA (bus drive selection)	I_α	—	—	20	mA
	Ports 1 and 2		—	—	10	
	Other output pins		—	—	2	
Allowable output low (total)	Ports 1 and 2, total	ΣI_α	—	—	80	mA
	Total of all output		—	—	120	
Allowable output high current (per pin)	All output pins	$-I_{OH}$	—	—	2	mA
Allowable output high current (total)	Total of all output	$\Sigma -I_{OH}$	—	—	40	mA

Table 22-6 Allowable Output Current Values (3-V Version)

Conditions: $V_{CC} = 2.7$ to 5.5 V, $AV_{CC} = 2.7$ V to 5.5 V, $V_{SS} = AV_{SS} = 0$ V, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$

Item		Symbol	Min	Typ	Max	Unit
Allowable output low current (per pin)	SCL, SDA (bus drive selection)	I_α	—	—	10	mA
	Ports 1 and 2		—	—	2	
	Other output pins		—	—	1	
Allowable output low (total)	Ports 1 and 2, total	ΣI_α	—	—	40	mA
	Total of all output		—	—	60	
Allowable output high current (per pin)	All output pins	$-I_{OH}$	—	—	2	mA
Allowable output high current (total)	Total of all output	$\Sigma -I_{OH}$	—	—	30	mA

Note: To avoid degrading the reliability of the chip, be careful not to exceed the output current values in tables 22-5 and 22-6. In particular, when driving a darlington transistor pair or LED directly, be sure to insert a current-limiting resistor in the output path. See figures 22-1 and 22-2.

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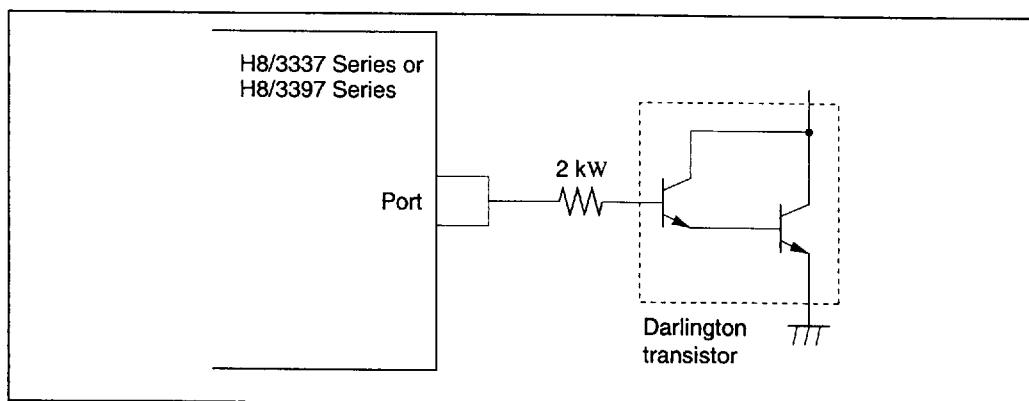


Figure 22-1 Example of Circuit for Driving a Darlington Transistor (5-V Version)

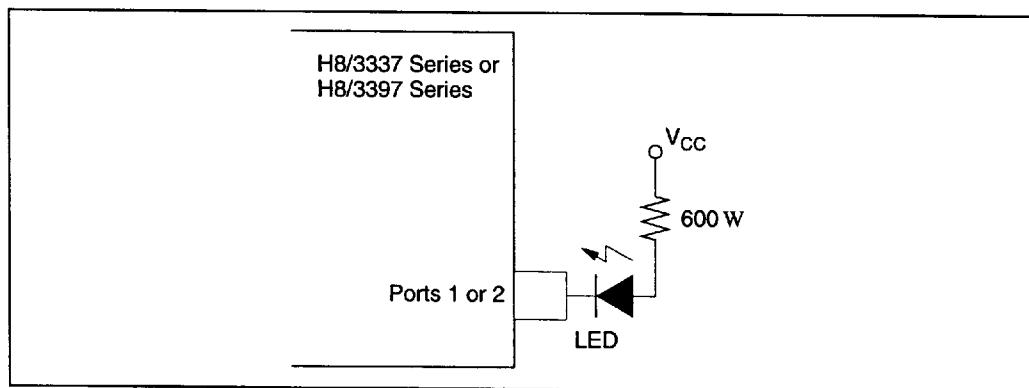


Figure 22-2 Example of Circuit for Driving an LED (5-V Version)

Table 22-7 Bus Drive Characteristics

Conditions: V_{SS} = 0 V, Ta = -20 to 75°C

Item	Symbol	Min	Typ	Max	Unit	Test Condition
Output low voltage (bus drive selection)	V _{OL}	—	—	0.5	V	V _{CC} = 5 V ±10% I _{OL} = 16 mA
		—	—	0.5		V _{CC} = 2.7 V to 5.5 V I _{OL} = 8 mA

22.2.2 AC Characteristics

The AC characteristics are listed in following tables. Bus timing parameters are given in table 22-8, control signal timing parameters in table 22-9, timing parameters of the on-chip supporting modules in table 22-10, I²C bus timing parameters in table 22-11, and external clock output delay timing parameters in table 22-12.

Table 22-8 Bus Timing

Condition A: V_{CC} = 5.0 V ±10%, V_{SS} = 0 V, φ = 2.0 MHz to maximum operating frequency, Ta = -20°C to +75°C (regular specifications), Ta = -40°C to +85°C (wide-range specifications)

Condition B: V_{CC} = 4.0 V to 5.5 V, V_{SS} = 0 V, φ = 2.0 MHz to maximum operating frequency, Ta = -20°C to +75°C (regular specifications), Ta = -40°C to +85°C (wide-range specifications)

Condition C: V_{CC} = 2.7 V to 5.5 V, V_{SS} = 0 V, φ = 2.0 MHz to maximum operating frequency, Ta = -20°C to +75°C

Item	Symbol	Condition C		Condition B		Condition A		Unit	Conditions
		10 MHz	12 MHz	16 MHz	Min	Max	Min	Max	
Clock cycle time	t _{bc}	100	500	83.3	500	62.5	500	ns	Fig. 22-4
Clock pulse width low	t _L	30	—	30	—	20	—	ns	
Clock pulse width high	t _H	30	—	30	—	20	—	ns	
Clock rise time	t _{cr}	—	20	—	10	—	10	ns	
Clock fall time	t _{cf}	—	20	—	10	—	10	ns	
Address delay time	t _{AD}	—	50	—	35	—	30	ns	
Address hold time	t _{AH}	20	—	15	—	10	—	ns	
Address strobe delay time	t _{ASD}	—	50	—	35	—	30	ns	
Write strobe delay time	t _{WSO}	—	50	—	35	—	30	ns	
Strobe delay time	t _{SD}	—	50	—	35	—	30	ns	
Write strobe pulse width ¹	t _{WSW}	110	—	90	—	60	—	ns	
Address setup time 1 ¹	t _{AS1}	15	—	10	—	10	—	ns	
Address setup time 2 ¹	t _{AS2}	65	—	50	—	40	—	ns	
Read data setup time	t _{RDS}	35	—	20	—	20	—	ns	
Read data hold time ¹	t _{RDH}	0	—	0	—	0	—	ns	
Read data access time ¹	t _{ACC}	—	170	—	160	—	110	ns	
Write data delay time	t _{WDD}	—	80/75 ²	—	65/60 ²	—	60	ns	
Write data setup time	t _{WOS}	0/5 ²	—	0/5 ²	—	0/5 ²	—	ns	
Write data hold time	t _{WDH}	20	—	20	—	20	—	ns	
Wait setup time	t _{WTS}	40	—	35	—	30	—	ns	Fig. 22-5
Wait hold time	t _{WTH}	10	—	10	—	10	—	ns	

Note: *1 Values at maximum operating frequency

*2 H8/3337YF-ZTAT version/other products

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Table 22-9 Control Signal Timing

- Condition A: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)
- Condition B: $V_{CC} = 4.0 \text{ V}$ to 5.5 V , $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)
- Condition C: $V_{CC} = 2.7 \text{ V}$ to 5.5 V , $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$

Item	Symbol	Condition C		Condition B		Condition A		Test Conditions
		10 MHz	12 MHz	15 MHz	16 MHz	Min	Max	
RES setup time	t_{RESS}	300	—	200	—	200	—	ns Fig. 22-6
RES pulse width	t_{RESW}	10	—	10	—	10	—	t_{osc}
NMI setup time (NMI, IRQ ₀ to IRQ ₇)	t_{NMIS}	300	—	150	—	150	—	ns Fig. 22-7
NMI hold time (NMI, IRQ ₀ to IRQ ₇)	t_{NMIH}	10	—	10	—	10	—	ns
Interrupt pulse width for recovery from software standby mode (NMI, IRQ ₀ to IRQ ₂ , IRQ ₆)	t_{NMIW}	300	—	200	—	200	—	ns
Crystal oscillator settling time (reset)	t_{osc1}	20	—	20	—	20	—	ms Fig. 22-8
Crystal oscillator settling time (software standby)	t_{osc2}	8	—	8	—	8	—	ms Fig. 22-9

- Measurement Conditions for AC Characteristics

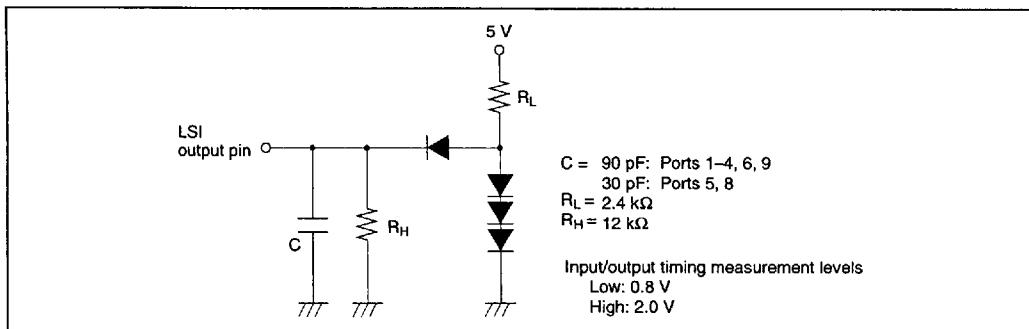


Figure 22-3 Output Load Circuit

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Table 22-10 Timing Conditions of On-Chip Supporting Modules

- Condition A: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency,
 $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)
- Condition B: $V_{CC} = 4.0 \text{ V}$ to 5.5 V , $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency,
 $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)
- Condition C: $V_{CC} = 2.7 \text{ V}$ to 5.5 V , $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency,
 $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$

Item	Symbol	Condition C		Condition B		Condition A		Test Unit	Conditions
		10 MHz	12 MHz	12 MHz	16 MHz	100	100		
FRT	Timer output delay time t_{TOD}	—	150	—	100	—	100	ns	Fig. 22-10
	Timer input setup time t_{TIS}	80	—	50	—	50	—	ns	
	Timer clock input setup time t_{TCIS}	80	—	50	—	50	—	ns	
	Timer clock pulse width t_{TCWH} t_{TCWL}	1.5	—	1.5	—	1.5	—	t_{osc}	
TMR	Timer output delay time t_{TMOO}	—	150	—	100	—	100	ns	Fig. 22-12
	Timer reset input setup time t_{TMRS}	80	—	50	—	50	—	ns	
	Timer clock input setup time t_{TMCS}	80	—	50	—	50	—	ns	
	Timer clock pulse width t_{TMCHW} (single edge)	1.5	—	1.5	—	1.5	—	t_{osc}	
	Timer clock pulse width t_{TMCLW} (both edges)	2.5	—	2.5	—	2.5	—	t_{osc}	
PWM	Timer output delay time t_{PWOO}	—	150	—	100	—	100	ns	Fig. 22-15
SCI	Input clock cycle (Async)	t_{Sosc}	4	—	4	—	4	—	Fig. 22-16
	(Sync)	t_{Sosc}	6	—	6	—	6	—	
	Transmit data delay time (Sync)	t_{TXD}	—	200	—	100	—	100	
	Receive data setup time (Sync)	t_{RXS}	150	—	100	—	100	—	
	Receive data hold time (Sync)	t_{RKH}	150	—	100	—	100	—	
	Input clock pulse width t_{SCKW}	0.4	0.6	0.4	0.6	0.4	0.6	t_{osc}	
Ports	Output data delay time t_{PWD}	—	150	—	100	—	100	ns	Fig. 22-18
	Input data setup time t_{PRS}	80	—	50	—	50	—	ns	
	Input data hold time t_{PRH}	80	—	50	—	50	—	ns	

Table 22-10 Timing Conditions of On-Chip Supporting Modules (cont)

Condition A: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Condition B: $V_{CC} = 4.0 \text{ V}$ to 5.5 V , $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Condition C: $V_{CC} = 2.7 \text{ V}$ to 5.5 V , $V_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$

Item	Symbol	Condition C		Condition B		Condition A		Unit	Conditions		
		10 MHz		12 MHz		16 MHz					
		Min	Max	Min	Max	Min	Max				
HIF read cycle	t_{HAR}	10	—	10	—	10	—	ns	Fig. 22-19		
	t_{HRA}	10	—	10	—	10	—	ns			
	t_{HWPW}	220	—	120	—	120	—	ns			
	t_{HRD}	—	200	—	100	—	100	ns			
	t_{HRF}	0	40	0	25	0	25	ns			
	t_{HIRQ}	—	200	—	120	—	120	ns			
HIF write cycle	t_{HAW}	10	—	10	—	10	—	ns	Fig. 22-20		
	t_{HWA}	10	—	10	—	10	—	ns			
	t_{HWPW}	100	—	60	—	60	—	ns			
HDB High-speed setup time	t_{HWD}	50	—	30	—	30	—	ns			
	GATE A_{20} not used										
	High-speed GATE A_{20} used	85	—	55	—	45	—				
	t_{HWD}	25	—	15	—	15	—	ns			
	t_{HGA}	—	180	—	90	—	90	ns			

Table 22-11 I²C Bus TimingConditions: V_{CC} = 2.7 V to 5.5 V, V_{SS} = 0 V, Ta = -20°C to +75°C

Rating							
Item	Symbol	Min	Typ	Max	Unit	Test Condition	Note
SCL clock cycle time	t _{SCL}	12t _{cyc}	—	—	ns		Figure 22-21
SCL clock high pulse width	t _{SCLH}	3t _{cyc}	—	—	ns		
SCL clock low pulse width	t _{SCLL}	5t _{cyc}	—	—	ns		
SCL, SDA rise time	t _{sr}	—	—	1000	ns	Normal mode 100 kbit/s (max)	
		20 + 0.1C _b	—	300		High-speed mode 400 kbit/s (max)	
SCL, SDA fall time	t _{sf}	—	—	300	ns	Normal mode 100 kbit/s (max)	
		20 + 0.1C _b	—	300		High-speed mode 400 kbit/s (max)	
SDA bus free time	t _{BUF}	7t _{cyc} - 300	—	—	ns		
SCL start condition hold time	t _{STAH}	3t _{cyc}	—	—	ns		
SCL resend start condition hold time	t _{STAS}	3t _{cyc}	—	—	ns		
SDA stop condition setup time	t _{STOS}	3t _{cyc}	—	—	ns		
SDA data setup time	t _{SDAS}	1t _{cyc} + 10	—	—	ns		
SDA data hold time	t _{SDAH}	0	—	—	ns		
SDA load capacitance	C _b	—	—	400	pF		

Table 22-12 External clock output delay Timing

Conditions: $V_{CC} = 2.7 \text{ V to } 5.5 \text{ V}$, $AV_{CC} = 2.7 \text{ V to } 5.5 \text{ V}$,
 $V_{SS} = AV_{SS} = 0 \text{ V}$, $T_a = -40^\circ\text{C to } +85^\circ\text{C}$

Item	Symbol	Min	Max	Unit	Notes
External clock output delay time	t_{DEXT}	500	—	μs	fig-22-22

Note: * t_{DEXT} includes to \overline{RES} pulse width t_{RESW} (10 t_{cyc}).

22.2.3 A/D Converter Characteristics

Table 22-13 lists the characteristics of the on-chip A/D converter.

Table 22-13 A/D Converter Characteristics

Condition A: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $AV_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C to } +75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C to } +85^\circ\text{C}$ (wide-range specifications)

Condition B: $V_{CC} = 4.0 \text{ V to } 5.5 \text{ V}$, $AV_{CC} = 4.0 \text{ V to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C to } +75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C to } +85^\circ\text{C}$ (wide-range specifications)

Condition C: $V_{CC} = 2.7 \text{ V to } 5.5 \text{ V}$, $AV_{CC} = 2.7 \text{ V to } 5.5 \text{ V}$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C to } +75^\circ\text{C}$

Item	Condition C			Condition B			Condition A			Unit
	10 MHz	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Resolution	10	10	10	10	10	10	10	10	10	Bits
Conversion (single mode)*	—	—	13.4	—	—	11.2	—	—	8.4	μs
Analog input capacitance	—	—	20	—	—	20	—	—	20	pF
Allowable signal source impedance	—	—	5	—	—	10	—	—	10	k Ω
Nonlinearity error	—	—	± 6.0	—	—	± 3.0	—	—	± 3.0	LSB
Offset error	—	—	± 4.0	—	—	± 3.5	—	—	± 3.5	LSB
Full-scale error	—	—	± 4.0	—	—	± 3.5	—	—	± 3.5	LSB
Quantizing error	—	—	± 0.5	—	—	± 0.5	—	—	± 0.5	LSB
Absolute accuracy	—	—	± 8.0	—	—	± 4.0	—	—	± 4.0	LSB

Note: * Values at maximum operating frequency

22.2.4 D/A Converter Characteristics (H8/3337 Series Only)

Table 22-14 lists the characteristics of the on-chip D/A converter.

Table 22-14 D/A Converter Characteristics

Condition A: $V_{CC} = 5.0 \text{ V} \pm 10\%$, $AV_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = AV_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Condition B: $V_{CC} = 4.0 \text{ V}$ to 5.5 V , $AV_{CC} = 4.0 \text{ V}$ to 5.5 V , $V_{SS} = AV_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$ (regular specifications), $T_a = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (wide-range specifications)

Condition C: $V_{CC} = 2.7 \text{ V}$ to 5.5 V , $AV_{CC} = 2.7 \text{ V}$ to 5.5 V , $V_{SS} = AV_{SS} = 0 \text{ V}$, $\phi = 2.0 \text{ MHz}$ to maximum operating frequency, $T_a = -20^\circ\text{C}$ to $+75^\circ\text{C}$

Item	Condition C			Condition B			Condition A			Test Conditions
	10 MHz	12 MHz	16 MHz	Min	Typ	Max	Min	Typ	Max	
Resolution	8	8	8	8	8	8	8	8	8	Bits
Conversion time — (settling time)	—	10.0	—	—	10.0	—	—	10.0	μs	30 pF load capacitance
Absolute accuracy	—	±2.0	±3.0	—	±1.0	±1.5	—	±1.0	±1.5	LSB 2 MΩ load resistance
	—	—	±2.0	—	—	±1.0	—	—	±1.0	LSB 4 MΩ load resistance

22.3 MCU Operational Timing

This section provides the following timing charts:

- | | |
|---|-------------------------|
| 22.3.1 Bus Timing | Figures 22-4 and 22-5 |
| 22.3.2 Control Signal Timing | Figures 22-6 to 22-9 |
| 22.3.3 16-Bit Free-Running Timer Timing | Figures 22-10 and 22-11 |
| 22.3.4 8-Bit Timer Timing | Figures 22-12 to 22-14 |
| 22.3.5 PWM Timer Timing | Figure 22-15 |
| 22.3.6 SCI Timing | Figures 22-16 and 22-17 |
| 22.3.7 I/O Port Timing | Figure 22-18 |
| 22.3.8 Host Interface Timing (H8/3337 Series Only) | Figures 22-19 and 22-20 |
| 22.3.9 I ² C Bus Timing (Option) (H8/3337 Series Only) | Figure 22-21 |
| 22.3.10 External Clock Output Timing | Figure 22-22 |

22.3.1 Bus Timing

(1) Basic Bus Cycle (without Wait States) in Expanded Modes

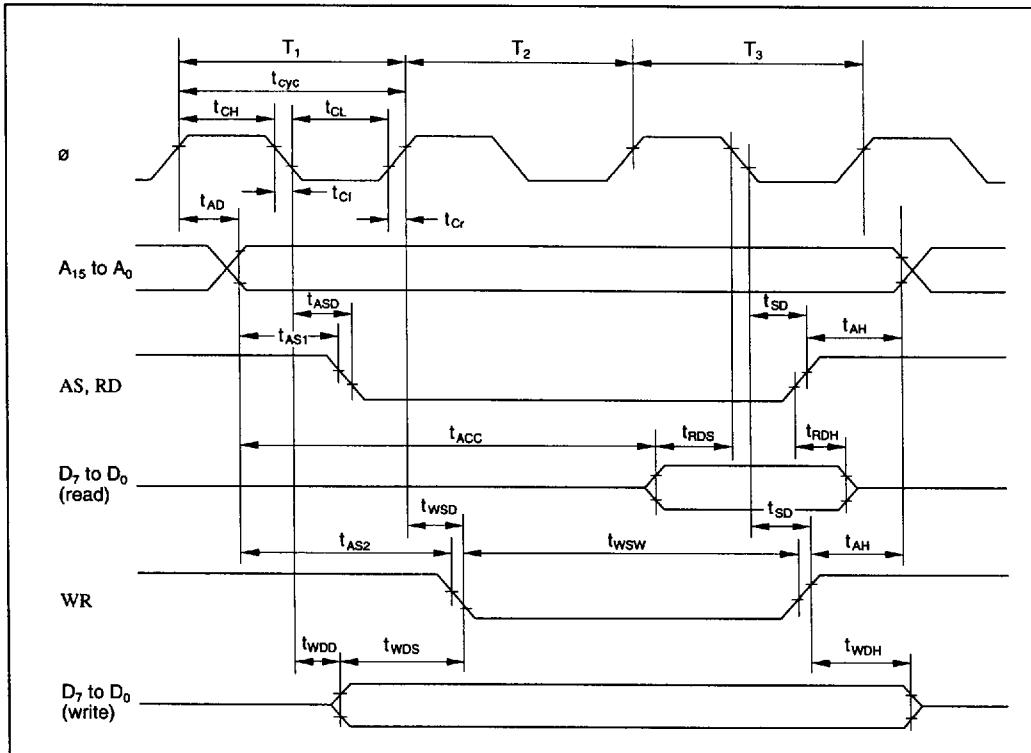


Figure 22-4 Basic Bus Cycle (without Wait States) in Expanded Modes

(2) Basic Bus Cycle (with 1 Wait State) in Expanded Modes

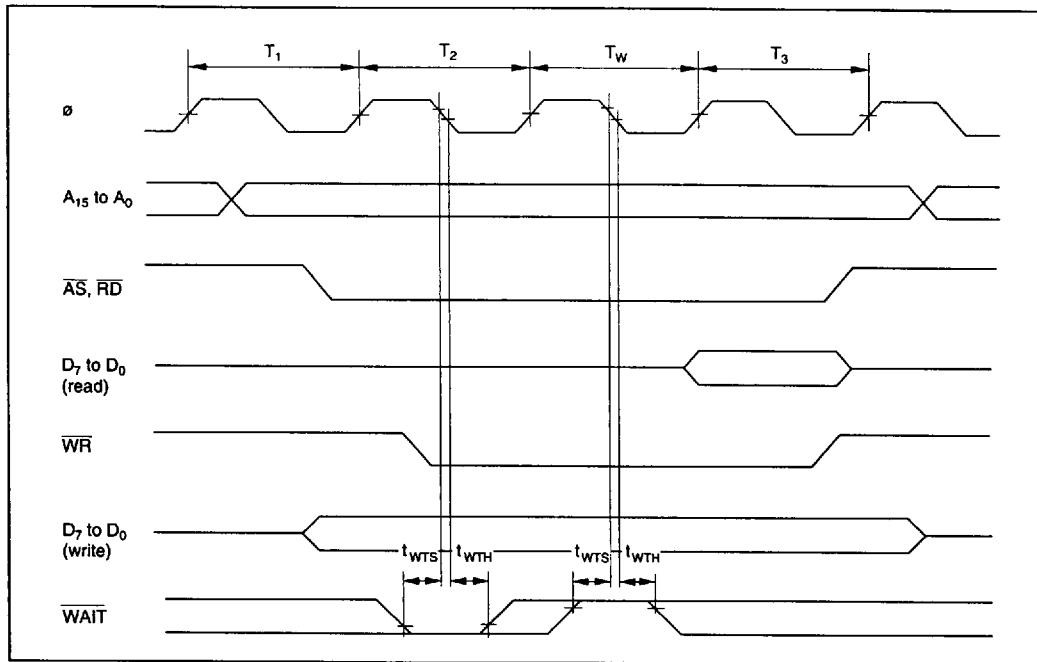


Figure 22-5 Basic Bus Cycle (with 1 Wait State) in Expanded Modes (Modes 1 and 2)

22.3.2 Control Signal Timing

(1) Reset Input Timing

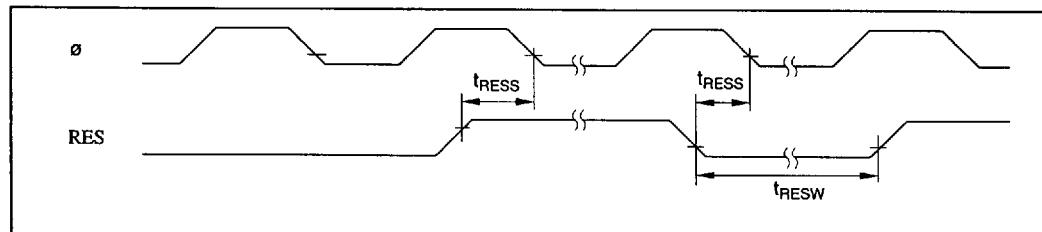


Figure 22-6 Reset Input Timing

(2) Interrupt Input Timing

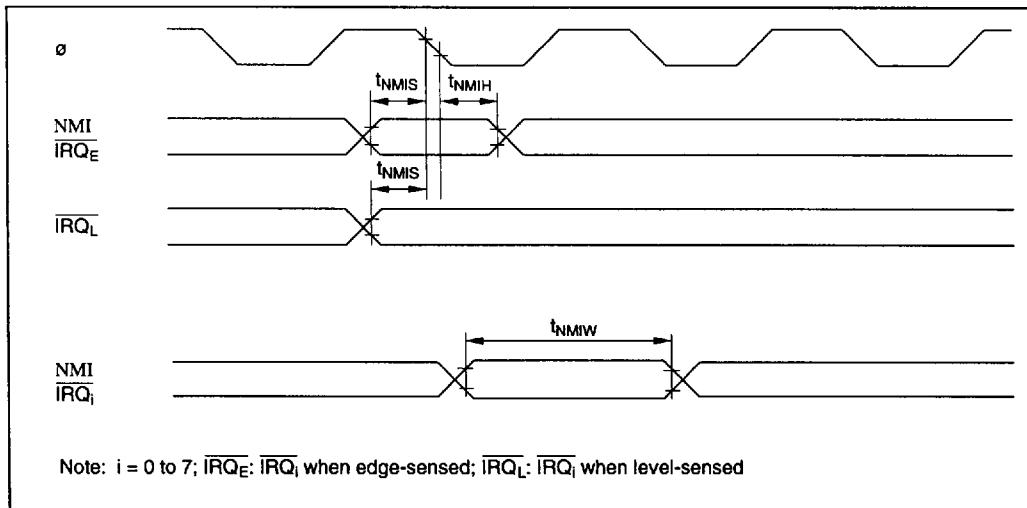


Figure 22-7 Interrupt Input Timing

(3) Clock Settling Timing

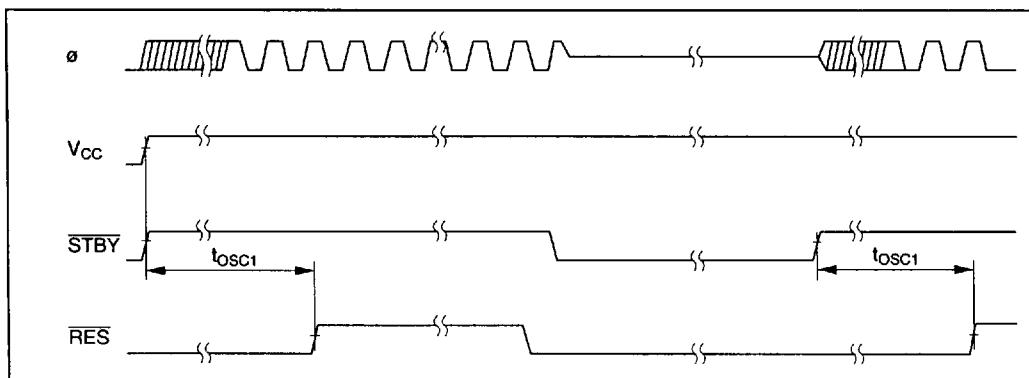


Figure 22-8 Clock Settling Timing

(4) Clock Settling Timing for Recovery from Software Standby Mode

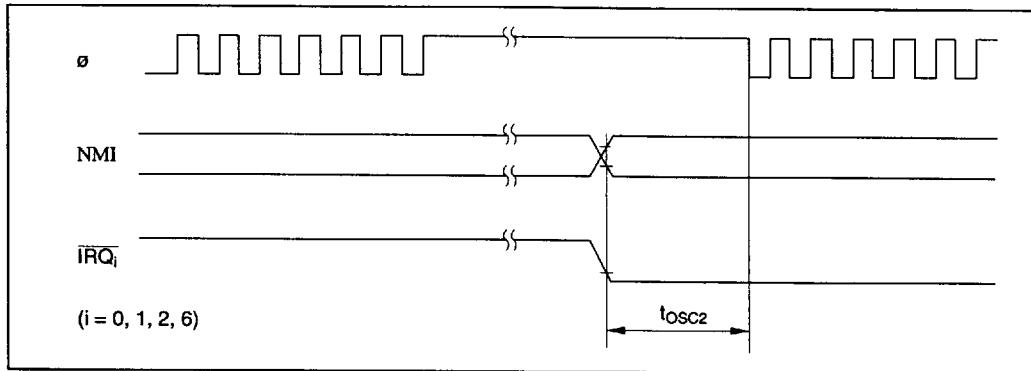


Figure 22-9 Clock Settling Timing for Recovery from Software Standby Mode

22.3.3 16-Bit Free-Running Timer Timing

(1) Free-Running Timer Input/Output Timing

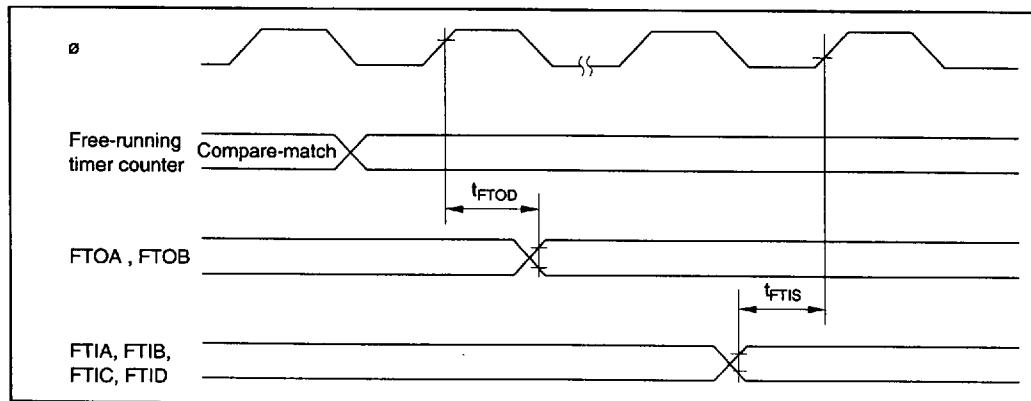


Figure 22-10 Free-Running Timer Input/Output Timing

(2) External Clock Input Timing for Free-Running Timer

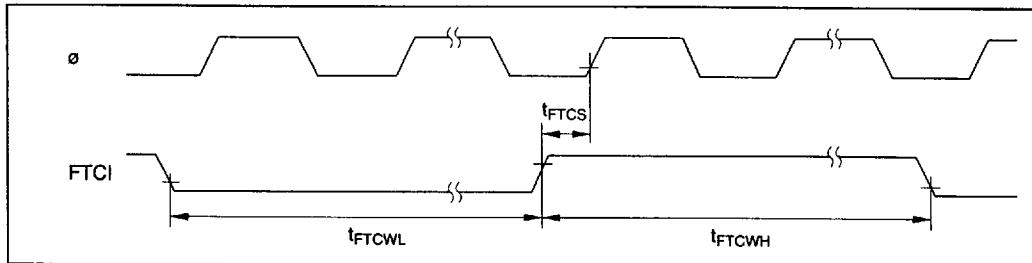


Figure 22-11 External Clock Input Timing for Free-Running Timer

22.3.4 8-Bit Timer Timing

(1) 8-Bit Timer Output Timing

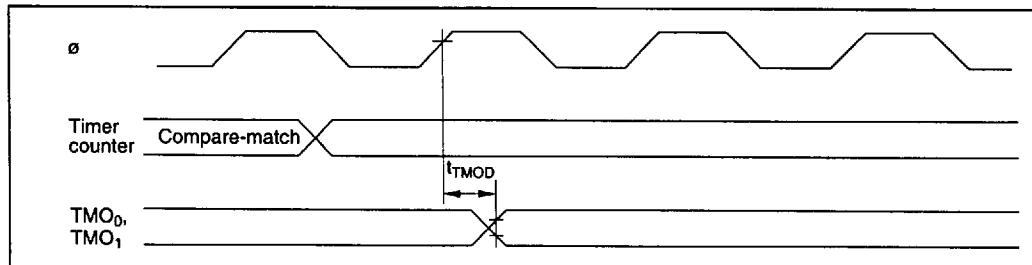


Figure 22-12 8-Bit Timer Output Timing

(2) 8-Bit Timer Clock Input Timing

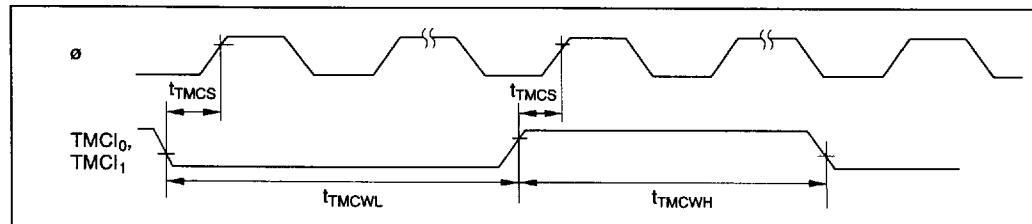


Figure 22-13 8-Bit Timer Clock Input Timing

(3) 8-Bit Timer Reset Input Timing

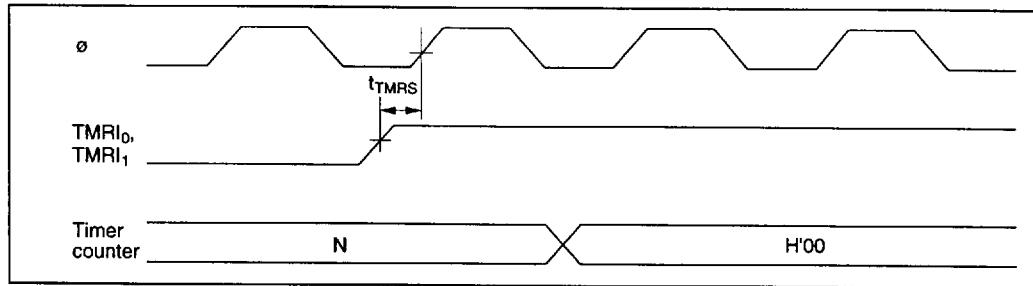


Figure 22-14 8-Bit Timer Reset Input Timing

22.3.5 Pulse Width Modulation Timer Timing

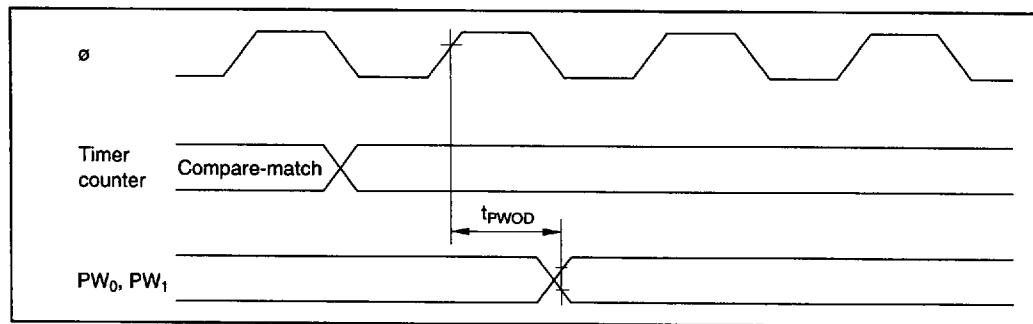


Figure 22-15 PWM Timer Output Timing

22.3.6 Serial Communication Interface Timing

(1) SCI Input/Output Timing

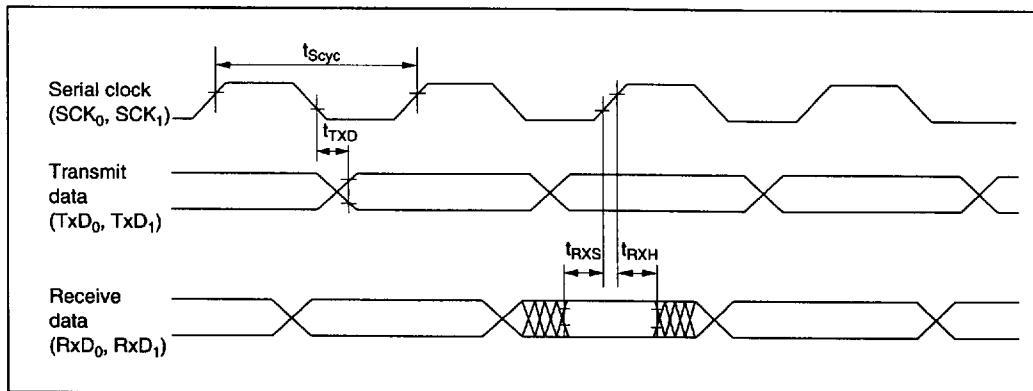


Figure 22-16 SCI Input/Output Timing (Synchronous Mode)

(2) SCI Input Clock Timing

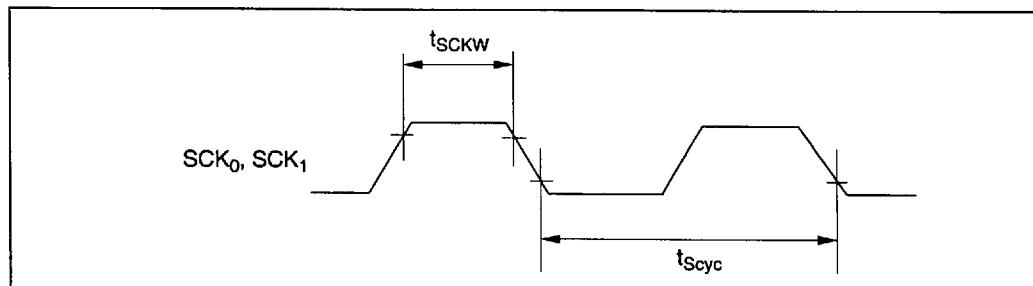


Figure 22-17 SCI Input Clock Timing

22.3.7 I/O Port Timing

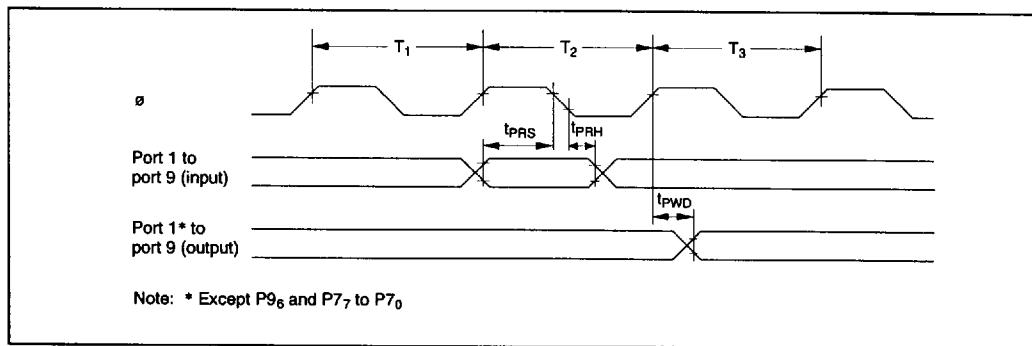


Figure 22-18 I/O Port Input/Output Timing

22.3.8 Host Interface Timing (H8/3337 Series Only)

(1) Host Interface Read Timing

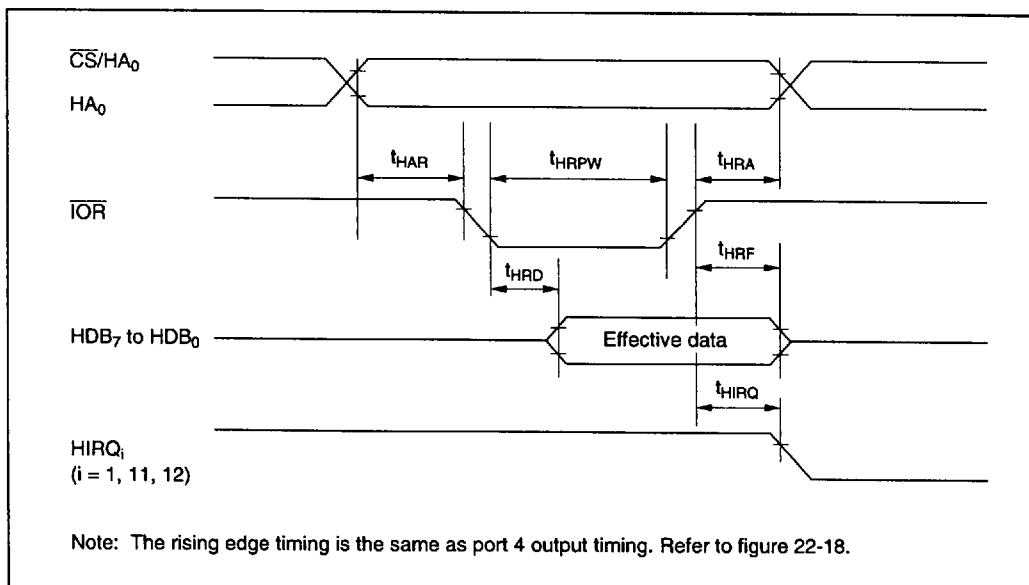


Figure 22-19 Host Interface Read Timing

(2) Host Interface Write Timing

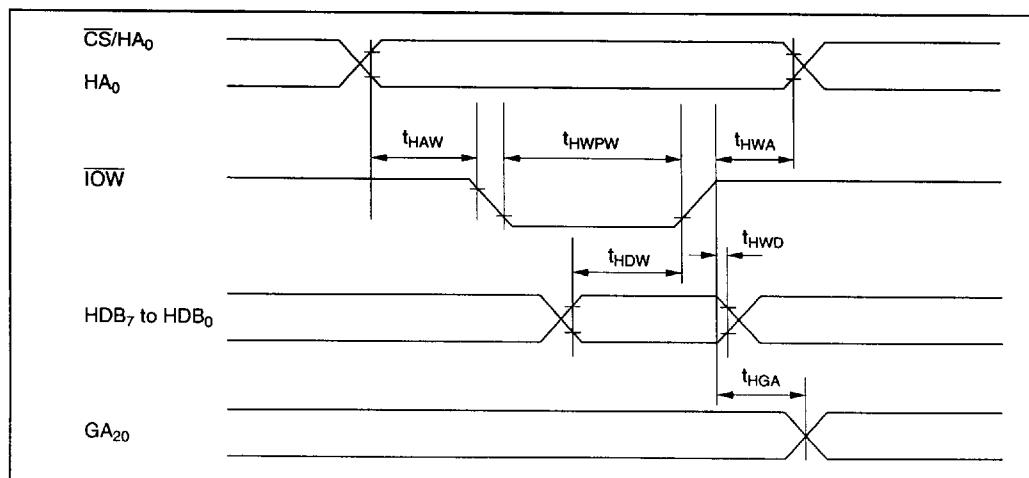


Figure 22-20 Host Interface Write Timing

22.3.9 I²C Bus Timing (Option) (H8/3337 Series Only)

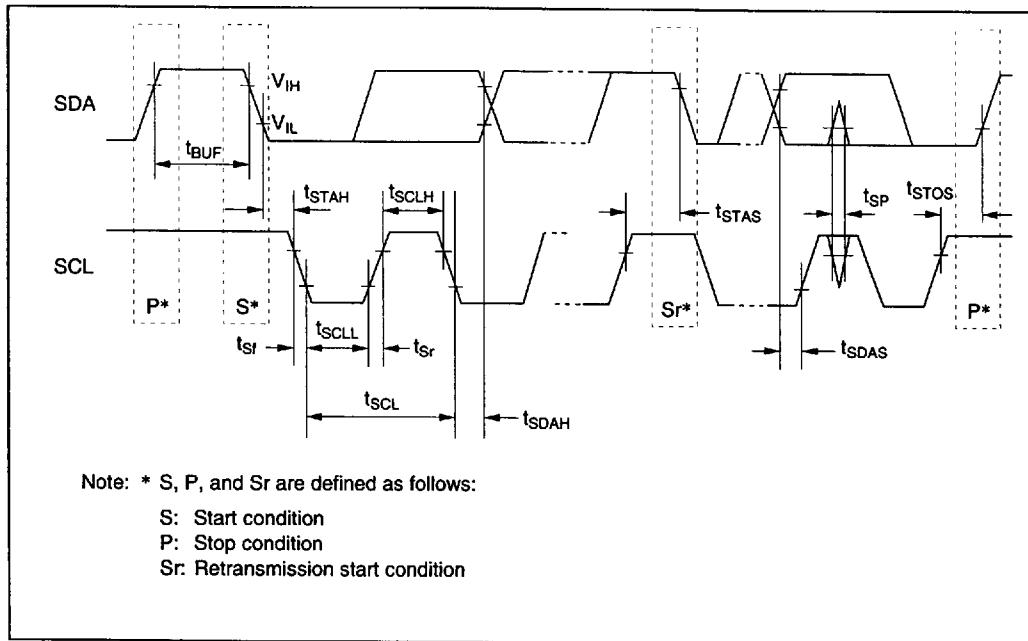


Figure 22-21 I²C Interface Input/Output Timing

22.3.10 External Clock Output Timing

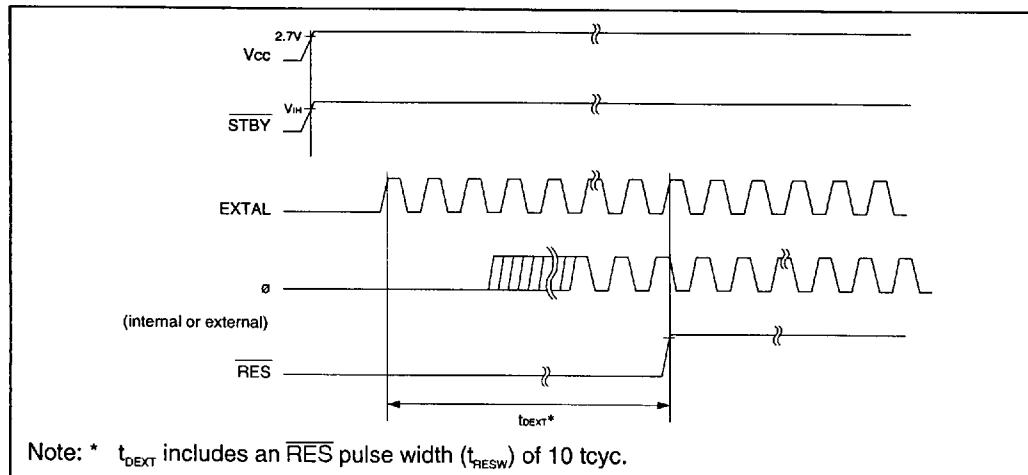


Figure 22-22 External clock output delay Timing

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