

Features

- Pin and Software Compatibility with Standard 80C51 Products and 80C51Fx/Rx/Rx+
- Plug-In Replacement of Intel's 8xC251Sx
- C251 Core: Intel's MCS[®]251 D-step Compliance
- 40-byte Register File
- Registers Accessible as Bytes, Words or Dwords
- Three-stage Instruction Pipeline
- 16-bit Internal Code Fetch
- Enriched C51 Instruction Set
- 16-bit and 32-bit ALU
- Compare and Conditional Jump Instructions
- Expanded Set of Move Instructions
- Linear Addressing
- 1 Kbyte of On-Chip RAM
- External Memory Space (Code/Data) Programmable from 64 kilobytes to 256 kilobytes
- TSC87251G2D: 32 kilobytes of On-Chip EPROM/OTPROM
 - SINGLE PULSE Programming Algorithm
- TSC83251G2D: 32 kilobytes of On-Chip Masked ROM
- TSC80251G2D: ROMless Version
- Four 8-bit Parallel I/O Ports (Ports 0, 1, 2 and 3 of the Standard 80C51)
- Serial I/O Port: Full Duplex UART (80C51 Compatible) With Independent Baud Rate Generator
- SSLC: Synchronous Serial Link Controller
- TWI Multi-master Protocol
- μ Wire and SPI Master and Slave Protocols
- Three 16-bit Timers/Counters (Timers 0, 1 and 2 of the Standard 80C51)
- EWC: Event and Waveform Controller
- Compatible with Intel's Programmable Counter Array (PCA)
- Common 16-bit Timer/Counter Reference with Four Possible Clock Sources (Fosc/4, Fosc/12, Timer 1 and External Input)
- Five Modules, Each with Four Programmable Modes:
 - 16-bit Software Timer/Counter
 - 16-bit Timer/Counter Capture Input and Software Pulse Measurement
 - High-speed Output and 16-bit Software Pulse Width Modulation (PWM)
 - 8-bit Hardware PWM Without Overhead
- 16-bit Watchdog Timer/Counter Capability
- Secure 14-bit Hardware Watchdog Timer
- Power Management
- Power-On Reset (Integrated on the Chip)
- Power-Off Flag (Cold and Warm Resets)
- Software Programmable System Clock
- Idle Mode
- Power-down Mode
- Keyboard Interrupt Interface on Port 1
- Non Maskable Interrupt Input (NMI)
- Real-Time Wait States Inputs (WAIT#/AWAIT#)
- ONCE Mode and Full Speed Real-time In-circuit Emulation Support (Third Party Vendors)
- High Speed Versions:
 - 4.5V to 5.5V
 - 16 MHz and 24 MHz
- Typical Operating Current: 35 mA at 24 MHz
24 mA at 16 MHz
- Typical Power-down Current: 2 μ A
- Low Voltage Version:
 - 2.7V to 5.5V
 - 16 MHz



8/16-bit Microcontroller with Serial Communication Interfaces

TSC80251G2D
TSC83251G2D
TSC87251G2D
AT80251G2D
AT83251G2D
AT87251G2D

Rev. 4135F-8051-11/06





- **Typical Operating Current:** 11 mA at 3V
- **Typical Power-down Current:** 1 μ A
- **Temperature Ranges:** Commercial (0°C to +70°C), Industrial (-40°C to +85°C), Automotive ((-40°C to +85°C) ROM only)
- **Option:** Extended Range (-55°C to +125°C)
- **Packages:** PDIL 40, PLCC 44 and VQFP 44
- **Options:** Known Good Dice and Ceramic Packages

Description

The TSC80251G2D products are derivatives of the Atmel Microcontroller family based on the 8/16-bit C251 Architecture. This family of products is tailored to 8/16-bit microcontroller applications requiring an increased instruction throughput, a reduced operating frequency or a larger addressable memory space. The architecture can provide a significant code size reduction when compiling C programs while fully preserving the legacy of C51 assembly routines.

The TSC80251G2D derivatives are pin and software compatible with standard 80C51/Fx/Rx/Rx+ with extended on-chip data memory (1 Kbyte RAM) and up to 256 kilobytes of external code and data. Additionally, the TSC83251G2D and TSC87251G2D provide on-chip code memory: 32 kilobytes ROM and 32 kilobytes EPROM/OTPROM respectively.

They provide transparent enhancements to Intel's 8xC251Sx family with an additional Synchronous Serial Link Controller (SSLC supporting TWI, μ Wire and SPI protocols), a Keyboard interrupt interface, a dedicated Baud Rate Generator for UART, and Power Management features.

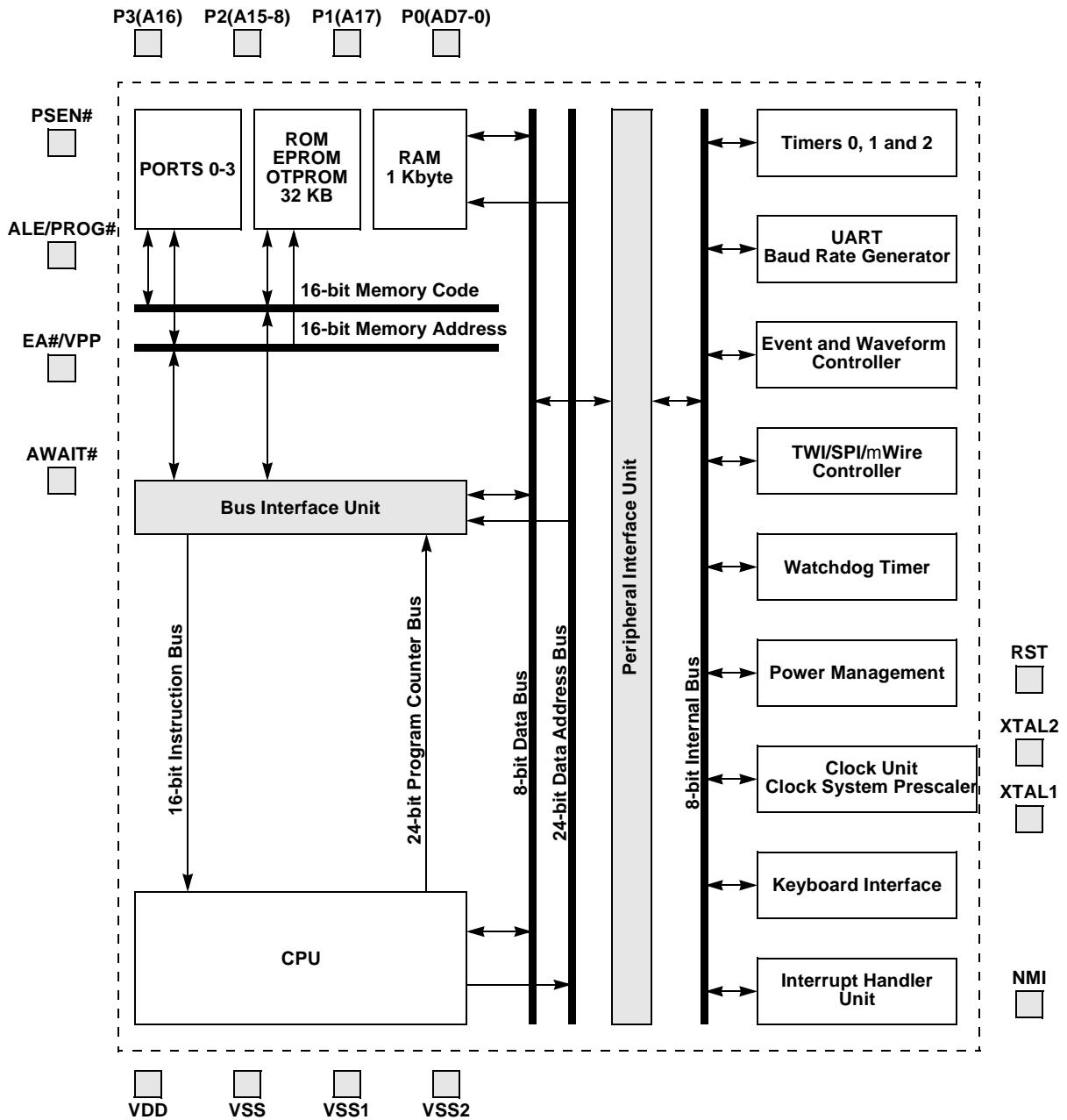
TSC80251G2D derivatives are optimized for speed and for low power consumption on a wide voltage range.

Note: 1. This Datasheet provides the technical description of the TSC80251G2D derivatives. For further information on the device usage, please request the TSC80251 Programmer's Guide and the TSC80251G1D Design Guide and errata sheet.

Typical Applications

- ISDN Terminals
- High-Speed Modems
- PABX (SOHO)
- Line Cards
- DVD ROM and Players
- Printers
- Plotters
- Scanners
- Banking Machines
- Barcode Readers
- Smart Cards Readers
- High-End Digital Monitors
- High-End Joysticks
- High-end TV's

Block Diagram



Pin Description

Pinout

Figure 1. TSC80251G2D 40-pin DIP package

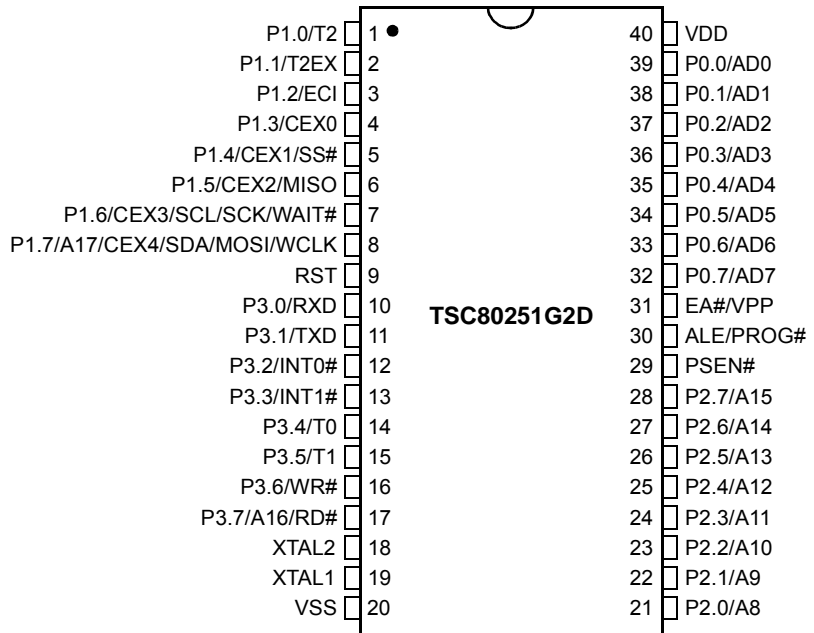


Figure 2. TSC80251G2D 44-pin PLCC Package

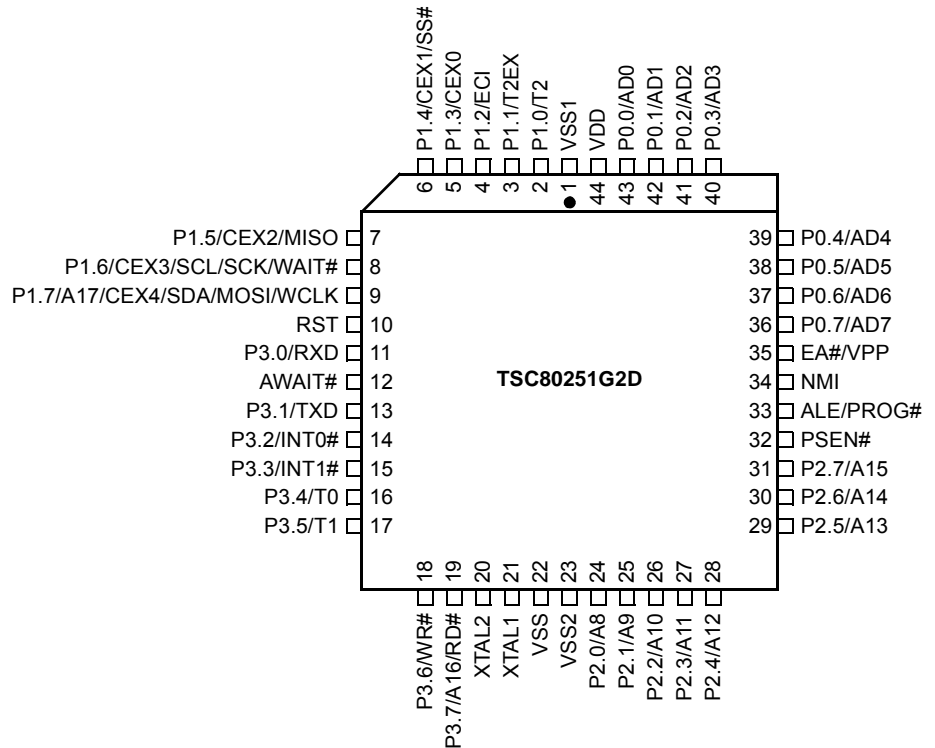


Figure 3. TSC80251G2D 44-pin VQFP Package

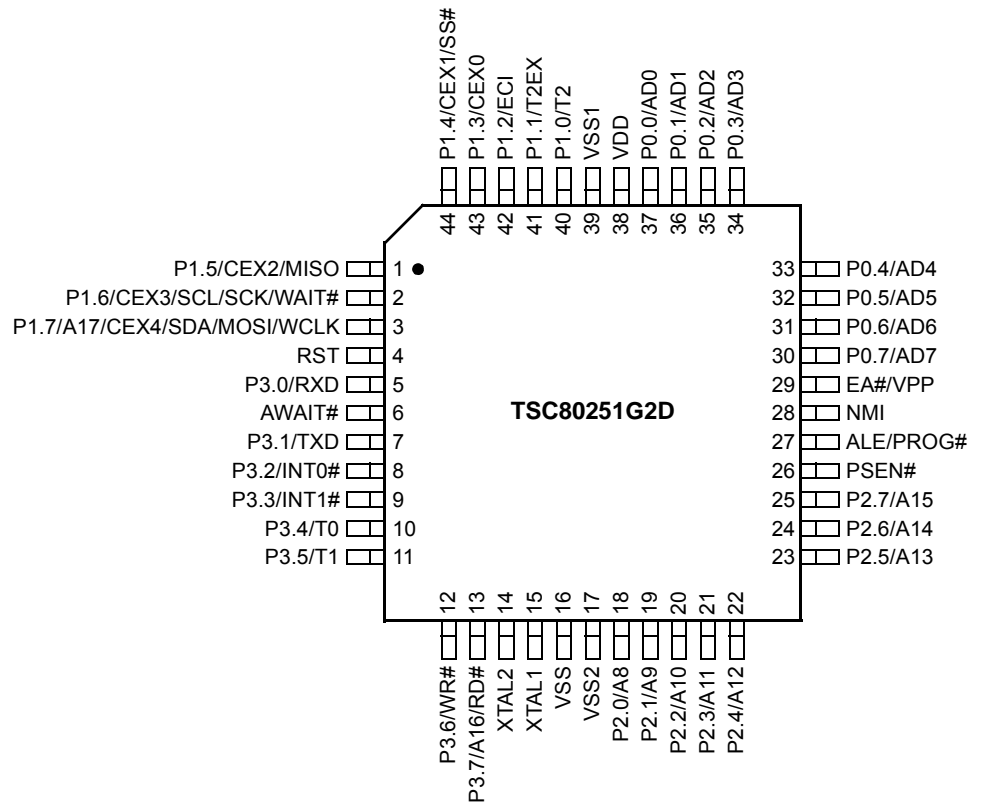




Table 1. TSC80251G2D Pin Assignment

| DIP | PLCC | VQFP | Name | DIP | PLCC | VQFP | Name |
|-----|------|------|-----------------------------|-----|------|------|-----------|
| | 1 | 39 | VSS1 | | 23 | 17 | VSS2 |
| 1 | 2 | 40 | P1.0/T2 | 21 | 24 | 18 | P2.0/A8 |
| 2 | 3 | 41 | P1.1/T2EX | 22 | 25 | 19 | P2.1/A9 |
| 3 | 4 | 42 | P1.2/ECI | 23 | 26 | 20 | P2.2/A10 |
| 4 | 5 | 43 | P1.3/CEX0 | 24 | 27 | 21 | P2.3/A11 |
| 5 | 6 | 44 | P1.4/CEX1/SS# | 25 | 28 | 22 | P2.4/A12 |
| 6 | 7 | 1 | P1.5/CEX2/MISO | 26 | 29 | 23 | P2.5/A13 |
| 7 | 8 | 2 | P1.6/CEX3/SCL/SCK/WAIT# | 27 | 30 | 24 | P2.6/A14 |
| 8 | 9 | 3 | P1.7/A17/CEX4/SDA/MOSI/WCLK | 28 | 31 | 25 | P2.7/A15 |
| 9 | 10 | 4 | RST | 29 | 32 | 26 | PSEN# |
| 10 | 11 | 5 | P3.0/RXD | 30 | 33 | 27 | ALE/PROG# |
| | 12 | 6 | AWAIT# | | 34 | 28 | NMI |
| 11 | 13 | 7 | P3.1/TXD | 31 | 35 | 29 | EA#/VPP |
| 12 | 14 | 8 | P3.2/INT0# | 32 | 36 | 30 | P0.7/AD7 |
| 13 | 15 | 9 | P3.3/INT1# | 33 | 37 | 31 | P0.6/AD6 |
| 14 | 16 | 10 | P3.4/T0 | 34 | 38 | 32 | P0.5/AD5 |
| 15 | 17 | 11 | P3.5/T1 | 35 | 39 | 33 | P0.4/AD4 |
| 16 | 18 | 12 | P3.6/WR# | 36 | 40 | 34 | P0.3/AD3 |
| 17 | 19 | 13 | P3.7/A16/RD# | 37 | 41 | 35 | P0.2/AD2 |
| 18 | 20 | 14 | XTAL2 | 38 | 42 | 36 | P0.1/AD1 |
| 19 | 21 | 15 | XTAL1 | 39 | 43 | 37 | P0.0/AD0 |
| 20 | 22 | 16 | VSS | 40 | 44 | 38 | VDD |

Signals

Table 2. Product Name Signal Description

| Signal Name | Type | Description | Alternate Function |
|----------------------|------|--|--------------------|
| A17 | O | 18th Address Bit Output to memory as 18th external address bit (A17) in extended bus applications, depending on the values of bits RD0 and RD1 in UCONFIG0 byte (see Table 13, Page 20). | P1.7 |
| A16 | O | 17th Address Bit Output to memory as 17th external address bit (A16) in extended bus applications, depending on the values of bits RD0 and RD1 in UCONFIG0 byte (see Table 13, Page 20). | P3.7 |
| A15:8 ⁽¹⁾ | O | Address Lines Upper address lines for the external bus. | P2.7:0 |
| AD7:0 ⁽¹⁾ | I/O | Address/Data Lines Multiplexed lower address lines and data for the external memory. | P0.7:0 |
| ALE | O | Address Latch Enable ALE signals the start of an external bus cycle and indicates that valid address information are available on lines A16/A17 and A7:0. An external latch can use ALE to demultiplex the address from address/data bus. | – |
| AWAIT# | I | Real-time Asynchronous Wait States Input When this pin is active (low level), the memory cycle is stretched until it becomes high. When using the Product Name as a pin-for-pin replacement for a 8xC51 product, AWAIT# can be unconnected without loss of compatibility or power consumption increase (on-chip pull-up). Not available on DIP package. | – |
| CEX4:0 | I/O | PCA Input/Output pins CEXx are input signals for the PCA capture mode and output signals for the PCA compare and PWM modes. | P1.7:3 |
| EA# | I | External Access Enable EA# directs program memory accesses to on-chip or off-chip code memory. For EA# = 0, all program memory accesses are off-chip. For EA# = 1, an access is on-chip ROM if the address is within the range of the on-chip ROM; otherwise the access is off-chip. The value of EA# is latched at reset. For devices without ROM on-chip, EA# must be strapped to ground. | – |
| ECl | O | PCA External Clock input ECl is the external clock input to the 16-bit PCA timer. | P1.2 |
| MISO | I/O | SPI Master Input Slave Output line When SPI is in master mode, MISO receives data from the slave peripheral. When SPI is in slave mode, MISO outputs data to the master controller. | P1.5 |
| MOSI | I/O | SPI Master Output Slave Input line When SPI is in master mode, MOSI outputs data to the slave peripheral. When SPI is in slave mode, MOSI receives data from the master controller. | P1.7 |
| INT1:0# | I | External Interrupts 0 and 1 INT1#/INT0# inputs set IE1:0 in the TCON register. If bits IT1:0 in the TCON register are set, bits IE1:0 are set by a falling edge on INT1#/INT0#. If bits IT1:0 are cleared, bits IE1:0 are set by a low level on INT1#/INT0#. | P3.3:2 |

Table 2. Product Name Signal Description (Continued)

| Signal Name | Type | Description | Alternate Function |
|-------------|------|---|--------------------|
| NMI | I | Non Maskable Interrupt Holding this pin high for 24 oscillator periods triggers an interrupt. When using the Product Name as a pin-for-pin replacement for a 8xC51 product, NMI can be unconnected without loss of compatibility or power consumption increase (on-chip pull-down). Not available on DIP package. | – |
| P0.0:7 | I/O | Port 0 P0 is an 8-bit open-drain bidirectional I/O port. Port 0 pins that have 1s written to them float and can be used as high impedance inputs. To avoid any parasitic current consumption, Floating P0 inputs must be polarized to V_{DD} or V_{SS} . | AD7:0 |
| P1.0:7 | I/O | Port 1 P1 is an 8-bit bidirectional I/O port with internal pull-ups. P1 provides interrupt capability for a keyboard interface. | – |
| P2.0:7 | I/O | Port 2 P2 is an 8-bit bidirectional I/O port with internal pull-ups. | A15:8 |
| P3.0:7 | I/O | Port 3 P3 is an 8-bit bidirectional I/O port with internal pull-ups. | – |
| PROG# | I | Programming Pulse input The programming pulse is applied to this input for programming the on-chip EPROM/OTPROM. | – |
| PSEN# | O | Program Store Enable/Read signal output PSEN# is asserted for a memory address range that depends on bits RD0 and RD1 in UCONFIG0 byte (see). | – |
| RD# | O | Read or 17th Address Bit (A16) Read signal output to external data memory depending on the values of bits RD0 and RD1 in UCONFIG0 byte (see Table 13, Page 20). | P3.7 |
| RST | I | Reset input to the chip Holding this pin high for 64 oscillator periods while the oscillator is running resets the device. The Port pins are driven to their reset conditions when a voltage greater than V_{IH1} is applied, whether or not the oscillator is running. This pin has an internal pull-down resistor which allows the device to be reset by connecting a capacitor between this pin and VDD. Asserting RST when the chip is in Idle mode or Power-Down mode returns the chip to normal operation. | – |
| RXD | I/O | Receive Serial Data RXD sends and receives data in serial I/O mode 0 and receives data in serial I/O modes 1, 2 and 3. | P3.0 |
| SCL | I/O | TWI Serial Clock When TWI controller is in master mode, SCL outputs the serial clock to slave peripherals. When TWI controller is in slave mode, SCL receives clock from the master controller. | P1.6 |
| SCK | I/O | SPI Serial Clock When SPI is in master mode, SCK outputs clock to the slave peripheral. When SPI is in slave mode, SCK receives clock from the master controller. | P1.6 |
| SDA | I/O | TWI Serial Data SDA is the bidirectional TWI data line. | P1.7 |
| SS# | I | SPI Slave Select Input When in Slave mode, SS# enables the slave mode. | P1.4 |

Table 2. Product Name Signal Description (Continued)

| Signal Name | Type | Description | Alternate Function |
|-------------|------|--|--------------------|
| T1:0 | I/O | Timer 1:0 External Clock Inputs When timer 1:0 operates as a counter, a falling edge on the T1:0 pin increments the count. | – |
| T2 | I/O | Timer 2 Clock Input/Output For the timer 2 capture mode, T2 is the external clock input. For the Timer 2 clock-out mode, T2 is the clock output. | P1.0 |
| T2EX | I | Timer 2 External Input In timer 2 capture mode, a falling edge initiates a capture of the timer 2 registers. In auto-reload mode, a falling edge causes the timer 2 register to be reloaded. In the up-down counter mode, this signal determines the count direction: 1 = up, 0 = down. | P1.1 |
| TXD | O | Transmit Serial Data TXD outputs the shift clock in serial I/O mode 0 and transmits data in serial I/O modes 1, 2 and 3. | P3.1 |
| VDD | PWR | Digital Supply Voltage Connect this pin to +5V or +3V supply voltage. | – |
| VPP | I | Programming Supply Voltage The programming supply voltage is applied to this input for programming the on-chip EPROM/OTPROM. | – |
| VSS | GND | Circuit Ground Connect this pin to ground. | – |
| VSS1 | GND | Secondary Ground 1 This ground is provided to reduce ground bounce and improve power supply bypassing. Connection of this pin to ground is recommended. However, when using the TSC80251G2D as a pin-for-pin replacement for a 8xC51 product, VSS1 can be unconnected without loss of compatibility. Not available on DIP package. | – |
| VSS2 | GND | Secondary Ground 2 This ground is provided to reduce ground bounce and improve power supply bypassing. Connection of this pin to ground is recommended. However, when using the TSC80251G2D as a pin-for-pin replacement for a 8xC51 product, VSS2 can be unconnected without loss of compatibility. Not available on DIP package. | – |
| WAIT# | I | Real-time Synchronous Wait States Input The real-time WAIT# input is enabled by setting RTWE bit in WCON (S:A7h). During bus cycles, the external memory system can signal 'system ready' to the microcontroller in real time by controlling the WAIT# input signal. | P1.6 |
| WCLK | O | Wait Clock Output The real-time WCLK output is enabled by setting RTWCE bit in WCON (S:A7h). When enabled, the WCLK output produces a square wave signal with a period of one half the oscillator frequency. | P1.7 |
| WR# | O | Write Write signal output to external memory. | P3.6 |
| XTAL1 | I | Input to the on-chip inverting oscillator amplifier To use the internal oscillator, a crystal/resonator circuit is connected to this pin. If an external oscillator is used, its output is connected to this pin. XTAL1 is the clock source for internal timing. | – |



Table 2. Product Name Signal Description (Continued)

| Signal Name | Type | Description | Alternate Function |
|-------------|------|--|--------------------|
| XTAL2 | O | Output of the on-chip inverting oscillator amplifier To use the internal oscillator, a crystal/resonator circuit is connected to this pin. If an external oscillator is used, leave XTAL2 unconnected. | – |

Note: The description of A15:8/P2.7:0 and AD7:0/P0.7:0 are for the Non-Page mode chip configuration. If the chip is configured in Page mode operation, port 0 carries the lower address bits (A7:0) while port 2 carries the upper address bits (A15:8) and the data (D7:0).

compatibility with the C51 Architecture). When PC increments beyond the end of segment FE:, it continues at the reset address FF:0000h (linearity). When PC increments beyond the end of segment 01:, it loops to the beginning of segment 00: (this prevents from its going into the reserved area).

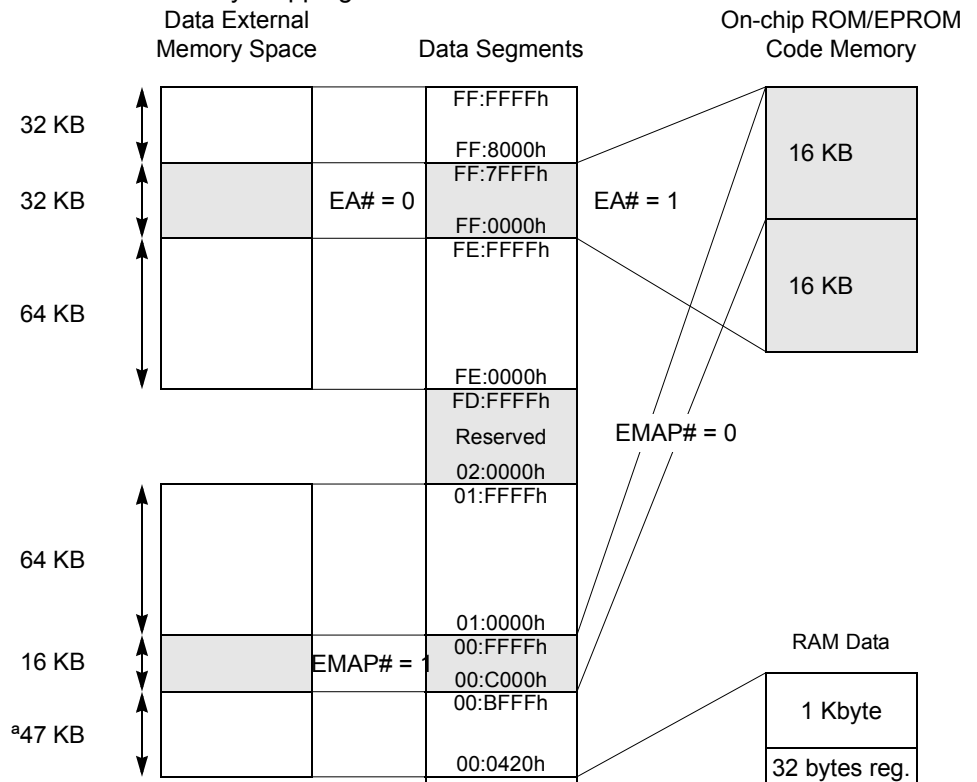
Data Memory

The TSC80251G2D derivatives implement 1 Kbyte of on-chip data RAM. Figure 5 shows the split of the internal and external data memory spaces. This memory is mapped in the data space just over the 32 bytes of registers area (see TSC80251 Programmers' Guide). Hence, the part of the on-chip RAM located from 20h to FFh is bit addressable. This on-chip RAM is not accessible through the program/code memory space.

For faster computation with the on-chip ROM/EPROM code of the TSC83251G2D/TSC87251G2D, its upper 16 KB are also mapped in the upper part of the region 00: if the On-Chip Code Memory Map configuration bit is cleared (EMAP# bit in UCONFIG1 byte, see Figure). However, if EA# is tied to a low level, the TSC80251G2D derivative is running as a ROMless product and the code is actually fetched in the corresponding external memory (i.e. the upper 16 KB of the lower 32 KB of the segment FF:). If EMAP# bit is set, the on-chip ROM is not accessible through the region 00:.

All the accesses to the portion of the data space with no on-chip memory mapped onto are redirected to the external memory.

Figure 5. Data Memory Mapping



Special Function Registers

The Special Function Registers (SFRs) of the TSC80251G2D derivatives fall into the categories detailed in Table 1 to Table 9.

SFRs are placed in a reserved on-chip memory region S: which is not represented in the data memory mapping (Figure 5). The relative addresses within S: of these SFRs are provided together with their reset values in Table . They are upward compatible with the SFRs of the standard 80C51 and the Intel's 80C251Sx family. In this table, the C251 core registers are identified by Note 1 and are described in the TSC80251 Programmer's Guide. The other SFRs are described in the TSC80251G1D Design Guide. All the SFRs are bit-addressable using the C251 instruction set.

Table 1. C251 Core SFRs

| Mnemonic | Name |
|--------------------|----------------------------|
| ACC ⁽¹⁾ | Accumulator |
| B ⁽¹⁾ | B Register |
| PSW | Program Status Word |
| PSW1 | Program Status Word 1 |
| SP ⁽¹⁾ | Stack Pointer - LSB of SPX |

| Mnemonic | Name |
|---------------------|---|
| SPH ⁽¹⁾ | Stack Pointer High - MSB of SPX |
| DPL ⁽¹⁾ | Data Pointer Low byte - LSB of DPTR |
| DPH ⁽¹⁾ | Data Pointer High byte - MSB of DPTR |
| DPXL ⁽¹⁾ | Data Pointer Extended Low byte of DPX - Region number |

Note: 1. These SFRs can also be accessed by their corresponding registers in the register file.

Table 2. I/O Port SFRs

| Mnemonic | Name |
|----------|--------|
| P0 | Port 0 |
| P1 | Port 1 |

| Mnemonic | Name |
|----------|--------|
| P2 | Port 2 |
| P3 | Port 3 |

Table 3. Timers SFRs

| Mnemonic | Name |
|----------|-------------------------------|
| TL0 | Timer/Counter 0 Low Byte |
| TH0 | Timer/Counter 0 High Byte |
| TL1 | Timer/Counter 1 Low Byte |
| TH1 | Timer/Counter 1 High Byte |
| TL2 | Timer/Counter 2 Low Byte |
| TH2 | Timer/Counter 2 High Byte |
| TCON | Timer/Counter 0 and 1 Control |

| Mnemonic | Name |
|----------|--|
| TMOD | Timer/Counter 0 and 1 Modes |
| T2CON | Timer/Counter 2 Control |
| T2MOD | Timer/Counter 2 Mode |
| RCAP2L | Timer/Counter 2 Reload/Capture Low Byte |
| RCAP2H | Timer/Counter 2 Reload/Capture High Byte |
| WDTRST | WatchDog Timer Reset |

Table 4. Serial I/O Port SFRs

| Mnemonic | Name |
|----------|--------------------|
| SCON | Serial Control |
| SBUF | Serial Data Buffer |
| SADEN | Slave Address Mask |

| Mnemonic | Name |
|----------|-------------------|
| SADDR | Slave Address |
| BRL | Baud Rate Reload |
| BDRCON | Baud Rate Control |

Table 5. SSLC SFRs

| Mnemonic | Name |
|----------|---------------------------------------|
| SSCON | Synchronous Serial control |
| SSDAT | Synchronous Serial Data |
| SSCS | Synchronous Serial Control and Status |

| Mnemonic | Name |
|----------|-----------------------------|
| SSADR | Synchronous Serial Address |
| SSBR | Synchronous Serial Bit Rate |

Table 6. Event Waveform Control SFRs

| Mnemonic | Name |
|----------|-------------------------------------|
| CCON | EWC-PCA Timer/Counter Control |
| CMOD | EWC-PCA Timer/Counter Mode |
| CL | EWC-PCA Timer/Counter Low Register |
| CH | EWC-PCA Timer/Counter High Register |
| CCAPM0 | EWC-PCA Timer/Counter Mode 0 |
| CCAPM1 | EWC-PCA Timer/Counter Mode 1 |
| CCAPM2 | EWC-PCA Timer/Counter Mode 2 |
| CCAPM3 | EWC-PCA Timer/Counter Mode 3 |
| CCAPM4 | EWC-PCA Timer/Counter Mode 4 |

| Mnemonic | Name |
|----------|--|
| CCAP0L | EWC-PCA Compare Capture Module 0 Low Register |
| CCAP1L | EWC-PCA Compare Capture Module 1 Low Register |
| CCAP2L | EWC-PCA Compare Capture Module 2 Low Register |
| CCAP3L | EWC-PCA Compare Capture Module 3 Low Register |
| CCAP4L | EWC-PCA Compare Capture Module 4 Low Register |
| CCAP0H | EWC-PCA Compare Capture Module 0 High Register |
| CCAP1H | EWC-PCA Compare Capture Module 1 High Register |
| CCAP2H | EWC-PCA Compare Capture Module 2 High Register |
| CCAP3H | EWC-PCA Compare Capture Module 3 High Register |
| CCAP4H | EWC-PCA Compare Capture Module 4 High Register |

Table 7. System Management SFRs

| Mnemonic | Name |
|----------|------------------|
| PCON | Power Control |
| POWM | Power Management |

| Mnemonic | Name |
|----------|--|
| CKRL | Clock Reload |
| WCON | Synchronous Real-Time Wait State Control |

Table 8. Interrupt SFRs

| Mnemonic | Name |
|----------|-----------------------------------|
| IE0 | Interrupt Enable Control 0 |
| IE1 | Interrupt Enable Control 1 |
| IPH0 | Interrupt Priority Control High 0 |

| Mnemonic | Name |
|----------|-----------------------------------|
| IPL0 | Interrupt Priority Control Low 0 |
| IPH1 | Interrupt Priority Control High 1 |
| IPL1 | Interrupt Priority Control Low 1 |

Table 9. Keyboard Interface SFRs

| Mnemonic | Name |
|----------|-------------------------------|
| P1IE | Port 1 Input Interrupt Enable |
| P1F | Port 1 Flag |

| Mnemonic | Name |
|----------|------------------------|
| P1LS | Port 1 Level Selection |

Table 10. SFR Descriptions

| | 0/8 | 1/9 | 2/A | 3/B | 4/C | 5/D | 6/E | 7/F | |
|-----|---------------------------------|----------------------------------|---------------------------------|---------------------------------|----------------------------------|---------------------|---------------------------------|-------------------|-----|
| F8h | | CH 0000 0000 | CCAP0H 0000 0000 | CCAP1H 0000 0000 | CCAP2H 0000 0000 | CCAP3H 0000 0000 | CCAP4H 0000 0000 | | FFh |
| F0h | B ⁽¹⁾ 0000 0000 | | | | | | | | F7h |
| E8h | | CL 0000 0000 | CCAP0L 0000 0000 | CCAP1L 0000 0000 | CCAP2L 0000 0000 | CCAP3L 0000 0000 | CCAP4L 0000 0000 | | EFh |
| E0h | ACC ⁽¹⁾ 0000 0000 | | | | | | | | E7h |
| D8h | CCON 00X0 0000 | CMOD 00XX X000 | CCAPM0 X000 0000 | CCAPM1 X000 0000 | CCAPM2 X000 0000 | CCAPM3 X000 0000 | CCAPM4 X000 0000 | | DFh |
| D0h | PSW ⁽¹⁾ 0000 0000 | PSW1 ⁽¹⁾ 0000 0000 | | | | | | | D7h |
| C8h | T2CON 0000 0000 | T2MOD XXXX XX00 | RCAP2L 0000 0000 | RCAP2H 0000 0000 | TL2 0000 0000 | TH2 0000 0000 | | | CFh |
| C0h | | | | | | | | | C7h |
| B8h | IPL0 X000 0000 | SADEN 0000 0000 | | | | | SPH ⁽¹⁾ 0000 0000 | | BFh |
| B0h | P3 1111 1111 | IE1 XX0X XXX0 | IPL1 XX0X XXX0 | IPH1 XX0X XXX0 | | | | IPH0 X000 0000 | B7h |
| A8h | IE0 0000 0000 | SADDR 0000 0000 | | | | | | | AFh |
| A0h | P2 1111 1111 | | | | | | WDRST 1111 1111 | WCON XXXX XX00 | A7h |
| 98h | SCON 0000 0000 | SBUF XXXX XXXX | BRL 0000 0000 | BDRCON XXX0 0000 | P1LS 0000 0000 | P1IE 0000 0000 | P1F 0000 0000 | | 9Fh |
| 90h | P1 1111 1111 | | SSBR 0000 0000 | SSCON ⁽²⁾ | SSCS ⁽³⁾ | SSDAT 0000 0000 | SSADR 0000 0000 | | 97h |
| 88h | TCON 0000 0000 | TMOD 0000 0000 | TL0 0000 0000 | TL1 0000 0000 | TH0 0000 0000 | TH1 0000 0000 | CKRL 0000 1000 | POWM 0XXX XXXX | 8Fh |
| 80h | P0 1111 1111 | SP ⁽¹⁾ 0000 0111 | DPL ⁽¹⁾ 0000 0000 | DPH ⁽¹⁾ 0000 0000 | DPXL ⁽¹⁾ 0000 0001 | | | PCON 0000 0000 | 87h |
| | 0/8 | 1/9 | 2/A | 3/B | 4/C | 5/D | 6/E | 7/F | |

 Reserved

- Notes:
1. These registers are described in the TSC80251 Programmer's Guide (C251 core registers).
 2. In TWI and SPI modes, SSCON is splitted in two separate registers. SSCON reset value is 0000 0000 in TWI mode and 0000 0100 in SPI mode.
 3. In read and write modes, SSCS is splitted in two separate registers. SSCS reset value is 1111 1000 in read mode and 0000 0000 in write mode.

Configuration Bytes

The TSC80251G2D derivatives provide user design flexibility by configuring certain operating features at device reset. These features fall into the following categories:

- external memory interface (Page mode, address bits, programmed wait states and the address range for RD#, WR#, and PSEN#)
- source mode/binary mode opcodes
- selection of bytes stored on the stack by an interrupt
- mapping of the upper portion of on-chip code memory to region 00:

Two user configuration bytes UCONFIG0 (see Table 11) and UCONFIG1 (see Table 12) provide the information.

When EA# is tied to a low level, the configuration bytes are fetched from the external address space. The TSC80251G2D derivatives reserve the top eight bytes of the memory address space (FF:FFF8h-FF:FFFFh) for an external 8-byte configuration array. Only two bytes are actually used: UCONFIG0 at FF:FFF8h and UCONFIG1 at FF:FFF9h.

For the mask ROM devices, configuration information is stored in on-chip memory (see ROM Verifying). When EA# is tied to a high level, the configuration information is retrieved from the on-chip memory instead of the external address space and there is no restriction in the usage of the external memory.

Table 11. Configuration Byte 0
UCONFIG0

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | | | | | | | | | | | | | |
|------------|--------------|---|-------|-----|-----|-------|-----|-------|-------|-----------------------|---|---|---|---|---|---|---|---|---|---|---|---|
| - | WSA1# | WSA0# | XALE# | RD1 | RD0 | PAGE# | SRC | | | | | | | | | | | | | | | |
| Bit Number | Bit Mnemonic | Description | | | | | | | | | | | | | | | | | | | | |
| 7 | - | Reserved Set this bit when writing to UCONFIG0. | | | | | | | | | | | | | | | | | | | | |
| 6 | WSA1# | Wait State A bits Select the number of wait states for RD#, WR# and PSEN# signals for external memory accesses (all regions except 01:). | | | | | | | | | | | | | | | | | | | | |
| 5 | WSA0# | <table border="1"> <thead> <tr> <th>WSA1#</th> <th>WSA0#</th> <th>Number of Wait States</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>3</td> </tr> <tr> <td>0</td> <td>1</td> <td>2</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> </tr> </tbody> </table> | | | | | | WSA1# | WSA0# | Number of Wait States | 0 | 0 | 3 | 0 | 1 | 2 | 1 | 0 | 1 | 1 | 1 | 0 |
| WSA1# | WSA0# | Number of Wait States | | | | | | | | | | | | | | | | | | | | |
| 0 | 0 | 3 | | | | | | | | | | | | | | | | | | | | |
| 0 | 1 | 2 | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | 1 | | | | | | | | | | | | | | | | | | | | |
| 1 | 1 | 0 | | | | | | | | | | | | | | | | | | | | |
| 4 | XALE# | Extend ALE bit Clear to extend the duration of the ALE pulse from T_{osc} to $3 \cdot T_{osc}$. Set to minimize the duration of the ALE pulse to $1 \cdot T_{osc}$. | | | | | | | | | | | | | | | | | | | | |
| 3 | RD1 | Memory Signal Select bits Specify a 18-bit, 17-bit or 16-bit external address bus and the usage of RD#, WR# and PSEN# signals (see Table 13). | | | | | | | | | | | | | | | | | | | | |
| 2 | RD0 | | | | | | | | | | | | | | | | | | | | | |
| 1 | PAGE# | Page Mode Select bit⁽¹⁾ Clear to select the faster Page mode with A15:8/D7:0 on Port 2 and A7:0 on Port 0. Set to select the non-Page mode ⁽²⁾ with A15:8 on Port 2 and A7:0/D7:0 on Port 0. | | | | | | | | | | | | | | | | | | | | |
| 0 | SRC | Source Mode/Binary Mode Select bit Clear to select the binary mode. Set to select the source mode. | | | | | | | | | | | | | | | | | | | | |

- Notes:
1. UCONFIG0 is fetched twice so it can be properly read both in Page or Non-Page modes. If P2.1 is cleared during the first data fetch, a Page mode configuration is used, otherwise the subsequent fetches are performed in Non-Page mode.
 2. This selection provides compatibility with the standard 80C51 hardware which is multiplexing the address LSB and the data on Port 0.

Table 12. Configuration Byte 1
UCONFIG1

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | | | | | | | | | | | | | | | |
|------------|----------------------------|--|------|-----|-------|-------|-------|-----------------------|-------|-----------------------|---|---|---|---|---|---|---|---|---|---|---|---|
| CSIZE | - | - | INTR | WSB | WSB1# | WSB0# | EMAP# | | | | | | | | | | | | | | | |
| Bit Number | Bit Mnemonic | Description | | | | | | | | | | | | | | | | | | | | |
| 7 | CSIZE TSC87251G2D | On-Chip Code Memory Size bit⁽¹⁾ Clear to select 16 KB of on-chip code memory (TSC87251G1D product). Set to select 32 KB of on-chip code memory (TSC87251G2D product). | | | | | | | | | | | | | | | | | | | | |
| | TSC80251G2D TSC83251G2D | Reserved Set this bit when writing to UCONFIG1. | | | | | | | | | | | | | | | | | | | | |
| 6 | - | Reserved Set this bit when writing to UCONFIG1. | | | | | | | | | | | | | | | | | | | | |
| 5 | - | Reserved Set this bit when writing to UCONFIG1. | | | | | | | | | | | | | | | | | | | | |
| 4 | INTR | Interrupt Mode bit⁽²⁾ Clear so that the interrupts push two bytes onto the stack (the two lower bytes of the PC register). Set so that the interrupts push four bytes onto the stack (the three bytes of the PC register and the PSW1 register). | | | | | | | | | | | | | | | | | | | | |
| 3 | WSB | Wait State B bit⁽³⁾ Clear to generate one wait state for memory region 01:. Set for no wait states for memory region 01:. | | | | | | | | | | | | | | | | | | | | |
| 2 | WSB1# | Wait State B bits Select the number of wait states for RD#, WR# and PSEN# signals for external memory accesses (only region 01:). <table border="1"> <thead> <tr> <th>WSB1#</th> <th>WSB0#</th> <th>Number of Wait States</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>3</td> </tr> <tr> <td>0</td> <td>1</td> <td>2</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> </tr> </tbody> </table> | | | | | | WSB1# | WSB0# | Number of Wait States | 0 | 0 | 3 | 0 | 1 | 2 | 1 | 0 | 1 | 1 | 1 | 0 |
| WSB1# | WSB0# | | | | | | | Number of Wait States | | | | | | | | | | | | | | |
| 0 | 0 | 3 | | | | | | | | | | | | | | | | | | | | |
| 0 | 1 | 2 | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | 1 | | | | | | | | | | | | | | | | | | | | |
| 1 | 1 | 0 | | | | | | | | | | | | | | | | | | | | |
| 1 | WSB0# | | | | | | | | | | | | | | | | | | | | | |
| 0 | EMAP# | On-Chip Code Memory Map bit Clear to map the upper 16 KB of on-chip code memory (at FF:4000h-FF:7FFFh) to the data space (at 00:C000h-00:FFFFh). Set not to map the upper 16 KB of on-chip code memory (at FF:4000h-FF:7FFFh) to the data space. | | | | | | | | | | | | | | | | | | | | |

- Notes:
1. The CSIZE is only available on EPROM/OTPROM products.
 2. Two or four bytes are transparently popped according to INTR when using the RETI instruction. INTR must be set if interrupts are used with code executing outside region FF:.
 3. Use only for Step A compatibility; set this bit when WSB1:0# are used.

Configuration Byte 1

Table 13. Address Ranges and Usage of RD#, WR# and PSEN# Signals

| RD1 | RD0 | P1.7 | P3.7/RD# | PSEN# | WR# | External Memory |
|-----|-----|---------|-------------------------------------|---|--|--------------------------|
| 0 | 0 | A17 | A16 | Read signal for all external memory locations | Write signal for all external memory locations | 256 KB |
| 0 | 1 | I/O pin | A16 | Read signal for all external memory locations | Write signal for all external memory locations | 128 KB |
| 1 | 0 | I/O pin | I/O pin | Read signal for all external memory locations | Write signal for all external memory locations | 64 KB |
| 1 | 1 | I/O pin | Read signal for regions 00: and 01: | Read signal for regions FE: and FF: | Write signal for all external memory locations | 2 × 64 KB ⁽¹⁾ |

Notes: 1. This selection provides compatibility with the standard 80C51 hardware which has separate external memory spaces for data and code.

Instruction Set Summary

This section contains tables that summarize the instruction set. For each instruction there is a short description, its length in bytes, and its execution time in states (one state time is equal to two system clock cycles). There are two concurrent processes limiting the effective instruction throughput:

- Instruction Fetch
- Instruction Execution

Table 20 to Table 32 assume code executing from on-chip memory, then the CPU is fetching 16-bit at a time and this is never limiting the execution speed.

If the code is fetched from external memory, a pre-fetch queue will store instructions ahead of execution to optimize the memory bandwidth usage when slower instructions are executed. However, the effective speed may be limited depending on the average size of instructions (for the considered section of the program flow). The maximum average instruction throughput is provided by Table 14 depending on the external memory configuration (from Page Mode to Non-Page Mode and the maximum number of wait states). If the average size of instructions is not an integer, the maximum effective throughput is found by pondering the number of states for the neighbor integer values.

Table 14. Minimum Number of States per Instruction for given Average Sizes

| Average size of Instructions (bytes) | Page Mode (states) | Non-page Mode (states) | | | | |
|--------------------------------------|--------------------|------------------------|--------------|---------------|---------------|---------------|
| | | 0 Wait State | 1 Wait State | 2 Wait States | 3 Wait States | 4 Wait States |
| 1 | 1 | 2 | 3 | 4 | 5 | 6 |
| 2 | 2 | 4 | 6 | 8 | 10 | 12 |
| 3 | 3 | 6 | 9 | 12 | 15 | 18 |
| 4 | 4 | 8 | 12 | 16 | 20 | 24 |
| 5 | 5 | 10 | 15 | 20 | 25 | 30 |

If the average execution time of the considered instructions is larger than the number of states given by Table 14, this larger value will prevail as the limiting factor. Otherwise, the value from Table 14 must be taken. This is providing a fair estimation of the execution speed but only the actual code execution can provide the final value.

Notation for Instruction Operands

Table 15 to Table 19 provide notation for Instruction Operands.

Table 15. Notation for Direct Addressing

| Direct Address | Description | C251 | C51 |
|----------------|--|------|-----|
| dir8 | A direct 8-bit address. This can be a memory address (00h-7Fh) or a SFR address (80h-FFh). It is a byte (default), word or double word depending on the other operand. | 3 | 3 |
| dir16 | A 16-bit memory address (00:0000h-00:FFFFh) used in direct addressing. | 3 | – |

Table 16. Notation for Immediate Addressing

| Immediate Address | Description | C251 | C51 |
|----------------------|---|------|-----|
| #data | An 8-bit constant that is immediately addressed in an instruction | 3 | 3 |
| #data16 | A 16-bit constant that is immediately addressed in an instruction | 3 | – |
| #0data16 #1data16 | A 32-bit constant that is immediately addressed in an instruction. The upper word is filled with zeros (#0data16) or ones (#1data16). | 3 | – |
| #short | A constant, equal to 1, 2, or 4, that is immediately addressed in an instruction. | 3 | – |

Table 17. Notation for Bit Addressing

| Direct Address | Description | C251 | C51 |
|----------------|---|------|-----|
| bit51 | A directly addressed bit (bit number = 00h-FFh) in memory or an SFR. Bits 00h-7Fh are the 128 bits in byte locations 20h-2Fh in the on-chip RAM. Bits 80h-FFh are the 128 bits in the 16 SFRs with addresses that end in 0h or 8h, S:80h, S:88h, S:90h,..., S:F0h, S:F8h. | – | 3 |
| bit | A directly addressed bit in memory locations 00:0020h-00:007Fh or in any defined SFR. | 3 | |

Table 18. Notation for Destination in Control Instructions

| Direct Address | Description | C251 | C51 |
|----------------|--|------|-----|
| rel | A signed (two's complement) 8-bit relative address. The destination is -128 to +127 bytes relative to the next instruction's first byte. | 3 | 3 |
| addr11 | An 11-bit target address. The target is in the same 2-Kbyte block of memory as the next instruction's first byte. | – | 3 |
| addr16 | A 16-bit target address. The target can be anywhere within the same 64-Kbyte region as the next instruction's first byte. | – | 3 |
| addr24 | A 24-bit target address. The target can be anywhere within the 16-Mbyte address space. | 3 | – |

Table 19. Notation for Register Operands

| Register | Description | C251 | C51 |
|---|--|------|-----|
| at Ri | A memory location (00h-FFh) addressed indirectly via byte registers R0 or R1 | – | 3 |
| Rn n | Byte register R0-R7 of the currently selected register bank Byte register index: n = 0-7 | – | 3 |
| Rm Rmd Rms m, md, ms | Byte register R0-R15 of the currently selected register file Destination register Source register Byte register index: m, md, ms = 0-15 | 3 | – |
| WRj WRjd WRjs at WRj at WRj +dis16 j, jd, js | Word register WR0, WR2, ..., WR30 of the currently selected register file Destination register Source register A memory location (00:0000h-00:FFFFh) addressed indirectly through word register WR0-WR30, is the target address for jump instructions. A memory location (00:0000h-00:FFFFh) addressed indirectly through word register (WR0-WR30) + 16-bit signed (two's complement) displacement value Word register index: j, jd, js = 0-30 | 3 | – |
| DRk DRkd DRks at DRk at DRk +dis16 k, kd, ks | Dword register DR0, DR4, ..., DR28, DR56, DR60 of the currently selected register file Destination register Source register A memory location (00:0000h-FF:FFFFh) addressed indirectly through dword register DR0-DR28, DR56 and DR60, is the target address for jump instruction A memory location (00:0000h-FF:FFFFh) addressed indirectly through dword register (DR0-DR28, DR56, DR60) + 16-bit (two's complement) signed displacement value Dword register index: k, kd, ks = 0, 4, 8..., 28, 56, 60 | 3 | – |

Size and Execution Time for Instruction Families

Table 20. Summary of Add and Subtract Instructions

| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
|---------------|------------------------------|--|---|------------------|-------------|------------------|
| | | | Bytes | States | Bytes | States |
| | | | Add ADD <dest>, <src>dest opnd ← dest opnd + src opnd Subtract SUB <dest>, <src>dest opnd ← dest opnd - src opnd Add with Carry ADDC <dest>, <src>(A) ← (A) + src opnd + (CY) Subtract with Borrow SUBB <dest>, <src>(A) ← (A) - src opnd - (CY) | | | |
| ADD | A, Rn | Register to ACC | 1 | 1 | 2 | 2 |
| | A, dir8 | Direct address to ACC | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | A, at Ri | Indirect address to ACC | 1 | 2 | 2 | 3 |
| | A, #data | Immediate data to ACC | 2 | 1 | 2 | 1 |
| ADD/SUB | Rmd, Rms | Byte register to/from byte register | 3 | 2 | 2 | 1 |
| | WRjd, WRjs | Word register to/from word register | 3 | 3 | 2 | 2 |
| | DRkd, DRks | Dword register to/from dword register | 3 | 5 | 2 | 4 |
| | Rm, #data | Immediate 8-bit data to/from byte register | 4 | 3 | 3 | 2 |
| | WRj, #data16 | Immediate 16-bit data to/from word register | 5 | 4 | 4 | 3 |
| | DRk, #0data16 | 16-bit unsigned immediate data to/from dword register | 5 | 6 | 4 | 5 |
| | Rm, dir8 | Direct address (on-chip RAM or SFR) to/from byte register | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| | WRj, dir8 | Direct address (on-chip RAM or SFR) to/from word register | 4 | 4 | 3 | 3 |
| | Rm, dir16 | Direct address (64K) to/from byte register | 5 | 3 ⁽³⁾ | 4 | 2 ⁽³⁾ |
| | WRj, dir16 | Direct address (64K) to/from word register | 5 | 4 ⁽⁴⁾ | 4 | 3 ⁽⁴⁾ |
| | Rm, at WRj | Indirect address (64K) to/from byte register | 4 | 3 ⁽³⁾ | 3 | 2 ⁽³⁾ |
| | Rm, at DRk | Indirect address (16M) to/from byte register | 4 | 4 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| ADDC/SU BB | A, Rn | Register to/from ACC with carry | 1 | 1 | 2 | 2 |
| | A, dir8 | Direct address (on-chip RAM or SFR) to/from ACC with carry | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | A, at Ri | Indirect address to/from ACC with carry | 1 | 2 | 2 | 3 |
| | A, #data | Immediate data to/from ACC with carry | 2 | 1 | 2 | 1 |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 3. If this instruction addresses external memory location, add N+2 to the number of states (N: number of wait states).

- If this instruction addresses external memory location, add 2(N+2) to the number of states (N: number of wait states).

Table 21. Summary of Increment and Decrement Instructions

| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
|--|------------------------------|--|-------------|------------------|-------------|------------------|
| | | | Bytes | States | Bytes | States |
| Increment INC <dest> dest opnd ← dest opnd + 1 | | | | | | |
| Increment INC <dest>, <src> dest opnd ← dest opnd + src opnd | | | | | | |
| Decrement DEC <dest> dest opnd ← dest opnd - 1 | | | | | | |
| Decrement DEC <dest>, <src> dest opnd ← dest opnd - src opnd | | | | | | |
| INC DEC | A | ACC by 1 | 1 | 1 | 1 | 1 |
| | Rn | Register by 1 | 1 | 1 | 2 | 2 |
| | dir8 | Direct address (on-chip RAM or SFR) by 1 | 2 | 2 ⁽²⁾ | 2 | 2 ⁽²⁾ |
| | at Ri | Indirect address by 1 | 1 | 3 | 2 | 4 |
| INC DEC | Rm, #short | Byte register by 1, 2, or 4 | 3 | 2 | 2 | 1 |
| | WRj, #short | Word register by 1, 2, or 4 | 3 | 2 | 2 | 1 |
| INC | DRk, #short | Double word register by 1, 2, or 4 | 3 | 4 | 2 | 3 |
| DEC | DRk, #short | Double word register by 1, 2, or 4 | 3 | 5 | 2 | 4 |
| INC | DPTR | Data pointer by 1 | 1 | 1 | 1 | 1 |

- Notes:
- A shaded cell denotes an instruction in the C51 Architecture.
 - If this instruction addresses an I/O Port (Px, x = 0-3), add 2 to the number of states. Add 3 if it addresses a Peripheral SFR.

Table 22. Summary of Compare Instructions

| CompareCMP <dest>, <src>dest opnd - src opnd | | | | | | |
|--|------------------------------|---|-------------|------------------|-------------|------------------|
| Mnemonic | <dest>, <src> ⁽²⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| CMP | Rmd, Rms | Register with register | 3 | 2 | 2 | 1 |
| | WRjd, WRjs | Word register with word register | 3 | 3 | 2 | 2 |
| | DRkd, DRks | Dword register with dword register | 3 | 5 | 2 | 4 |
| | Rm, #data | Register with immediate data | 4 | 3 | 3 | 2 |
| | WRj, #data16 | Word register with immediate 16-bit data | 5 | 4 | 4 | 3 |
| | DRk, #0data16 | Dword register with zero-extended 16-bit immediate data | 5 | 6 | 4 | 5 |
| | DRk, #1data16 | Dword register with one-extended 16-bit immediate data | 5 | 6 | 4 | 5 |
| | Rm, dir8 | Direct address (on-chip RAM or SFR) with byte register | 4 | 3 ⁽¹⁾ | 3 | 2 ⁽¹⁾ |
| | WRj, dir8 | Direct address (on-chip RAM or SFR) with word register | 4 | 4 | 3 | 3 |
| | Rm, dir16 | Direct address (64K) with byte register | 5 | 3 ⁽²⁾ | 4 | 2 ⁽²⁾ |
| | WRj, dir16 | Direct address (64K) with word register | 5 | 4 ⁽³⁾ | 4 | 3 ⁽³⁾ |
| | Rm, at WRj | Indirect address (64K) with byte register | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| | Rm, at DRk | Indirect address (16M) with byte register | 4 | 4 ⁽²⁾ | 3 | 3 ⁽²⁾ |

- Notes:
1. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 2. If this instruction addresses external memory location, add N+2 to the number of states (N: number of wait states).
 3. If this instruction addresses external memory location, add 2(N+2) to the number of states (N: number of wait states).

Logical AND⁽¹⁾ANL <dest>, <src>dest opnd ← dest opnd ∧ src opnd
 Logical OR⁽¹⁾ORL <dest>, <src>dest opnd ← dest opnd ∨ src opnd
 Logical Exclusive OR⁽¹⁾XRL <dest>, <src>dest opnd ← dest opnd ⊕ src opnd
 Clear⁽¹⁾CLR A(A) ← 0
 Complement⁽¹⁾CPL A(A) ← \overline{A}
 Rotate LeftRL A(A)_{n+1} ← (A)_n, n = 0..6
 (A)₀ ← (A)₇
 Rotate Left CarryRLC A(A)_{n+1} ← (A)_n, n = 0..6
 (CY) ← (A)₇
 (A)₀ ← (CY)
 Rotate RightRR A(A)_{n-1} ← (A)_n, n = 7..1
 (A)₇ ← (A)₀
 Rotate Right CarryRRC A(A)_{n-1} ← (A)_n, n = 7..1
 (CY) ← (A)₀
 (A)₇ ← (CY)

| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
|-------------------|------------------------------|--|-------------|------------------|-------------|------------------|
| | | | Bytes | States | Bytes | States |
| ANL ORL XRL | A, Rn | register to ACC | 1 | 1 | 2 | 2 |
| | A, dir8 | Direct address (on-chip RAM or SFR) to ACC | 2 | 1 ⁽³⁾ | 2 | 1 ⁽³⁾ |
| | A, at Ri | Indirect address to ACC | 1 | 2 | 2 | 3 |
| | A, #data | Immediate data to ACC | 2 | 1 | 2 | 1 |
| | dir8, A | ACC to direct address | 2 | 2 ⁽⁴⁾ | 2 | 2 ⁽⁴⁾ |
| | dir8, #data | Immediate 8-bit data to direct address | 3 | 3 ⁽⁴⁾ | 3 | 3 ⁽⁴⁾ |
| | Rmd, Rms | Byte register to byte register | 3 | 2 | 2 | 1 |
| | WRjd, WRjs | Word register to word register | 3 | 3 | 2 | 2 |
| | Rm, #data | Immediate 8-bit data to byte register | 4 | 3 | 3 | 2 |
| | WRj, #data16 | Immediate 16-bit data to word register | 5 | 4 | 4 | 3 |
| | Rm, dir8 | Direct address (on-chip RAM or SFR) to byte register | 4 | 3 ⁽³⁾ | 3 | 2 ⁽³⁾ |
| | WRj, dir8 | Direct address (on-chip RAM or SFR) to word register | 4 | 4 | 3 | 3 |
| | Rm, dir16 | Direct address (64K) to byte register | 5 | 3 ⁽⁵⁾ | 4 | 2 ⁽⁵⁾ |
| | WRj, dir16 | Direct address (64K) to word register | 5 | 4 ⁽⁶⁾ | 4 | 3 ⁽⁶⁾ |
| | Rm, at WRj | Indirect address (64K) to byte register | 4 | 3 ⁽⁵⁾ | 3 | 2 ⁽⁵⁾ |
| | Rm, at DRk | Indirect address (16M) to byte register | 4 | 4 ⁽⁵⁾ | 3 | 3 ⁽⁵⁾ |
| CLR | A | Clear ACC | 1 | 1 | 1 | 1 |
| CPL | A | Complement ACC | 1 | 1 | 1 | 1 |
| RL | A | Rotate ACC left | 1 | 1 | 1 | 1 |
| RLC | A | Rotate ACC left through CY | 1 | 1 | 1 | 1 |
| RR | A | Rotate ACC right | 1 | 1 | 1 | 1 |
| RRC | A | Rotate ACC right through CY | 1 | 1 | 1 | 1 |

- Notes:
1. Logical instructions that affect a bit are in Table 27.
 2. A shaded cell denotes an instruction in the C51 Architecture.
 3. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 4. If this instruction addresses an I/O Port (Px, x = 0-3), add 2 to the number of states. Add 3 if it addresses a Peripheral SFR.
 5. If this instruction addresses external memory location, add N+2 to the number of states (N: number of wait states).
 6. If this instruction addresses external memory location, add 2(N+2) to the number of states (N: number of wait states).

Table 23. Summary of Logical Instructions (2/2)

| Shift Left LogicalSLL <dest><dest> ₀ ← 0 <dest> _{n+1} ← <dest> _n , n = 0..msb-1 (CY) ← <dest> _{msb} Shift Right ArithmeticSRA <dest><dest> _{msb} ← <dest> _{msb} <dest> _{n-1} ← <dest> _n , n = msb..1 (CY) ← <dest> ₀ Shift Right LogicalSRL <dest><dest> _{msb} ← 0 <dest> _{n-1} ← <dest> _n , n = msb..1 (CY) ← <dest> ₀ SwapSWAP AA _{3:0} A _{7:4} | | | | | | |
|---|------------------------------|--|-------------|--------|-------------|--------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| SLL | Rm | Shift byte register left through the MSB | 3 | 2 | 2 | 1 |
| | WRj | Shift word register left through the MSB | 3 | 2 | 2 | 1 |
| SRA | Rm | Shift byte register right | 3 | 2 | 2 | 1 |
| | WRj | Shift word register right | 3 | 2 | 2 | 1 |
| SRL | Rm | Shift byte register left | 3 | 2 | 2 | 1 |
| | WRj | Shift word register left | 3 | 2 | 2 | 1 |
| SWAP | A | Swap nibbles within ACC | 1 | 2 | 1 | 2 |

Note: 1. A shaded cell denotes an instruction in the C51 Architecture.

Table 24. Summary of Multiply, Divide and Decimal-adjust Instructions

| Multiply MUL AB(B:A) ← (A)×(B) MUL <dest>, <src>extended dest opnd ← dest opnd × src opnd Divide DIV AB(A) ← Quotient ((A)/(B)) (B) ← Remainder ((A)/(B)) Divide DIV <dest>, <src>ext. dest opnd high ← Quotient (dest opnd /src opnd) ext. dest opnd low ← Remainder (dest opnd /src opnd) Decimal-adjust ACCDA AIF [[(A) _{3:0} > 9] ∨ [(AC) = 1]] for Addition (BCD) THEN (A) _{3:0} ← (A) _{3:0} + 6 !affects CY; IF [[(A) _{7:4} > 9] ∨ [(CY) = 1]] THEN (A) _{7:4} ← (A) _{7:4} + 6 | | | | | | |
|--|------------------------------|--|-------------|--------|-------------|--------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| MUL | AB | Multiply A and B | 1 | 5 | 1 | 5 |
| | Rmd, Rms | Multiply byte register and byte register | 3 | 6 | 2 | 5 |
| | WRjd, WRjs | Multiply word register and word register | 3 | 12 | 2 | 11 |
| DIV | AB | Divide A and B | 1 | 10 | 1 | 10 |
| | Rmd, Rms | Divide byte register and byte register | 3 | 11 | 2 | 10 |
| | WRjd, WRjs | Divide word register and word register | 3 | 21 | 2 | 20 |
| DA | A | Decimal adjust ACC | 1 | 1 | 1 | 1 |

Note: 1. A shaded cell denotes an instruction in the C51 Architecture.

Table 25. Summary of Move Instructions (1/3)

| Move to High wordMOVH <dest>, <src>dest opnd _{31:16} ← src opnd Move with Sign extensionMOVS <dest>, <src>dest opnd ← src opnd with sign extend Move with Zero extensionMOVZ <dest>, <src>dest opnd ← src opnd with zero extend Move CodeMOVC A, <src>(A) ← src opnd Move eXtendedMOVX <dest>, <src>dest opnd ← src opnd | | | | | | |
|---|------------------------------|---|-------------|------------------|-------------|------------------|
| Mnemonic | <dest>, <src> ⁽²⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| MOVH | DRk, #data16 | 16-bit immediate data into upper word of dword register | 5 | 3 | 4 | 2 |
| MOVS | WRj, Rm | Byte register to word register with sign extension | 3 | 2 | 2 | 1 |
| MOVZ | WRj, Rm | Byte register to word register with zeros extension | 3 | 2 | 2 | 1 |
| MOVC | A, at A +DPTR | Code byte relative to DPTR to ACC | 1 | 6 ⁽³⁾ | 1 | 6 ⁽³⁾ |
| | A, at A +PC | Code byte relative to PC to ACC | 1 | 6 ⁽³⁾ | 1 | 6 ⁽³⁾ |
| MOVX | A, at Ri | Extended memory (8-bit address) to ACC ⁽²⁾ | 1 | 4 | 1 | 5 |
| | A, at DPTR | Extended memory (16-bit address) to ACC ⁽²⁾ | 1 | 3 ⁽⁴⁾ | 1 | 3 ⁽⁴⁾ |
| | at Ri, A | ACC to extended memory (8-bit address) ⁽²⁾ | 1 | 4 | 1 | 4 |
| | at DPTR, A | ACC to extended memory (16-bit address) ⁽²⁾ | 1 | 4 ⁽³⁾ | 1 | 4 ⁽³⁾ |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. Extended memory addressed is in the region specified by DPXL (reset value = 01h).
 3. If this instruction addresses external memory location, add N+1 to the number of states (N: number of wait states).
 4. If this instruction addresses external memory location, add N+2 to the number of states (N: number of wait states).

Table 26. Summary of Move Instructions (2/3)

| Move ⁽¹⁾ MOV <dest>, <src>dest opnd ← src opnd | | | | | | |
|---|--|---|-------------|------------------|-------------|------------------|
| Mnemonic | <dest>, <src> ⁽²⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| MOV | A, Rn | Register to ACC | 1 | 1 | 2 | 2 |
| | A, dir8 | Direct address (on-chip RAM or SFR) to ACC | 2 | 1 ⁽³⁾ | 2 | 1 ⁽³⁾ |
| | A, at Ri | Indirect address to ACC | 1 | 2 | 2 | 3 |
| | A, #data | Immediate data to ACC | 2 | 1 | 2 | 1 |
| | Rn, A | ACC to register | 1 | 1 | 2 | 2 |
| | Rn, dir8 | Direct address (on-chip RAM or SFR) to register | 2 | 1 ⁽³⁾ | 3 | 2 ⁽³⁾ |
| | Rn, #data | Immediate data to register | 2 | 1 | 3 | 2 |
| | dir8, A | ACC to direct address (on-chip RAM or SFR) | 2 | 2 ⁽³⁾ | 2 | 2 ⁽³⁾ |
| | dir8, Rn | Register to direct address (on-chip RAM or SFR) | 2 | 2 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| | dir8, dir8 | Direct address to direct address (on-chip RAM or SFR) | 3 | 3 ⁽⁴⁾ | 3 | 3 ⁽⁴⁾ |
| | dir8, at Ri | Indirect address to direct address (on-chip RAM or SFR) | 2 | 3 ⁽³⁾ | 3 | 4 ⁽³⁾ |
| | dir8, #data | Immediate data to direct address (on-chip RAM or SFR) | 3 | 3 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| | at Ri, A | ACC to indirect address | 1 | 3 | 2 | 4 |
| | at Ri, dir8 | Direct address (on-chip RAM or SFR) to indirect address | 2 | 3 ⁽³⁾ | 3 | 4 ⁽³⁾ |
| | at Ri, #data | Immediate data to indirect address | 2 | 3 | 3 | 4 |
| DPTR, #data16 | Load Data Pointer with a 16-bit constant | 3 | 2 | 3 | 2 | |

- Notes:
1. Instructions that move bits are in Table 27.
 2. Move instructions from the C51 Architecture.
 3. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 4. Apply note 3 for each dir8 operand.

| Move ⁽¹⁾ MOV <dest>, <src>dest opnd ← src opnd | | | | | | |
|---|------------------------------|--|-------------|------------------|-------------|------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| MOV | Rmd, Rms | Byte register to byte register | 3 | 2 | 2 | 1 |
| MOV | WRjd, WRjs | Word register to word register | 3 | 2 | 2 | 1 |
| MOV | DRkd, DRks | Dword register to dword register | 3 | 3 | 2 | 2 |
| MOV | Rm, #data | Immediate 8-bit data to byte register | 4 | 3 | 3 | 2 |
| MOV | WRj, #data16 | Immediate 16-bit data to word register | 5 | 3 | 4 | 2 |
| MOV | DRk, #0data16 | zero-ext 16bit immediate data to dword register | 5 | 5 | 4 | 4 |
| MOV | DRk, #1data16 | one-ext 16bit immediate data to dword register | 5 | 5 | 4 | 4 |
| MOV | Rm, dir8 | Direct address (on-chip RAM or SFR) to byte register | 4 | 3 ⁽³⁾ | 3 | 2 ⁽³⁾ |
| MOV | WRj, dir8 | Direct address (on-chip RAM or SFR) to word register | 4 | 4 | 3 | 3 |
| MOV | DRk, dir8 | Direct address (on-chip RAM or SFR) to dword register | 4 | 6 | 3 | 5 |
| MOV | Rm, dir16 | Direct address (64K) to byte register | 5 | 3 ⁽⁴⁾ | 4 | 2 ⁽⁴⁾ |
| MOV | WRj, dir16 | Direct address (64K) to word register | 5 | 4 ⁽⁵⁾ | 4 | 3 ⁽⁵⁾ |
| MOV | DRk, dir16 | Direct address (64K) to dword register | 5 | 6 ⁽⁶⁾ | 4 | 5 ⁽⁶⁾ |
| MOV | Rm, at WRj | Indirect address (64K) to byte register | 4 | 3 ⁽⁴⁾ | 3 | 2 ⁽⁴⁾ |
| MOV | Rm, at DRk | Indirect address (16M) to byte register | 4 | 4 ⁽⁴⁾ | 3 | 3 ⁽⁴⁾ |
| MOV | WRjd, at WRjs | Indirect address (64K) to word register | 4 | 4 ⁽⁵⁾ | 3 | 3 ⁽⁵⁾ |
| MOV | WRj, at DRk | Indirect address (16M) to word register | 4 | 5 ⁽⁵⁾ | 3 | 4 ⁽⁵⁾ |
| MOV | dir8, Rm | Byte register to direct address (on-chip RAM or SFR) | 4 | 4 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| MOV | dir8, WRj | Word register to direct address (on-chip RAM or SFR) | 4 | 5 | 3 | 4 |
| MOV | dir8, DRk | Dword register to direct address (on-chip RAM or SFR) | 4 | 7 | 3 | 6 |
| MOV | dir16, Rm | Byte register to direct address (64K) | 5 | 4 ⁽⁴⁾ | 4 | 3 ⁽⁴⁾ |
| MOV | dir16, WRj | Word register to direct address (64K) | 5 | 5 ⁽⁵⁾ | 4 | 4 ⁽⁵⁾ |
| MOV | dir16, DRk | Dword register to direct address (64K) | 5 | 7 ⁽⁶⁾ | 4 | 6 ⁽⁶⁾ |
| MOV | at WRj, Rm | Byte register to indirect address (64K) | 4 | 4 ⁽⁴⁾ | 3 | 3 ⁽⁴⁾ |
| MOV | at DRk, Rm | Byte register to indirect address (16M) | 4 | 5 ⁽⁴⁾ | 3 | 4 ⁽⁴⁾ |
| MOV | at WRjd, WRjs | Word register to indirect address (64K) | 4 | 5 ⁽⁵⁾ | 3 | 4 ⁽⁵⁾ |
| MOV | at DRk, WRj | Word register to indirect address (16M) | 4 | 6 ⁽⁵⁾ | 3 | 5 ⁽⁵⁾ |
| MOV | Rm, at WRj +dis16 | Indirect with 16-bit displacement (64K) to byte register | 5 | 6 ⁽⁴⁾ | 4 | 5 ⁽⁴⁾ |
| MOV | WRj, at WRj +dis16 | Indirect with 16-bit displacement (64K) to word register | 5 | 7 ⁽⁵⁾ | 4 | 6 ⁽⁵⁾ |
| MOV | Rm, at DRk +dis24 | Indirect with 16-bit displacement (16M) to byte register | 5 | 7 ⁽⁴⁾ | 4 | 6 ⁽⁴⁾ |

| | | | | | | |
|-----|--------------------|--|---|------------------|---|------------------|
| MOV | WRj, at WRj +dis24 | Indirect with 16-bit displacement (16M) to word register | 5 | 8 ⁽⁵⁾ | 4 | 7 ⁽⁵⁾ |
| MOV | at WRj +dis16, Rm | Byte register to indirect with 16-bit displacement (64K) | 5 | 6 ⁽⁴⁾ | 4 | 5 ⁽⁴⁾ |
| MOV | at WRj +dis16, WRj | Word register to indirect with 16-bit displacement (64K) | 5 | 7 ⁽⁵⁾ | 4 | 6 ⁽⁵⁾ |
| MOV | at DRk +dis24, Rm | Byte register to indirect with 16-bit displacement (16M) | 5 | 7 ⁽⁴⁾ | 4 | 6 ⁽⁴⁾ |
| MOV | at DRk +dis24, WRj | Word register to indirect with 16-bit displacement (16M) | 5 | 8 ⁽⁵⁾ | 4 | 7 ⁽⁵⁾ |

- Notes:
1. Instructions that move bits are in Table 27.
 2. Move instructions unique to the C251 Architecture.
 3. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 4. If this instruction addresses external memory location, add N+2 to the number of states (N: number of wait states).
 5. If this instruction addresses external memory location, add 2(N+1) to the number of states (N: number of wait states).
 6. If this instruction addresses external memory location, add 4(N+2) to the number of states (N: number of wait states).

Table 27. Summary of Bit Instructions

| Clear BitCLR <dest>dest opnd ← 0 Set BitSETB <dest>dest opnd ← 1 Complement BitCPL <dest>dest opnd ← ∅ bit AND Carry with BitANL CY, <src>(CY) ← (CY) ∧ src opnd AND Carry with Complement of BitANL CY, /<src>(CY) ← (CY) ∧ ∅ src opnd OR Carry with BitORL CY, <src>(CY) ← (CY) ∨ src opnd OR Carry with Complement of BitORL CY, /<src>(CY) ← (CY) ∨ ∅ src opnd Move Bit to CarryMOV CY, <src>(CY) ← src opnd Move Bit from CarryMOV <dest>, CYdest opnd ← (CY) | | | | | | |
|--|------------------------------|--------------------------------------|-------------|------------------|-------------|------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| CLR | CY | Clear carry | 1 | 1 | 1 | 1 |
| | bit51 | Clear direct bit | 2 | 2 ⁽³⁾ | 2 | 2 ⁽³⁾ |
| | bit | Clear direct bit | 4 | 4 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| SETB | CY | Set carry | 1 | 1 | 1 | 1 |
| | bit51 | Set direct bit | 2 | 2 ⁽³⁾ | 2 | 2 ⁽³⁾ |
| | bit | Set direct bit | 4 | 4 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| CPL | CY | Complement carry | 1 | 1 | 1 | 1 |
| | bit51 | Complement direct bit | 2 | 2 ⁽³⁾ | 2 | 2 ⁽³⁾ |
| | bit | Complement direct bit | 4 | 4 ⁽³⁾ | 3 | 3 ⁽³⁾ |
| ANL | CY, bit51 | And direct bit to carry | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | CY, bit | And direct bit to carry | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| | CY, /bit51 | And complemented direct bit to carry | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | CY, /bit | And complemented direct bit to carry | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| ORL | CY, bit51 | Or direct bit to carry | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | CY, bit | Or direct bit to carry | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| | CY, /bit51 | Or complemented direct bit to carry | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | CY, /bit | Or complemented direct bit to carry | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| MOV | CY, bit51 | Move direct bit to carry | 2 | 1 ⁽²⁾ | 2 | 1 ⁽²⁾ |
| | CY, bit | Move direct bit to carry | 4 | 3 ⁽²⁾ | 3 | 2 ⁽²⁾ |
| | bit51, CY | Move carry to direct bit | 2 | 2 ⁽³⁾ | 2 | 2 ⁽³⁾ |
| | bit, CY | Move carry to direct bit | 4 | 4 ⁽³⁾ | 3 | 3 ⁽³⁾ |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 3. If this instruction addresses an I/O Port (Px, x = 0-3), add 2 to the number of states. Add 3 if it addresses a Peripheral SFR.

Table 28. Summary of Exchange, Push and Pop Instructions

| Exchange bytesXCH A, <src>(A) ↔ src opnd Exchange DigitXCHD A, <src>(A) _{3:0} ↔ src opnd _{3:0} PushPUSH <src>(SP) ← (SP) + 1; ((SP)) ← src opnd; (SP) ← (SP) + size (src opnd) - 1 PopPOP <dest>(SP) ← (SP) - size (dest opnd) + 1; dest opnd ← ((SP)); (SP) ← (SP) - 1 | | | | | | |
|--|------------------------------|--|-------------|------------------|-------------|------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| XCH | A, Rn | ACC and register | 1 | 3 | 2 | 4 |
| | A, dir8 | ACC and direct address (on-chip RAM or SFR) | 2 | 3 ⁽³⁾ | 2 | 3 ⁽³⁾ |
| | A, at Ri | ACC and indirect address | 1 | 4 | 2 | 5 |
| XCHD | A, at Ri | ACC low nibble and indirect address (256 bytes) | 1 | 4 | 2 | 5 |
| PUSH | dir8 | Push direct address onto stack | 2 | 2 ⁽²⁾ | 2 | 2 ⁽²⁾ |
| | #data | Push immediate data onto stack | 4 | 4 | 3 | 3 |
| | #data16 | Push 16-bit immediate data onto stack | 5 | 5 | 4 | 5 |
| | Rm | Push byte register onto stack | 3 | 4 | 2 | 3 |
| | WRj | Push word register onto stack | 3 | 5 | 2 | 4 |
| | DRk | Push double word register onto stack | 3 | 9 | 2 | 8 |
| POP | dir8 | Pop direct address (on-chip RAM or SFR) from stack | 2 | 3 ⁽²⁾ | 2 | 3 ⁽²⁾ |
| | Rm | Pop byte register from stack | 3 | 3 | 2 | 2 |
| | WRj | Pop word register from stack | 3 | 5 | 2 | 4 |
| | DRk | Pop double word register from stack | 3 | 9 | 2 | 8 |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 3. If this instruction addresses an I/O Port (Px, x = 0-3), add 2 to the number of states. Add 3 if it addresses a Peripheral SFR.

Table 29. Summary of Conditional Jump Instructions (1/2)

| Jump conditional on status: $Jcc\ rel(PC) \leftarrow (PC) + size\ (instr);$ IF [cc] THEN $(PC) \leftarrow (PC) + rel$ | | | | | | |
|--|------------------------------|--|-------------|--------------------|-------------|--------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| JC | rel | Jump if carry | 2 | 1/4 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JNC | rel | Jump if not carry | 2 | 1/4 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JE | rel | Jump if equal | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JNE | rel | Jump if not equal | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JG | rel | Jump if greater than | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JLE | rel | Jump if less than, or equal | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JSL | rel | Jump if less than (signed) | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JSLE | rel | Jump if less than, or equal (signed) | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JSG | rel | Jump if greater than (signed) | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |
| JSGE | rel | Jump if greater than or equal (signed) | 3 | 2/5 ⁽³⁾ | 2 | 1/4 ⁽³⁾ |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. States are given as jump not-taken/taken.
 3. In internal execution only, add 1 to the number of states of the 'jump taken' if the destination address is internal and odd.

Table 30. Summary of Conditional Jump Instructions (2/2)

| Jump if bitJB <src>, rel(PC) ← (PC) + size (instr); IF [src opnd = 1] THEN (PC) ← (PC) + rel Jump if not bitJNB <src>, rel(PC) ← (PC) + size (instr); IF [src opnd = 0] THEN (PC) ← (PC) + rel Jump if bit and clearJBC <dest>, rel(PC) ← (PC) + size (instr); IF [dest opnd = 1] THEN dest opnd ← 0 (PC) ← (PC) + rel Jump if accumulator is zeroJZ rel(PC) ← (PC) + size (instr); IF [(A) = 0] THEN (PC) ← (PC) + rel Jump if accumulator is not zeroJNZ rel(PC) ← (PC) + size (instr); IF [(A) ≠ 0] THEN (PC) ← (PC) + rel Compare and jump if not equalCJNE <src1>, <src2>, rel(PC) ← (PC) + size (instr); IF [src opnd1 < src opnd2] THEN (CY) ← 1 IF [src opnd1 ≥ src opnd2] THEN (CY) ← 0 IF [src opnd1 ≠ src opnd2] THEN (PC) ← (PC) + rel Decrement and jump if not zeroDJNZ <dest>, rel(PC) ← (PC) + size (instr); dest opnd ← dest opnd -1; IF [φ (Z)] THEN (PC) ← (PC) + rel | | | | | | |
|---|------------------------------|---|----------------------------|------------------------|----------------------------|-----------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode ⁽²⁾ | | Source Mode ⁽²⁾ | |
| | | | Bytes | States | Bytes | States |
| JB | bit51, rel | Jump if direct bit is set | 3 | 2/5 ⁽³⁾⁽⁶⁾ | 3 | 2/5 ⁽³⁾⁽⁶⁾ |
| | bit, rel | Jump if direct bit of 8-bit address location is set | 5 | 4/7 ⁽³⁾⁽⁶⁾ | 4 | 3/6 ⁽³⁾⁽⁶⁾ |
| JNB | bit51, rel | Jump if direct bit is not set | 3 | 2/5 ⁽³⁾⁽⁶⁾ | 3 | 2/5 ⁽³⁾⁽⁶⁾ |
| | bit, rel | Jump if direct bit of 8-bit address location is not set | 5 | 4/7 ⁽³⁾⁽⁶⁾ | 4 | 3/6 ⁽³⁾ |
| JBC | bit51, rel | Jump if direct bit is set & clear bit | 3 | 4/7 ⁽⁵⁾⁽⁶⁾ | 3 | 4/7 ⁽⁵⁾⁽⁶⁾ |
| | bit, rel | Jump if direct bit of 8-bit address location is set and clear | 5 | 7/10 ⁽⁵⁾⁽⁶⁾ | 4 | 6/9 ⁽⁵⁾⁽⁶⁾ |
| JZ | rel | Jump if ACC is zero | 2 | 2/5 ⁽⁶⁾ | 2 | 2/5 ⁽⁶⁾ |
| JNZ | rel | Jump if ACC is not zero | 2 | 2/5 ⁽⁶⁾ | 2 | 2/5 ⁽⁶⁾ |
| CJNE | A, dir8, rel | Compare direct address to ACC and jump if not equal | 3 | 2/5 ⁽³⁾⁽⁶⁾ | 3 | 2/5 ⁽³⁾⁽⁶⁾ |
| | A, #data, rel | Compare immediate to ACC and jump if not equal | 3 | 2/5 ⁽⁶⁾ | 3 | 2/5 ⁽⁶⁾ |
| | Rn, #data, rel | Compare immediate to register and jump if not equal | 3 | 2/5 ⁽⁶⁾ | 4 | 3/6 ⁽⁶⁾ |
| | at Ri, #data, rel | Compare immediate to indirect and jump if not equal | 3 | 3/6 ⁽⁶⁾ | 4 | 4/7 ⁽⁶⁾ |
| DJNZ | Rn, rel | Decrement register and jump if not zero | 2 | 2/5 ⁽⁶⁾ | 3 | 3/6 ⁽⁶⁾ |
| | dir8, rel | Decrement direct address and jump if not zero | 3 | 3/6 ⁽⁴⁾⁽⁶⁾ | 3 | 3/6 ⁽⁴⁾⁽⁶⁾ |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. States are given as jump not-taken/taken.
 3. If this instruction addresses an I/O Port (Px, x = 0-3), add 1 to the number of states. Add 2 if it addresses a Peripheral SFR.
 4. If this instruction addresses an I/O Port (Px, x = 0-3), add 2 to the number of states.



- Add 3 if it addresses a Peripheral SFR.
5. If this instruction addresses an I/O Port (Px, x = 0-3), add 3 to the number of states. Add 5 if it addresses a Peripheral SFR.
 6. In internal execution only, add 1 to the number of states of the 'jump taken' if the destination address is internal and odd.

Table 31. Summary of Unconditional Jump Instructions

| Absolute jump AJMP <src>(PC) ← (PC) + 2; (PC) _{10:0} ← src opnd Extended jump E JMP <src>(PC) ← (PC) + size (instr); (PC) _{23:0} ← src opnd Long jump L JMP <src>(PC) ← (PC) + size (instr); (PC) _{15:0} ← src opnd Short jump S JMP rel(PC) ← (PC) + 2; (PC) ← (PC) + rel Jump indirect J MP at A + DPTR(PC) _{23:16} ← FFh; (PC) _{15:0} ← (A) + (DPTR) No operation N OP(PC) ← (PC) + 1 | | | | | | |
|--|------------------------------|------------------------------------|-------------|---------------------|-------------|---------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| AJMP | addr11 | Absolute jump | 2 | 3 ⁽²⁾⁽³⁾ | 2 | 3 ⁽²⁾⁽³⁾ |
| EJMP | addr24 | Extended jump | 5 | 6 ⁽²⁾⁽⁴⁾ | 4 | 5 ⁽²⁾⁽⁴⁾ |
| | at DRk | Extended jump (indirect) | 3 | 7 ⁽²⁾⁽⁴⁾ | 2 | 6 ⁽²⁾⁽⁴⁾ |
| LJMP | at WRj | Long jump (indirect) | 3 | 6 ⁽²⁾⁽⁴⁾ | 2 | 5 ⁽²⁾⁽⁴⁾ |
| | addr16 | Long jump (direct address) | 3 | 5 ⁽²⁾⁽⁴⁾ | 3 | 5 ⁽²⁾⁽⁴⁾ |
| SJMP | rel | Short jump (relative address) | 2 | 4 ⁽²⁾⁽⁴⁾ | 2 | 4 ⁽²⁾⁽⁴⁾ |
| JMP | at A + DPTR | Jump indirect relative to the DPTR | 1 | 5 ⁽²⁾⁽⁴⁾ | 1 | 5 ⁽²⁾⁽⁴⁾ |
| NOP | | No operation (Jump never) | 1 | 1 | 1 | 1 |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. In internal execution only, add 1 to the number of states if the destination address is internal and odd.
 3. Add 2 to the number of states if the destination address is external.
 4. Add 3 to the number of states if the destination address is external.

Table 32. Summary of Call and Return Instructions

| Absolute call ACALL <src>(PC) ← (PC) + 2; push (PC) _{15:0} ; (PC) _{10:0} ← src opnd Extended call ECALL <src>(PC) ← (PC) + size (instr); push (PC) _{23:0} ; (PC) _{23:0} ← src opnd Long call LCALL <src>(PC) ← (PC) + size (instr); push (PC) _{15:0} ; (PC) _{15:0} ← src opnd Return from subroutine RET pop (PC) _{15:0} Extended return from subroutine ERET pop (PC) _{23:0} Return from interrupt RETI IF [INTR = 0] THEN pop (PC) _{15:0} IF [INTR = 1] THEN pop (PC) _{23:0} ; pop (PSW1) Trap interrupt TRAP (PC) ← (PC) + size (instr); IF [INTR = 0] THEN push (PC) _{15:0} IF [INTR = 1] THEN push (PSW1); push (PC) _{23:0} | | | | | | |
|--|------------------------------|-------------------------------------|-------------|----------------------|-------------|----------------------|
| Mnemonic | <dest>, <src> ⁽¹⁾ | Comments | Binary Mode | | Source Mode | |
| | | | Bytes | States | Bytes | States |
| ACALL | addr11 | Absolute subroutine call | 2 | 9 ⁽²⁾⁽³⁾ | 2 | 9 ⁽²⁾⁽³⁾ |
| ECALL | at DRk | Extended subroutine call (indirect) | 3 | 14 ⁽²⁾⁽³⁾ | 2 | 13 ⁽²⁾⁽³⁾ |
| | addr24 | Extended subroutine call | 5 | 14 ⁽²⁾⁽³⁾ | 4 | 13 ⁽²⁾⁽³⁾ |
| LCALL | at WRj | Long subroutine call (indirect) | 3 | 10 ⁽²⁾⁽³⁾ | 2 | 9 ⁽²⁾⁽³⁾ |
| | addr16 | Long subroutine call | 3 | 9 ⁽²⁾⁽³⁾ | 3 | 9 ⁽²⁾⁽³⁾ |
| RET | | Return from subroutine | 1 | 7 ⁽²⁾ | 1 | 7 ⁽²⁾ |
| ERET | | Extended subroutine return | 3 | 9 ⁽²⁾ | 2 | 8 ⁽²⁾ |
| RETI | | Return from interrupt | 1 | 7 ⁽²⁾⁽⁴⁾ | 1 | 7 ⁽²⁾⁽⁴⁾ |
| TRAP | | Jump to the trap interrupt vector | 2 | 12 ⁽⁴⁾ | 1 | 11 ⁽⁴⁾ |

- Notes:
1. A shaded cell denotes an instruction in the C51 Architecture.
 2. In internal execution only, add 1 to the number of states if the destination/return address is internal and odd.
 3. Add 2 to the number of states if the destination address is external.
 4. Add 5 to the number of states if INTR = 1.

Programming and Verifying Non-volatile Memory

Internal Features

The internal non-volatile memory of the TSC80251G2D derivatives contains five different areas:

- Code Memory
- Configuration Bytes
- Lock Bits
- Encryption Array
- Signature Bytes

EPROM/OTPROM Devices

All the internal non-volatile memory but the Signature Bytes of the TSC87251G2D products is made of EPROM cells. The Signature Bytes of the TSC87251G2D products are made of Mask ROM.

The TSC87251G2D products are programmed and verified in the same manner as Atmel's TSC87251G1A, using a SINGLE-PULSE algorithm, which programs at $V_{PP} = 12.75V$ using only one 100 μ s pulse per byte. This results in a programming time of less than 10 seconds for the 32 kilobytes on-chip code memory.

The EPROM of the TSC87251G2D products in Window package is erasable by Ultra-Violet radiation⁽¹⁾ (UV). UV erasure set all the EPROM memory cells to one and allows reprogramming. The quartz window must be covered with an opaque label⁽²⁾ when the device is in operation. This is not so much to protect the EPROM array from inadvertent erasure, as to protect the RAM and other on-chip logic. Allowing light to impinge on the silicon die during device operation may cause a logical malfunction.

The TSC87251G2D products in plastic packages are One Time Programmable (OTP). An EPROM cell cannot be reset by UV once programmed to zero.

- Notes:
1. The recommended erasure procedure is exposure to ultra-violet light (at 2537 Å) to an integrated dose of at least 20 W-sec/cm². Exposing the EPROM to an ultra-violet lamp of 12000 μ W/cm² rating for 30 minutes should be sufficient.
 2. Erasure of the EPROM begins to occur when the chip is exposed to light wavelength shorter than 4000 Å. Since sunlight and fluorescent light have wavelength in this range, exposure to these light sources over an extended time (1 week in sunlight or 3 years in room-level fluorescent lighting) could cause inadvertent erasure.

Mask ROM Devices

All the internal non-volatile memory of TSC83251G2D products is made of Mask ROM cells. They can only be verified by the user, using the same algorithm as the EPROM/OTPROM devices.

ROMless Devices

The TSC80251G2D products do not include on-chip Configuration Bytes, Code Memory and Encryption Array. They only include Signature Bytes made of Mask ROM cells which can be read using the same algorithm as the EPROM/OTPROM devices.

Security Features

In some microcontroller applications, it is desirable that the user's program code be secured from unauthorized access. The TSC83251G2D and TSC87251G2D offer two kinds of protection for program code stored in the on-chip array:

- Program code in the on-chip Code Memory is encrypted when read out for verification if the Encryption Array is programmed.
- A three-level lock bit system restricts external access to the on-chip code memory.

Lock Bit System

The TSC87251G2D products implement 3 levels of security for User's program as described in Table 33. The TSC83251G2D products implement only the first level of security.

Level 0 is the level of an erased part and does not enable any security features.

Level 1 locks the programming of the User's internal Code Memory, the Configuration Bytes and the Encryption Array.

Level 2 locks the verifying of the User's internal Code Memory. It is always possible to verify the Configuration Bytes and the Lock Bits. It is not possible to verify the Encryption Array.

Level 3 locks the external execution.

Table 33. Lock Bits Programming

| Level | Lock bits LB[2:0] | Internal Execution | External Execution | Verification | Programming | External PROM read (MOVC) |
|-------|--------------------|--------------------|--------------------|-----------------------|-------------|---------------------------|
| 0 | 000 | Enable | Enable | Enable ⁽¹⁾ | Enable | Enable ⁽²⁾ |
| 1 | 001 | Enable | Enable | Enable ⁽¹⁾ | Disable | Disable |
| 2 | 01x ⁽³⁾ | Enable | Enable | Disable | Disable | Disable |
| 3 | 1xx ⁽³⁾ | Enable | Disable | Disable | Disable | Disable |

- Notes:
1. Returns encrypted data if Encryption Array is programmed.
 2. Returns non encrypted data.
 3. x means don't care. Level 2 always enables level 1, and level 3 always enables levels 1 and 2.

The security level may be verified according to Table 34.

Table 34. Lock Bits Verifying

| Level | Lock bits Data ⁽¹⁾ |
|-------|-------------------------------|
| 0 | xxxxx000 |
| 1 | xxxxx001 |
| 2 | xxxxx01x |
| 3 | xxxxx1xx |

- Note:
1. x means don't care.

Encryption Array

The TSC83251G2D and TSC87251G2D products include a 128-byte Encryption Array located in non-volatile memory outside the memory address space. During verification of the on-chip code memory, the seven low-order address bits also address the Encryption Array. As the byte of the code memory is read, it is exclusive-NOR'ed (XNOR) with the key byte from the Encryption Array. If the Encryption Array is not programmed (still all 1s), the user program code is placed on the data bus in its original, unencrypted form. If the Encryption Array is programmed with key bytes, the user program code is encrypted and cannot be used without knowledge of the key byte sequence.

To preserve the secrecy of the encryption key byte sequence, the Encryption Array can not be verified.

- Notes:
1. When a MOVC instruction is executed, the content of the ROM is not encrypted. In order to fully protect the user program code, the lock bit level 1 (see Table 33) must always be set when encryption is used.
 2. If the encryption feature is implemented, the portion of the on-chip code memory that does not contain program code should be filled with “random” byte values to prevent the encryption key sequence from being revealed.

Signature Bytes

The TSC80251G2D derivatives contain factory-programmed Signature Bytes. These bytes are located in non-volatile memory outside the memory address space at 30h, 31h, 60h and 61h. To read the Signature Bytes, perform the procedure described in section Verify Algorithm, using the verify signature mode (see Table 37). Signature byte values are listed in Table 35.

Table 35. Signature Bytes (Electronic ID)

| | | Signature Address | Signature Data |
|--------------|---------------------------------|-------------------|----------------|
| Vendor | Atmel | 30h | 58h |
| Architecture | C251 | 31h | 40h |
| Memory | 32 kilobytes EPROM or OTPROM | 60h | F7h |
| | 32 kilobytes MaskROM or ROMless | | 77h |
| Revision | TSC80251G2D derivative | 61h | FDh |

Programming Algorithm

Figure 6 shows the hardware setup needed to program the TSC87251G2D EPROM/OTPROM areas:

- The chip has to be put under reset and maintained in this state until completion of the programming sequence.
- PSEN# and the other control signals (ALE and Port 0) have to be set to a high level.
- Then PSEN# has to be forced to a low level after two clock cycles or more and it has to be maintained in this state until the completion of the programming sequence (see below).
- The voltage on the EA# pin must be set to V_{DD} .
- The programming mode is selected according to the code applied on Port 0 (see Table 36). It has to be applied until the completion of this programming operation.
- The programming address is applied on Ports 1 and 3 which are respectively the Most Significant Byte (MSB) and the Least Significant Byte (LSB) of the address.
- The programming data are applied on Port 2.
- The EPROM Programming is done by raising the voltage on the EA# pin to V_{PP} , then by generating a low level pulse on ALE/PROG# pin.
- The voltage on the EA# pin must be lowered to V_{DD} before completing the programming operation.
- It is possible to alternate programming and verifying operation (See Paragraph Verify Algorithm). Please make sure the voltage on the EA# pin has actually been lowered to V_{DD} before performing the verifying operation.

- PSEN# and the other control signals have to be released to complete a sequence of programming operations or a sequence of programming and verifying operations.

Figure 6. Setup for Programming

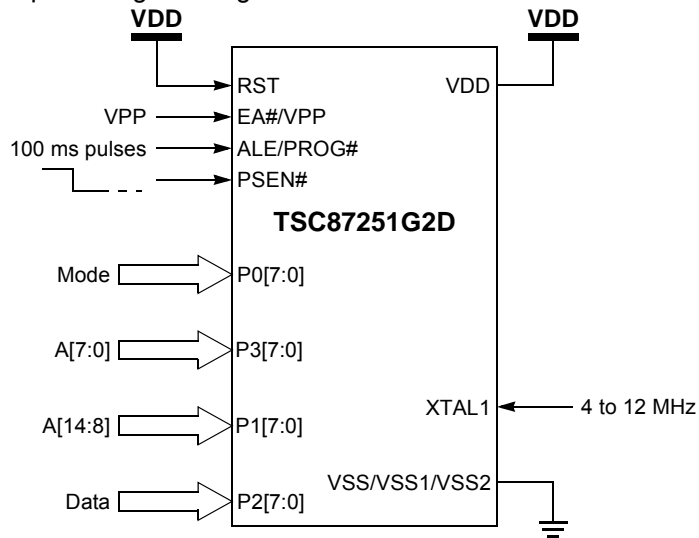


Table 36. Programming Modes

| ROM Area ⁽¹⁾ | RST | EA#/VPP | PSEN # | ALE/PROG# ⁽²⁾ | P0 | P2 | P1(MSB) P3(LSB) |
|-------------------------|-----|-----------------|--------|--------------------------|-----|------|--|
| On-chip Code Memory | 1 | V _{PP} | 0 | 1 Pulse | 68h | Data | 16-bit Address 0000h-7FFFh (32 kilobytes) |
| Configuration Bytes | 1 | V _{PP} | 0 | 1 Pulse | 69h | Data | CONFIG0: FFF8h CONFIG1: FFF9h |
| Lock Bits | 1 | V _{PP} | 0 | 1 Pulse | 6Bh | X | LB0: 0001h LB1: 0002h LB2: 0003h |
| Encryption Array | 1 | V _{PP} | 0 | 1 Pulse | 6Ch | Data | 0000h-007Fh |

- Notes:
1. Signature Bytes are not user-programmable.
 2. The ALE/PROG# pulse waveform is shown in Figure 23 page 59.

Verify Algorithm

Figure 7 shows the hardware setup needed to verify the TSC87251G2D EPROM/OTPROM or TSC83251G2D ROM areas:

- The chip has to be put under reset and maintained in this state until the completion of the verifying sequence.
- PSEN# and the other control signals (ALE and Port 0) have to be set to a high level.
- Then PSEN# has to be forced to a low level after two clock cycles or more and it has to be maintained in this state until the completion of the verifying sequence (see below).
- The voltage on the EA# pin must be set to V_{DD} and ALE must be set to a high level.
- The Verifying Mode is selected according to the code applied on Port 0. It has to be applied until the completion of this verifying operation.
- The verifying address is applied on Ports 1 and 3 which are respectively the MSB and the LSB of the address.

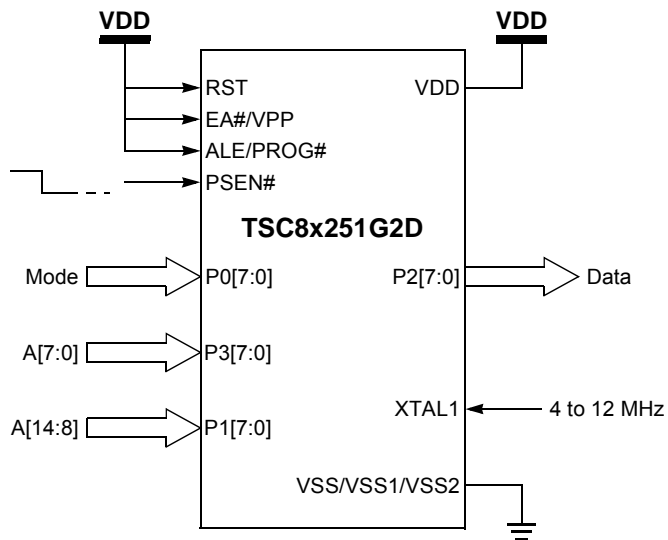
- Then device is driving the data on Port 2.
- It is possible to alternate programming and verification operation (see Paragraph Programming Algorithm). Please make sure the voltage on the EA# pin has actually been lowered to V_{DD} before performing the verifying operation.
- PSEN# and the other control signals have to be released to complete a sequence of verifying operations or a sequence of programming and verifying operations.

Table 37. Verifying Modes

| ROM Area ⁽¹⁾ | RST | EA#/VPP | PSEN# | ALE/PROG# | P0 | P2 | P1(MSB) P3(LSB) |
|-------------------------|-----|---------|-------|-----------|-----|------|--|
| On-chip code memory | 1 | 1 | 0 | 1 | 28h | Data | 16-bit Address 0000h-7FFFh (32 kilobytes) |
| Configuration Bytes | 1 | 1 | 0 | 1 | 29h | Data | CONFIG0: FFF8h CONFIG1: FFF9h |
| Lock Bits | 1 | 1 | 0 | 1 | 2Bh | Data | 0000h |
| Signature Bytes | 1 | 1 | 0 | 1 | 29h | Data | 0030h, 0031h, 0060h, 0061h |

Notes: 1. To preserve the secrecy of on-chip code memory when encrypted, the Encryption Array can not be verified.

Figure 7. Setup for Verifying



AC Characteristics - Commercial & Industrial

AC Characteristics - External Bus Cycles

Definition of Symbols

Table 38. External Bus Cycles Timing Symbol Definitions

| Signals | |
|---------|-----------|
| A | Address |
| D | Data In |
| L | ALE |
| Q | Data Out |
| R | RD#/PSEN# |
| W | WR# |

| Conditions | |
|------------|-----------------|
| H | High |
| L | Low |
| V | Valid |
| X | No Longer Valid |
| Z | Floating |

Timings

Test conditions: capacitive load on all pins = 50 pF.

Table 39 and Table 40 list the AC timing parameters for the TSC80251G2D derivatives with no wait states. External wait states can be added by extending PSEN#/RD#/WR# and or by extending ALE. In these tables, Note 2 marks parameters affected by one ALE wait state, and Note 3 marks parameters affected by PSEN#/RD#/WR# wait states.

Figure 8 to Figure 13 show the bus cycles with the timing parameters.

Table 39. Bus Cycles AC Timings; $V_{DD} = 4.5$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | 12 MHz | | 16 MHz | | 24 MHz | | Unit |
|------------------|--|--------|-----|--------|-----|--------|-----|----------------------|
| | | Min | Max | Min | Max | Min | Max | |
| T_{OSC} | $1/F_{OSC}$ | 83 | | 62 | | 41 | | ns |
| T_{LHLL} | ALE Pulse Width | 78 | | 58 | | 38 | | ns ⁽²⁾ |
| T_{AVLL} | Address Valid to ALE Low | 78 | | 58 | | 37 | | ns ⁽²⁾ |
| T_{LLAX} | Address hold after ALE Low | 19 | | 11 | | 3 | | ns |
| $T_{RLRH}^{(1)}$ | RD#/PSEN# Pulse Width | 162 | | 121 | | 78 | | ns ⁽³⁾ |
| T_{WLWH} | WR# Pulse Width | 165 | | 124 | | 81 | | ns ⁽³⁾ |
| $T_{LLRL}^{(1)}$ | ALE Low to RD#/PSEN# Low | 22 | | 14 | | 6 | | ns |
| T_{LHAX} | ALE High to Address Hold | 99 | | 70 | | 40 | | ns ⁽²⁾ |
| $T_{RLDV}^{(1)}$ | RD#/PSEN# Low to Valid Data | | 146 | | 104 | | 61 | ns ⁽³⁾ |
| $T_{RHDX}^{(1)}$ | Data Hold After RD#/PSEN# High | 0 | | 0 | | 0 | | ns |
| $T_{RHAX}^{(1)}$ | Address Hold After RD#/PSEN# High | 0 | | 0 | | 0 | | ns |
| $T_{RLAZ}^{(1)}$ | RD#/PSEN# Low to Address Float | | 0 | | 0 | | 0 | ns |
| T_{RHDZ1} | Instruction Float After RD#/PSEN# High | | 45 | | 40 | | 30 | ns |
| T_{RHDZ2} | Data Float After RD#/PSEN# High | | 215 | | 165 | | 115 | ns |
| T_{RHLH1} | RD#/PSEN# high to ALE High (Instruction) | 49 | | 43 | | 31 | | ns |
| T_{RHLH2} | RD#/PSEN# high to ALE High (Data) | 215 | | 169 | | 115 | | ns |
| T_{WHLH} | WR# High to ALE High | 215 | | 169 | | 115 | | ns |
| T_{AVDV1} | Address (P0) Valid to Valid Data In | | 250 | | 175 | | 105 | ns ⁽²⁾⁽³⁾ |
| T_{AVDV2} | Address (P2) Valid to Valid Data In | | 306 | | 223 | | 140 | ns ⁽²⁾⁽³⁾ |
| T_{AVDV3} | Address (P0) Valid to Valid Instruction In | | 150 | | 109 | | 68 | ns ⁽³⁾ |
| T_{AXDX} | Data Hold after Address Hold | 0 | | 0 | | 0 | | ns |
| $T_{AVRL}^{(1)}$ | Address Valid to RD# Low | 100 | | 70 | | 40 | | ns ⁽²⁾ |
| T_{AVWL1} | Address (P0) Valid to WR# Low | 100 | | 70 | | 40 | | ns ⁽²⁾ |
| T_{AVWL2} | Address (P2) Valid to WR# Low | 158 | | 115 | | 74 | | ns ⁽²⁾ |
| T_{WHQX} | Data Hold after WR# High | 90 | | 69 | | 32 | | ns |
| T_{QVWH} | Data Valid to WR# High | 133 | | 102 | | 72 | | ns ⁽³⁾ |
| T_{WHAX} | WR# High to Address Hold | 167 | | 125 | | 84 | | ns |

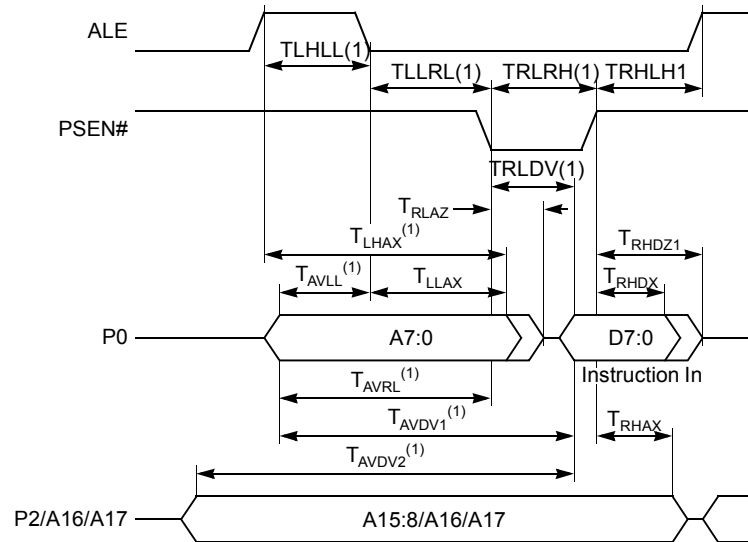
- Notes:
1. Specification for PSEN# are identical to those for RD#.
 2. If a wait state is added by extending ALE, add $2 \cdot T_{OSC}$.
 3. If wait states are added by extending RD#/PSEN#/WR#, add $2N \cdot T_{OSC}$ ($N = 1..3$).

Table 40. Bus Cycles AC Timings; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | 12 MHz | | 16 MHz | | Unit |
|------------------|--|--------|-----|--------|-----|----------------------|
| | | Min | Max | Min | Max | |
| T_{OSC} | $1/F_{OSC}$ | 83 | | 62 | | ns |
| T_{LHLL} | ALE Pulse Width | 72 | | 52 | | ns ⁽²⁾ |
| T_{AVLL} | Address Valid to ALE Low | 71 | | 51 | | ns ⁽²⁾ |
| T_{LLAX} | Address hold after ALE Low | 14 | | 6 | | ns |
| $T_{RLRH}^{(1)}$ | RD#/PSEN# Pulse Width | 163 | | 121 | | ns ⁽³⁾ |
| T_{WLWH} | WR# Pulse Width | 165 | | 124 | | ns ⁽³⁾ |
| $T_{LLRL}^{(1)}$ | ALE Low to RD#/PSEN# Low | 17 | | 11 | | ns |
| T_{LHAX} | ALE High to Address Hold | 90 | | 57 | | ns ⁽²⁾ |
| $T_{RLDV}^{(1)}$ | RD#/PSEN# Low to Valid Data | | 133 | | 92 | ns ⁽³⁾ |
| $T_{RHDX}^{(1)}$ | Data Hold After RD#/PSEN# High | 0 | | 0 | | ns |
| $T_{RHAX}^{(1)}$ | Address Hold After RD#/PSEN# High | 0 | | 0 | | ns |
| $T_{RLAZ}^{(1)}$ | RD#/PSEN# Low to Address Float | | 0 | | 0 | ns |
| T_{RHDZ1} | Instruction Float After RD#/PSEN# High | | 59 | | 48 | ns |
| T_{RHDZ2} | Data Float After RD#/PSEN# High | | 225 | | 175 | ns |
| T_{RHLH1} | RD#/PSEN# high to ALE High (Instruction) | 60 | | 47 | | ns |
| T_{RHLH2} | RD#/PSEN# high to ALE High (Data) | 226 | | 172 | | ns |
| T_{WHLH} | WR# High to ALE High | 226 | | 172 | | ns |
| T_{AVDV1} | Address (P0) Valid to Valid Data In | | 289 | | 160 | ns ⁽²⁾⁽³⁾ |
| T_{AVDV2} | Address (P2) Valid to Valid Data In | | 296 | | 211 | ns ⁽²⁾⁽³⁾ |
| T_{AVDV3} | Address (P0) Valid to Valid Instruction In | | 144 | | 98 | ns ⁽³⁾ |
| T_{AXDX} | Data Hold after Address Hold | 0 | | 0 | | ns |
| $T_{AVRL}^{(1)}$ | Address Valid to RD# Low | 111 | | 64 | | ns ⁽²⁾ |
| T_{AVWL1} | Address (P0) Valid to WR# Low | 111 | | 64 | | ns ⁽²⁾ |
| T_{AVWL2} | Address (P2) Valid to WR# Low | 158 | | 116 | | ns ⁽²⁾ |
| T_{WHQX} | Data Hold after WR# High | 82 | | 66 | | ns |
| T_{QVWH} | Data Valid to WR# High | 135 | | 103 | | ns ⁽³⁾ |
| T_{WHAX} | WR# High to Address Hold | 168 | | 125 | | ns |

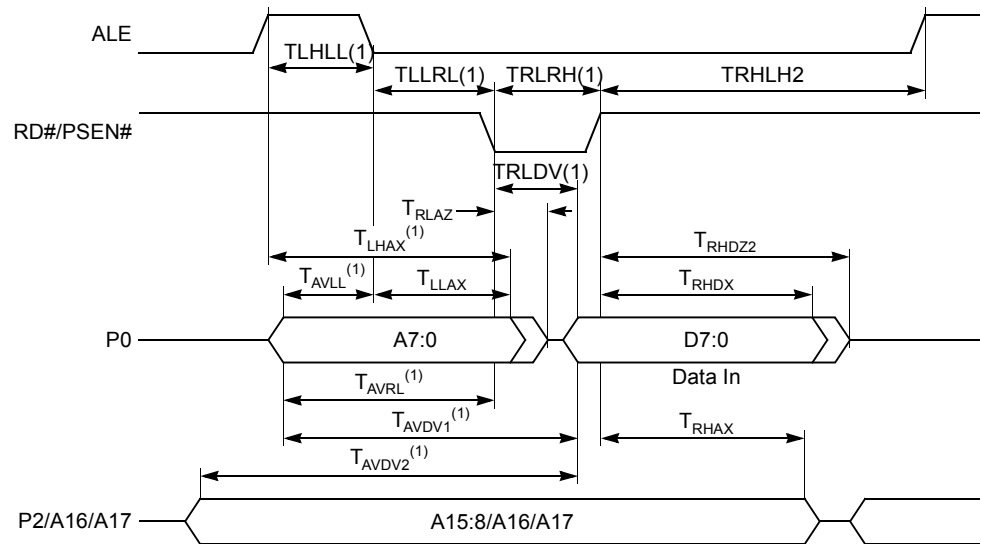
- Notes: 1. Specification for PSEN# are identical to those for RD#.
 2. If a wait state is added by extending ALE, add $2 \cdot T_{OSC}$.
 3. If wait states are added by extending RD#/PSEN#/WR#, add $2N \cdot T_{OSC}$ ($N = 1..3$).

Waveforms in Non-Page Mode Figure 8. External Bus Cycle: Code Fetch (Non-Page Mode)



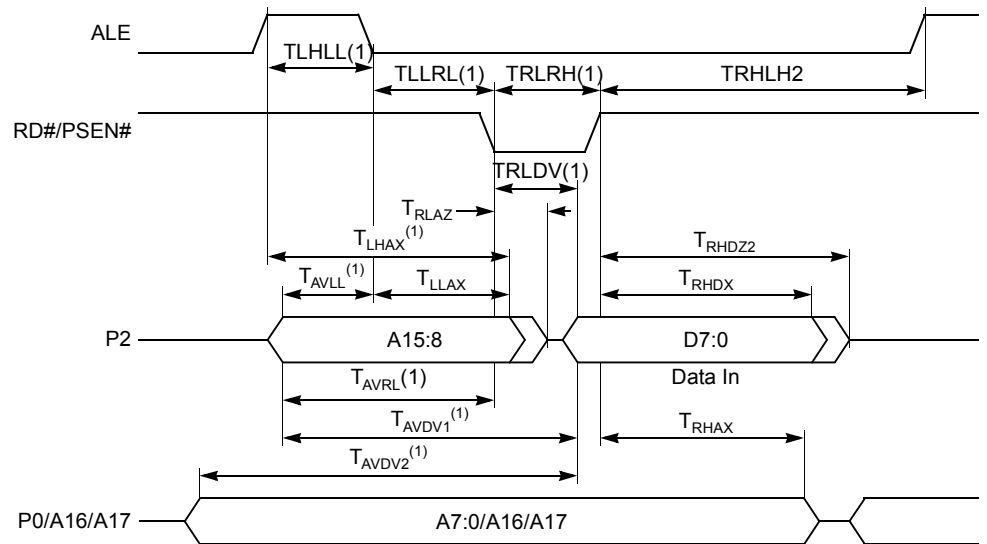
Note: 1. The value of this parameter depends on wait states. See Table 39 and Table 40.

Figure 9. External Bus Cycle: Data Read (Non-Page Mode)



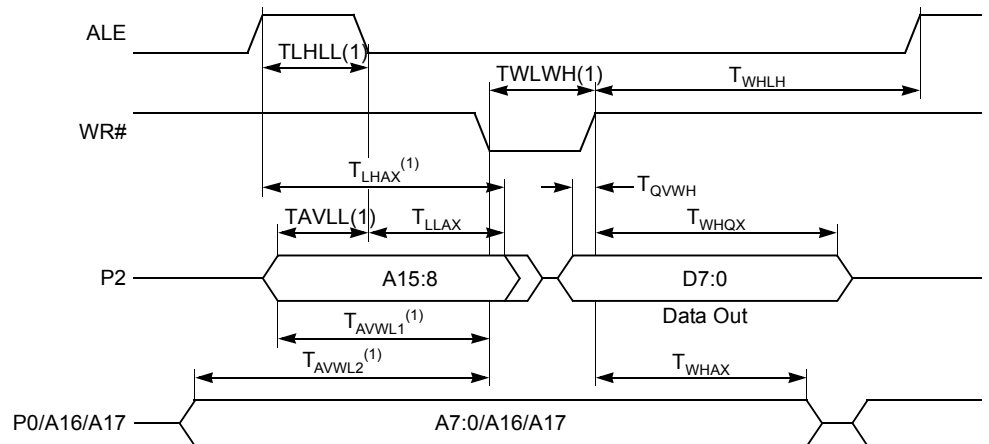
Note: 1. The value of this parameter depends on wait states. See Table 39 and Table 40.

Figure 12. External Bus Cycle: Data Read (Page Mode)



Note: 1. The value of this parameter depends on wait states. See Table 39 and Table 40.

Figure 13. External Bus Cycle: Data Write (Page Mode)



Note: 1. The value of this parameter depends on wait states. See Table 39 and Table 40.

AC Characteristics - Real-Time Synchronous Wait State

Definition of Symbols

Table 41. Real-Time Synchronous Wait Timing Symbol Definitions

| Signals | |
|---------|-----------|
| C | WCLK |
| R | RD#/PSEN# |
| W | WR# |
| Y | WAIT# |

| Conditions | |
|------------|-----------------|
| L | Low |
| V | Valid |
| X | No Longer Valid |

Timings

Table 42. Real-Time Synchronous Wait AC Timings; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | Min | Max | Unit |
|------------|--------------------------------|------------------------|-----------------------------|------|
| T_{CLYV} | Wait Clock Low to Wait Set-up | 0 | $T_{OSC} - 20$ | ns |
| T_{CLYX} | Wait Hold after Wait Clock Low | $2W \cdot T_{OSC} + 5$ | $(1+2W) \cdot T_{OSC} - 20$ | ns |
| T_{RLYV} | PSEN#/RD# Low to Wait Set-up | 0 | $T_{OSC} - 20$ | ns |
| T_{RLYX} | Wait Hold after PSEN#/RD# Low | $2W \cdot T_{OSC} + 5$ | $(1+2W) \cdot T_{OSC} - 20$ | ns |
| T_{WLYV} | WR# Low to Wait Set-up | 0 | $T_{OSC} - 20$ | ns |
| T_{WLYX} | Wait Hold after WR# Low | $2W \cdot T_{OSC} + 5$ | $(1+2W) \cdot T_{OSC} - 20$ | ns |

Waveforms

Figure 14. Real-time Synchronous Wait State: Code Fetch/Data Read

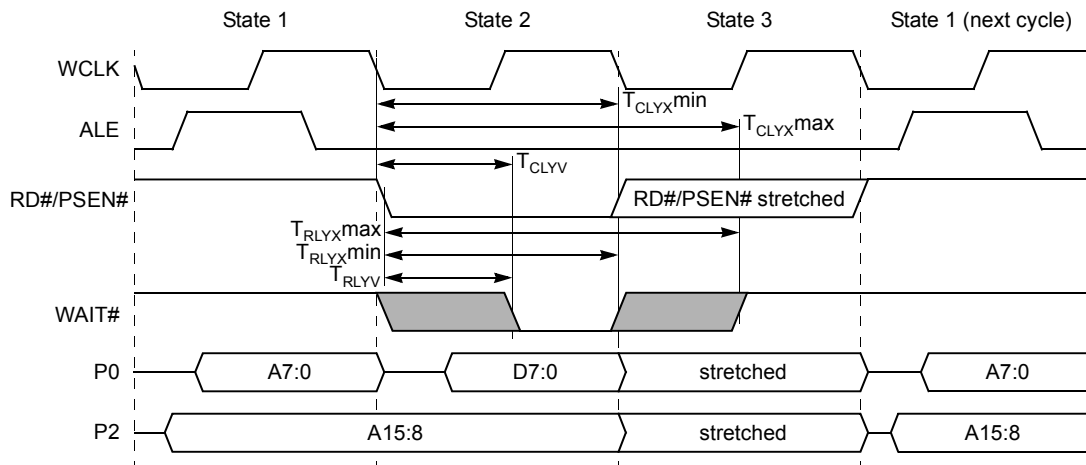
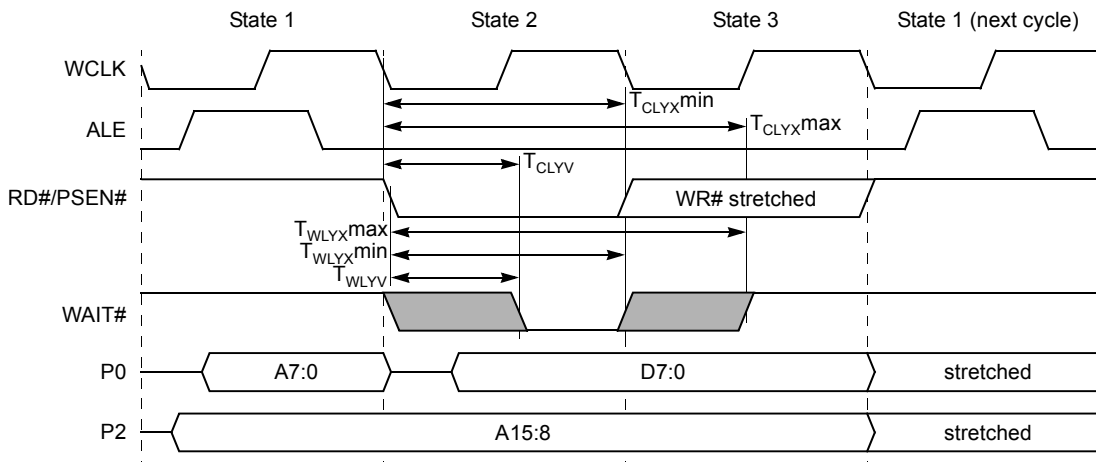


Figure 15. Real-time Synchronous Wait State: Data Write



AC Characteristics - Real-Time Asynchronous Wait State

Definition of Symbols

Table 43. Real-Time Asynchronous Wait Timing Symbol Definitions

| Signals | |
|---------|---------------|
| S | PSEN#/RD#/WR# |
| Y | AWAIT# |

| Conditions | |
|------------|-----------------|
| L | Low |
| V | Valid |
| X | No Longer Valid |

Timings

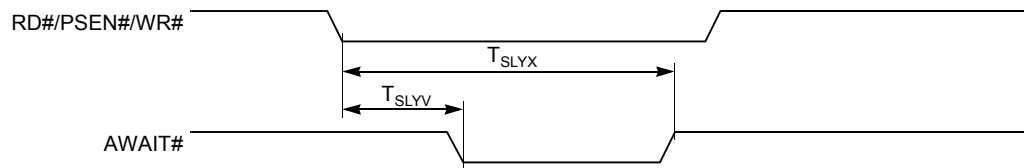
Table 44. Real-Time Asynchronous Wait AC Timings; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | Min | Max | Unit |
|------------|-----------------------------------|-----------------------------|----------------|-------------------|
| T_{SLYV} | PSEN#/RD#/WR# Low to Wait Set-up | | $T_{OSC} - 10$ | ns |
| T_{SLYX} | Wait Hold after PSEN#/RD#/WR# Low | $(2N-1) \cdot T_{OSC} + 10$ | | ns ⁽¹⁾ |

Note: 1. N is the number of wait states added ($N \geq 1$).

Waveforms

Figure 16. Real-time Asynchronous Wait State Timings



AC Characteristics - Serial Port in Shift Register Mode

Definition of Symbols

Table 45. Serial Port Timing Symbol Definitions

| Signals | |
|---------|----------|
| D | Data In |
| Q | Data Out |
| X | Clock |

| Conditions | |
|------------|-----------------|
| H | High |
| L | Low |
| V | Valid |
| X | No Longer Valid |

Timings

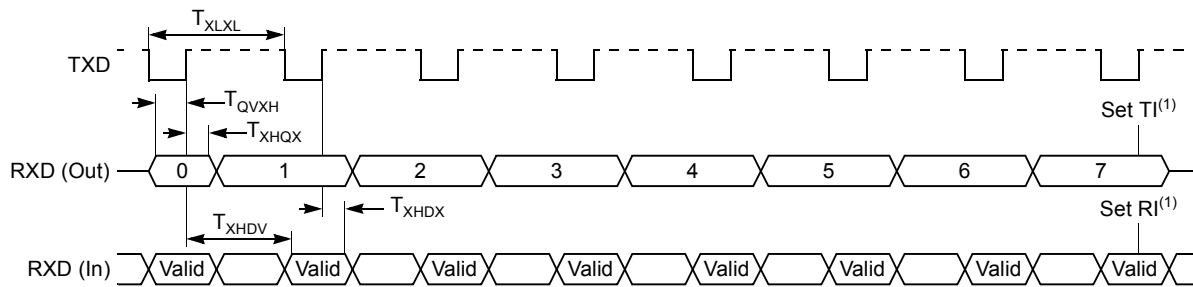
Table 46. Serial Port AC Timing -Shift Register Mode; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | 12 MHz | | 16 MHz | | 24 MHz ⁽¹⁾ | | Unit |
|------------|--|--------|-----|--------|-----|-----------------------|-----|------|
| | | Min | Max | Min | Max | Min | Max | |
| T_{XLXL} | Serial Port Clock Cycle Time | 998 | | 749 | | 500 | | ns |
| T_{QVXH} | Output Data Setup to Clock Rising Edge | 833 | | 625 | | 417 | | ns |
| T_{XHGX} | Output Data hold after Clock Rising Edge | 165 | | 124 | | 82 | | ns |
| T_{XHDX} | Input Data Hold after Clock Rising Edge | 0 | | 0 | | 0 | | ns |
| T_{XHDV} | Clock Rising Edge to Input Data Valid | | 974 | | 732 | | 482 | ns |

Note: 1. For high speed versions only.

Waveforms

Figure 17. Serial Port Waveforms - Shift Register Mode



Note: 1. TI and RI are set during S1P1 of the peripheral cycle following the shift of the eight bit.

AC Characteristics - SSLC: TWI Interface

Timings

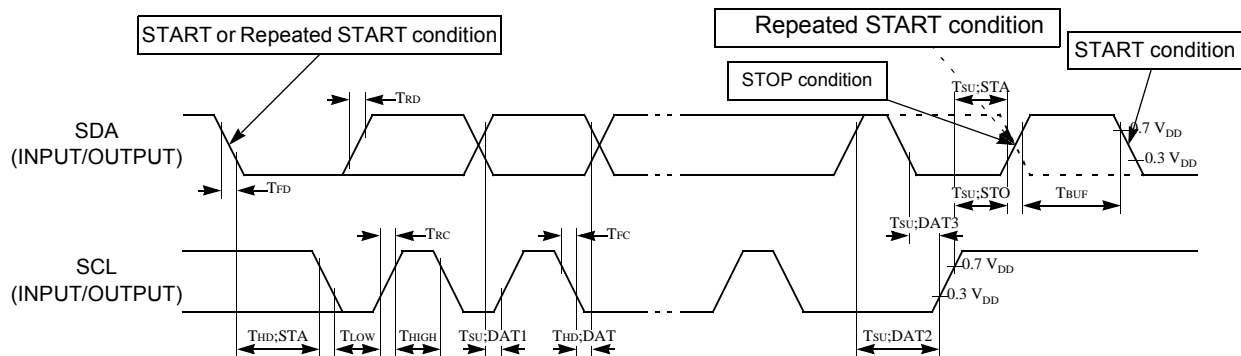
Table 47. TWI Interface AC Timing; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | INPUT | | OUTPUT | |
|----------------|---|---------------------------|-----|------------------------------------|-----|
| | | Min | Max | Min | Max |
| $T_{HD}; STA$ | Start condition hold time | $14 \cdot T_{CLCL}^{(4)}$ | | $4.0 \mu\text{s}^{(1)}$ | |
| T_{LOW} | SCL low time | $16 \cdot T_{CLCL}^{(4)}$ | | $4.7 \mu\text{s}^{(1)}$ | |
| T_{HIGH} | SCL high time | $14 \cdot T_{CLCL}^{(4)}$ | | $4.0 \mu\text{s}^{(1)}$ | |
| T_{RC} | SCL rise time | $1 \mu\text{s}$ | | $_{(2)}$ | |
| T_{FC} | SCL fall time | $0.3 \mu\text{s}$ | | $0.3 \mu\text{s}^{(3)}$ | |
| $T_{SU}; DAT1$ | Data set-up time | 250 ns | | $20 \cdot T_{CLCL}^{(4)} - T_{RD}$ | |
| $T_{SU}; DAT2$ | SDA set-up time (before repeated START condition) | 250 ns | | $1 \mu\text{s}^{(1)}$ | |
| $T_{SU}; DAT3$ | SDA set-up time (before STOP condition) | 250 ns | | $8 \cdot T_{CLCL}^{(4)}$ | |
| $T_{HD}; DAT$ | Data hold time | 0 ns | | $8 \cdot T_{CLCL}^{(4)} - T_{FC}$ | |
| $T_{SU}; STA$ | Repeated START set-up time | $14 \cdot T_{CLCL}^{(4)}$ | | $4.7 \mu\text{s}^{(1)}$ | |
| $T_{SU}; STO$ | STOP condition set-up time | $14 \cdot T_{CLCL}^{(4)}$ | | $4.0 \mu\text{s}^{(1)}$ | |
| T_{BUF} | Bus free time | $14 \cdot T_{CLCL}^{(4)}$ | | $4.7 \mu\text{s}^{(1)}$ | |
| T_{RD} | SDA rise time | $1 \mu\text{s}$ | | $_{(2)}$ | |
| T_{FD} | SDA fall time | $0.3 \mu\text{s}$ | | $0.3 \mu\text{s}^{(3)}$ | |

- Notes:
- At 100 kbit/s. At other bit-rates this value is inversely proportional to the bit-rate of 100 kbit/s.
 - Determined by the external bus-line capacitance and the external bus-line pull-up resistor, this must be $< 1 \mu\text{s}$.
 - Spikes on the SDA and SCL lines with a duration of less than $3 \cdot T_{CLCL}$ will be filtered out. Maximum capacitance on bus-lines SDA and SCL = 400 pF.
 - $T_{CLCL} = T_{OSC}$ = one oscillator clock period.

Waveforms

Figure 18. TWI Waveforms



AC Characteristics - SSLC: SPI Interface

Definition of Symbols

Table 48. SPI Interface Timing Symbol Definitions

| Signals | |
|---------|----------|
| C | Clock |
| I | Data In |
| O | Data Out |
| S | SS# |

| Conditions | |
|------------|-----------------|
| H | High |
| L | Low |
| V | Valid |
| X | No Longer Valid |
| Z | Floating |

Timings

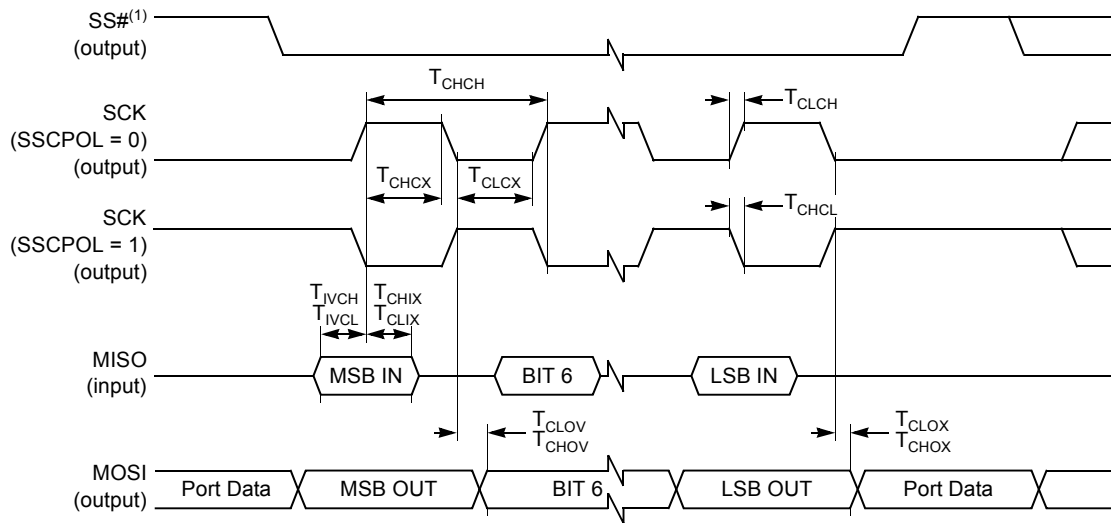
Table 49. SPI Interface AC Timing; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to 85°C

| Symbol | Parameter | Min | Max | Unit |
|----------------------------------|--|-----|-----|---------------|
| Slave Mode⁽¹⁾ | | | | |
| T_{CHCH} | Clock Period | 8 | | T_{OSC} |
| T_{CHCX} | Clock High Time | 3.2 | | T_{OSC} |
| T_{CLCX} | Clock Low Time | 3.2 | | T_{OSC} |
| T_{SLCH}, T_{SLCL} | SS# Low to Clock edge | 200 | | ns |
| T_{IVCL}, T_{IVCH} | Input Data Valid to Clock Edge | 100 | | ns |
| T_{CLIX}, T_{CHIX} | Input Data Hold after Clock Edge | 100 | | ns |
| T_{CLOV}, T_{CHOV} | Output Data Valid after Clock Edge | | 100 | ns |
| T_{CLOX}, T_{CHOX} | Output Data Hold Time after Clock Edge | 0 | | ns |
| T_{CLSH}, T_{CHSH} | SS# High after Clock Edge | 0 | | ns |
| T_{IVCL}, T_{IVCH} | Input Data Valid to Clock Edge | 100 | | ns |
| T_{CLIX}, T_{CHIX} | Input Data Hold after Clock Edge | 100 | | ns |
| T_{SLOV} | SS# Low to Output Data Valid | | 130 | ns |
| T_{SHOX} | Output Data Hold after SS# High | | 130 | ns |
| T_{SHSL} | SS# High to SS# Low | (2) | | |
| T_{ILIH} | Input Rise Time | | 2 | μs |
| T_{IHIL} | Input Fall Time | | 2 | μs |
| T_{OLOH} | Output Rise time | | 100 | ns |
| T_{OHOL} | Output Fall Time | | 100 | ns |
| Master Mode⁽³⁾ | | | | |
| T_{CHCH} | Clock Period | 4 | | T_{OSC} |
| T_{CHCX} | Clock High Time | 1.6 | | T_{OSC} |
| T_{CLCX} | Clock Low Time | 1.6 | | T_{OSC} |
| T_{IVCL}, T_{IVCH} | Input Data Valid to Clock Edge | 50 | | ns |
| T_{CLIX}, T_{CHIX} | Input Data Hold after Clock Edge | 50 | | ns |
| T_{CLOV}, T_{CHOV} | Output Data Valid after Clock Edge | | 65 | ns |
| T_{CLOX}, T_{CHOX} | Output Data Hold Time after Clock Edge | 0 | | ns |
| T_{ILIH} | Input Data Rise Time | | 2 | μs |
| T_{IHIL} | Input Data Fall Time | | 2 | μs |
| T_{OLOH} | Output Data Rise time | | 50 | ns |
| T_{OHOL} | Output Data Fall Time | | 50 | ns |

- Notes: 1. Capacitive load on all pins = 200 pF in slave mode.
 2. The value of this parameter depends on software.
 3. Capacitive load on all pins = 100 pF in master mode.

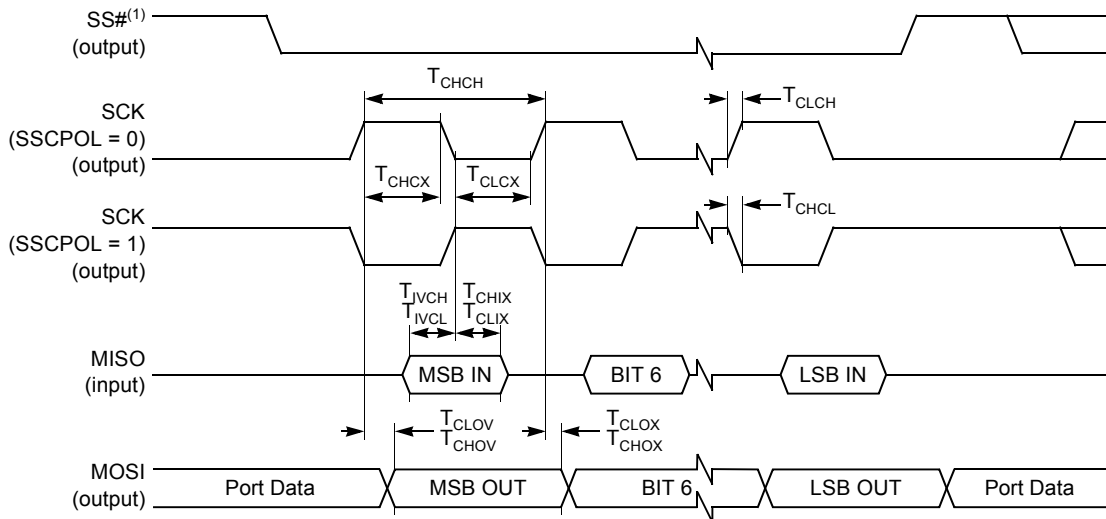
Waveforms

Figure 19. SPI Master Waveforms (SSCPHA = 0)



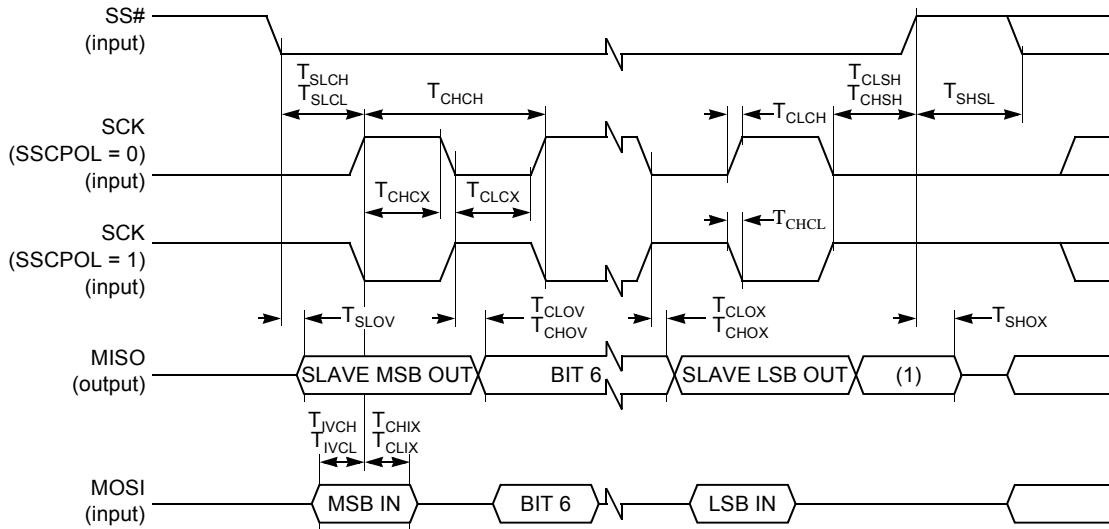
Note: 1. SS# handled by software.

Figure 20. SPI Master Waveforms (SSCPHA = 1)



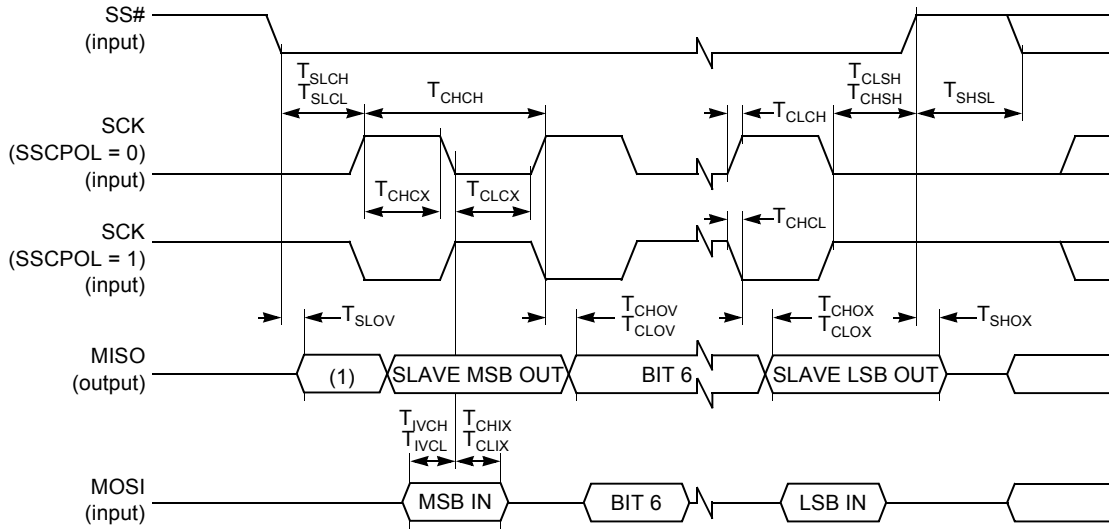
Note: 1. Not Defined but normally MSB of character just received.

Figure 21. SPI Slave Waveforms (SSCPHA = 0)



Note: 1. Not Defined but generally the LSB of the character which has just been received.

Figure 22. SPI Slave Waveforms (SSCPHA = 1)



AC Characteristics - EPROM Programming and Verifying

Definition of Symbols

Table 50. EPROM Programming and Verifying Timing Symbol Definitions

| Signals | |
|---------|----------------------------|
| A | Address |
| E | Enable: mode set on Port 0 |
| G | Program |
| Q | Data Out |
| S | Supply (V_{PP}) |

| Conditions | |
|------------|-----------------|
| H | High |
| L | Low |
| V | Valid |
| X | No Longer Valid |
| Z | Floating |

Timings

Table 51. EPROM Programming AC timings; $V_{DD} = 4.5$ to 5.5 V, $T_A = 0$ to 40°C

| Symbol | Parameter | Min | Max | Unit |
|------------|------------------------------|------|-----|---------------|
| T_{OSC} | XTAL1 Period | 83.5 | 250 | ns |
| T_{AVGL} | Address Setup to PROG# low | 48 | | T_{OSC} |
| T_{GHAX} | Address Hold after PROG# low | 48 | | T_{OSC} |
| T_{DVGL} | Data Setup to PROG# low | 48 | | T_{OSC} |
| T_{GHDX} | Data Hold after PROG# | 48 | | T_{OSC} |
| T_{ELSH} | ENABLE High to V_{PP} | 48 | | T_{OSC} |
| T_{SHGL} | V_{PP} Setup to PROG# low | 10 | | μs |
| T_{GHSL} | V_{PP} Hold after PROG# | 10 | | μs |
| T_{SLEH} | ENABLE Hold after V_{PP} | 0 | | ns |
| T_{GLGH} | PROG# Width | 90 | 110 | μs |

Table 52. EPROM Verifying AC timings; $V_{DD} = 4.5$ to 5.5 V, $V_{DD} = 2.7$ to 5.5 V, $T_A = 0$ to 40°C

| Symbol | Parameter | Min | Max | Unit |
|------------|--------------------------|------|-----|-----------|
| T_{OSC} | XTAL1 Period | 83.5 | 250 | ns |
| T_{AVQV} | Address to Data Valid | | 48 | T_{OSC} |
| T_{AXQX} | Address to Data Invalid | 0 | | ns |
| T_{ELQV} | ENABLE low to Data Valid | 0 | 48 | T_{OSC} |
| T_{EHQZ} | Data Float after ENABLE | 0 | 48 | T_{OSC} |

Waveforms

Figure 23. EPROM Programming Waveforms

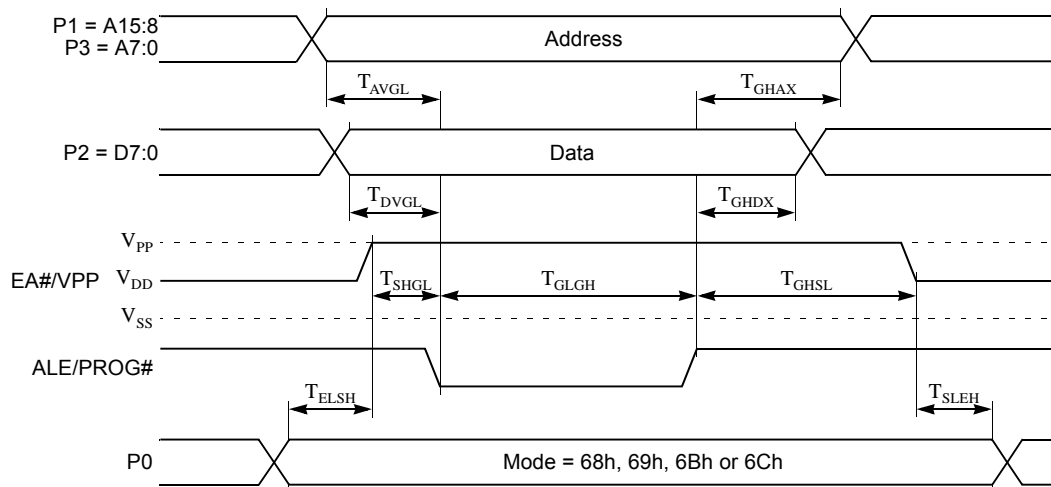
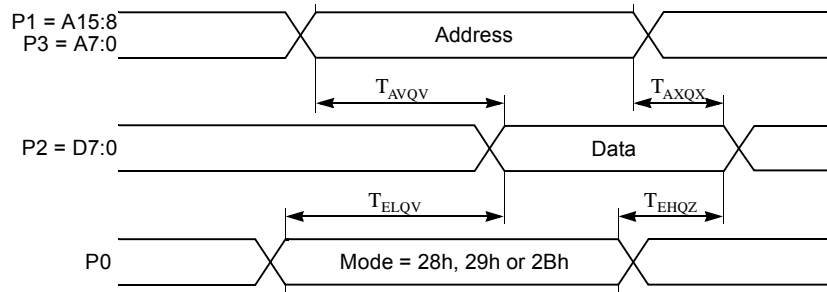


Figure 24. EPROM Verifying Waveforms



AC Characteristics - External Clock Drive and Logic Level References

Definition of Symbols

Table 53. External Clock Timing Symbol Definitions

| Signals | |
|---------|-------|
| C | Clock |

| Conditions | |
|------------|-----------------|
| H | High |
| L | Low |
| X | No Longer Valid |

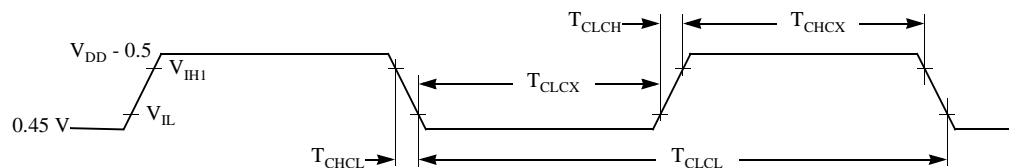
Timings

Table 54. External Clock AC Timings; $V_{DD} = 4.5$ to 5.5 V, $T_A = -40$ to $+85^\circ\text{C}$

| Symbol | Parameter | Min | Max | Unit |
|------------|----------------------|-----|-----|------|
| F_{OSC} | Oscillator Frequency | | 24 | MHz |
| T_{CHCX} | High Time | 10 | | ns |
| T_{CLCX} | Low Time | 10 | | ns |
| T_{CLCH} | Rise Time | 3 | | ns |
| T_{CHCL} | Fall Time | 3 | | ns |

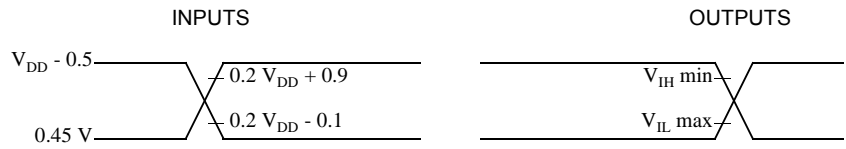
Waveforms

Figure 25. External Clock Waveform



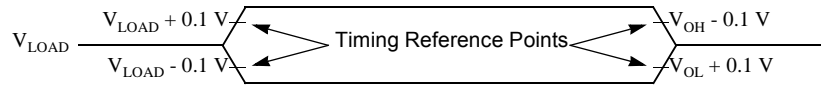
- Notes:
1. During AC testing, all inputs are driven at $V_{DD} - 0.5$ V for a logic 1 and 0.45 V for a logic 0.
 2. Timing measurements are made on all outputs at V_{IH} min for a logic 1 and V_{IL} max for a logic 0.

Figure 26. AC Testing Input/Output Waveforms



Note: For timing purposes, a port pin is no longer floating when a 100 mV change from load voltage occurs and begins to float when a 100 mV change from the loading V_{OH}/V_{OL} level occurs with $I_{OL}/I_{OH} = \pm 20$ mA.

Figure 27. Float Waveforms





Absolute Maximum Rating and Operating Conditions

Absolute Maximum Ratings

| | | |
|---------------------------------------|----------------|---|
| Storage Temperature | -65 to +150°C | *NOTICE: Stressing the device beyond the “Absolute Maximum Ratings” may cause permanent damage. These are stress ratings only. Operation beyond the “operating conditions” is not recommended and extended exposure beyond the “Operating Conditions” may affect device reliability. |
| Voltage on any other Pin to VSS | -0.5 to +6.5 V | |
| I _{OL} per I/O Pin | 15 mA | |
| Power Dissipation | 1.5 W | |
| Ambient Temperature Under Bias | | |
| Commercial..... | 0 to +70°C | |
| Industrial | -40 to +85°C | |
| Automotive..... | -40 to +85°C | |
| V _{DD} | | |
| High Speed versions..... | 4.5 to 5.5 V | |
| Low Voltage versions..... | 2.7 to 5.5 V | |

DC Characteristics

High Speed Versions - Commercial, Industrial, and Automotive

Table 55. DC Characteristics; $V_{DD} = 4.5$ to 5.5 V, $T_A = -40$ to $+85^\circ\text{C}$

| Symbol | Parameter | Min | Typical ⁽⁴⁾ | Max | Units | Test Conditions |
|-----------------|--|--|------------------------|--------------------------|---------------|---|
| V_{IL} | Input Low Voltage (except EA#, SCL, SDA) | -0.5 | | $0.2 \cdot V_{DD} - 0.1$ | V | |
| $V_{IL1}^{(5)}$ | Input Low Voltage (SCL, SDA) | -0.5 | | $0.3 \cdot V_{DD}$ | V | |
| V_{IL2} | Input Low Voltage (EA#) | 0 | | $0.2 \cdot V_{DD} - 0.3$ | V | |
| V_{IH} | Input high Voltage (except XTAL1, RST, SCL, SDA) | $0.2 \cdot V_{DD} + 0.9$ | | $V_{DD} + 0.5$ | V | |
| $V_{IH1}^{(5)}$ | Input high Voltage (XTAL1, RST, SCL, SDA) | $0.7 \cdot V_{DD}$ | | $V_{DD} + 0.5$ | V | |
| V_{OL} | Output Low Voltage (Ports 1, 2, 3) | | | 0.3 0.45 1.0 | V | $I_{OL} = 100 \mu\text{A}^{(1)(2)}$ $I_{OL} = 1.6 \text{ mA}^{(1)(2)}$ $I_{OL} = 3.5 \text{ mA}^{(1)(2)}$ |
| V_{OL1} | Output Low Voltage (Ports 0, ALE, PSEN#, Port 2 in Page Mode during External Address) | | | 0.3 0.45 1.0 | V | $I_{OL} = 200 \mu\text{A}^{(1)(2)}$ $I_{OL} = 3.2 \text{ mA}^{(1)(2)}$ $I_{OL} = 7.0 \text{ mA}^{(1)(2)}$ |
| V_{OH} | Output high Voltage (Ports 1, 2, 3, ALE, PSEN#) | $V_{DD} - 0.3$ $V_{DD} - 0.7$ $V_{DD} - 1.5$ | | | V | $I_{OH} = -10 \mu\text{A}^{(3)}$ $I_{OH} = -30 \mu\text{A}^{(3)}$ $I_{OH} = -60 \mu\text{A}^{(3)}$ |
| V_{OH1} | Output high Voltage (Port 0, Port 2 in Page Mode during External Address) | $V_{DD} - 0.3$ $V_{DD} - 0.7$ $V_{DD} - 1.5$ | | | V | $I_{OH} = -200 \mu\text{A}$ $I_{OH} = -3.2 \text{ mA}$ $I_{OH} = -7.0 \text{ mA}$ |
| V_{RET} | V_{DD} data retention limit | | | 1.8 | V | |
| I_{IL0} | Logical 0 Input Current (Ports 1, 2, 3) | | | - 50 | μA | $V_{IN} = 0.45 \text{ V}$ |
| I_{IL1} | Logical 1 Input Current (NMI) | | | + 50 | μA | $V_{IN} = V_{DD}$ |
| I_{LI} | Input Leakage Current (Port 0) | | | ± 10 | μA | $0.45 \text{ V} < V_{IN} < V_{DD}$ |
| I_{TL} | Logical 1-to-0 Transition Current (Ports 1, 2, 3 - AWAIT#) | | | - 650 | μA | $V_{IN} = 2.0 \text{ V}$ |
| R_{RST} | RST Pull-Down Resistor | 40 | 110 | 225 | k Ω | |
| C_{IO} | Pin Capacitance | | 10 | | pF | $T_A = 25^\circ\text{C}$ |
| I_{DD} | Operating Current | | 20 25 35 | 25 30 40 | mA | $F_{OSC} = 12 \text{ MHz}$ $F_{OSC} = 16 \text{ MHz}$ $F_{OSC} = 24 \text{ MHz}$ |
| I_{DL} | Idle Mode Current | | 5 6.5 9.5 | 8 10 14 | mA | $F_{OSC} = 12 \text{ MHz}$ $F_{OSC} = 16 \text{ MHz}$ $F_{OSC} = 24 \text{ MHz}$ |
| I_{PD} | Power-Down Current | | 2 | 20 | μA | $V_{RET} < V_{DD} < 5.5 \text{ V}$ |
| V_{PP} | Programming supply voltage | 12.5 | | 13 | V | $T_A = 0$ to $+40^\circ\text{C}$ |
| I_{PP} | Programming supply current | | | 75 | mA | $T_A = 0$ to $+40^\circ\text{C}$ |

Notes: 1. Under steady-state (non-transient) conditions, I_{OL} must be externally limited as follows:

Maximum IOL per port pin: 10 mA

Maximum IOL per 8-bit port: Port 0 26 mA

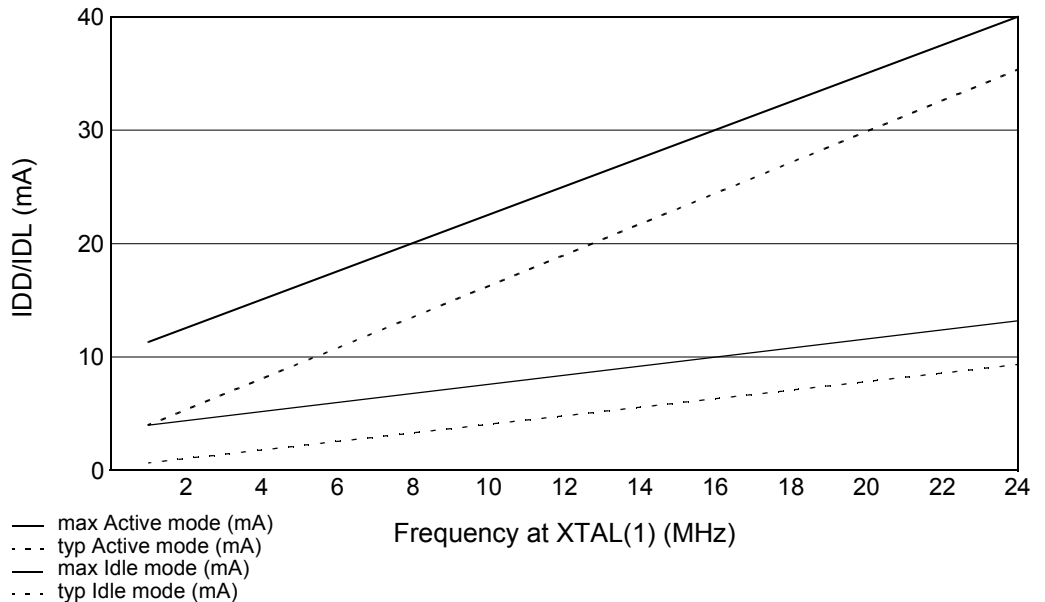
Ports 1-3 15 mA

Maximum Total IOL for all: Output Pins 71 mA

If IOL exceeds the test conditions, V_{OL} may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions.

2. Capacitive loading on Ports 0 and 2 may cause spurious noise pulses above 0.4 V on the low-level outputs of ALE and Ports 1, 2, and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins change from high to low. In applications where capacitive loading exceeds 100 pF, the noise pulses on these signals may exceed 0.8 V. It may be desirable to qualify ALE or other signals with a Schmitt Trigger or CMOS-level input logic.
3. Capacitive loading on Ports 0 and 2 causes the V_{OH} on ALE and PSEN# to drop below the specification when the address lines are stabilizing.
4. Typical values are obtained using $V_{DD} = 5\text{ V}$ and $T_A = 25^\circ\text{C}$. They are not tested and there is not guarantee on these values.
5. The input threshold voltage of SCL and SDA meets the TWI specification, so an input voltage below $0.3 \cdot V_{DD}$ will be recognized as a logic 0 while an input voltage above $0.7 \cdot V_{DD}$ will be recognized as a logic 1.

Figure 28. I_{DD}/I_{DL} Versus Frequency; $V_{DD} = 4.5$ to 5.5 V



Note: 1. The clock prescaler is not used: $F_{OSC} = F_{XTAL}$.

Low Voltage Versions - Commercial & Industrial

Table 56. DC Characteristics; $V_{DD} = 2.7$ to 5.5 V, $T_A = -40$ to $+85^\circ\text{C}$

| Symbol | Parameter | Min | Typical ⁽⁴⁾ | Max | Units | Test Conditions |
|-----------------|---|--------------------------|------------------------|--------------------------|---------------|---|
| V_{IL} | Input Low Voltage (except EA#, SCL, SDA) | -0.5 | | $0.2 \cdot V_{DD} - 0.1$ | V | |
| $V_{IL1}^{(5)}$ | Input Low Voltage (SCL, SDA) | -0.5 | | $0.3 \cdot V_{DD}$ | V | |
| V_{IL2} | Input Low Voltage (EA#) | 0 | | $0.2 \cdot V_{DD} - 0.3$ | V | |
| V_{IH} | Input high Voltage (except XTAL1, RST, SCL, SDA) | $0.2 \cdot V_{DD} + 0.9$ | | $V_{DD} + 0.5$ | V | |
| $V_{IH1}^{(5)}$ | Input high Voltage (XTAL1, RST, SCL, SDA) | $0.7 \cdot V_{DD}$ | | $V_{DD} + 0.5$ | V | |
| V_{OL} | Output Low Voltage (Ports 1, 2, 3) | | | 0.45 | V | $I_{OL} = 0.8 \text{ mA}^{(1)(2)}$ |
| V_{OL1} | Output Low Voltage (Ports 0, ALE, PSEN#, Port 2 in Page Mode during External Address) | | | 0.45 | V | $I_{OL} = 1.6 \text{ mA}^{(1)(2)}$ |
| V_{OH} | Output high Voltage (Ports 1, 2, 3, ALE, PSEN#) | $0.9 \cdot V_{DD}$ | | | V | $I_{OH} = -10 \mu\text{A}^{(3)}$ |
| V_{OH1} | Output high Voltage (Port 0, Port 2 in Page Mode during External Address) | $0.9 \cdot V_{DD}$ | | | V | $I_{OH} = -40 \mu\text{A}$ |
| V_{RET} | V_{DD} data retention limit | | | 1.8 | V | |
| I_{ILO} | Logical 0 Input Current (Ports 1, 2, 3 - AWAIT#) | | | - 50 | μA | $V_{IN} = 0.45 \text{ V}$ |
| I_{IL1} | Logical 1 Input Current (NMI) | | | + 50 | μA | $V_{IN} = V_{DD}$ |
| I_{LI} | Input Leakage Current (Port 0) | | | ± 10 | μA | $0.45 \text{ V} < V_{IN} < V_{DD}$ |
| I_{TL} | Logical 1-to-0 Transition Current (Ports 1, 2, 3) | | | - 650 | μA | $V_{IN} = 2.0 \text{ V}$ |
| R_{RST} | RST Pull-Down Resistor | 40 | 110 | 225 | k Ω | |
| C_{IO} | Pin Capacitance | | 10 | | pF | $T_A = 25^\circ\text{C}$ |
| I_{DD} | Operating Current | | 4 8 9 11 | 8 11 12 14 | mA | 5 MHz, $V_{DD} < 3.6 \text{ V}$ 10 MHz, $V_{DD} < 3.6 \text{ V}$ 12 MHz, $V_{DD} < 3.6 \text{ V}$ 16 MHz, $V_{DD} < 3.6 \text{ V}$ |
| I_{DL} | Idle Mode Current | | 0.5 1.5 2 3 | 1 4 5 7 | mA | 5 MHz, $V_{DD} < 3.6 \text{ V}$ 10 MHz, $V_{DD} < 3.6 \text{ V}$ 12 MHz, $V_{DD} < 3.6 \text{ V}$ 16 MHz, $V_{DD} < 3.6 \text{ V}$ |
| I_{PD} | Power-Down Current | | 1 | 10 | μA | $V_{RET} < V_{DD} < 3.6 \text{ V}$ |

Notes: 1. Under steady-state (non-transient) conditions, I_{OL} must be externally limited as follows:

Maximum IOL per port pin: 10 mA

Maximum IOL per 8-bit port: Port 0 26 mA

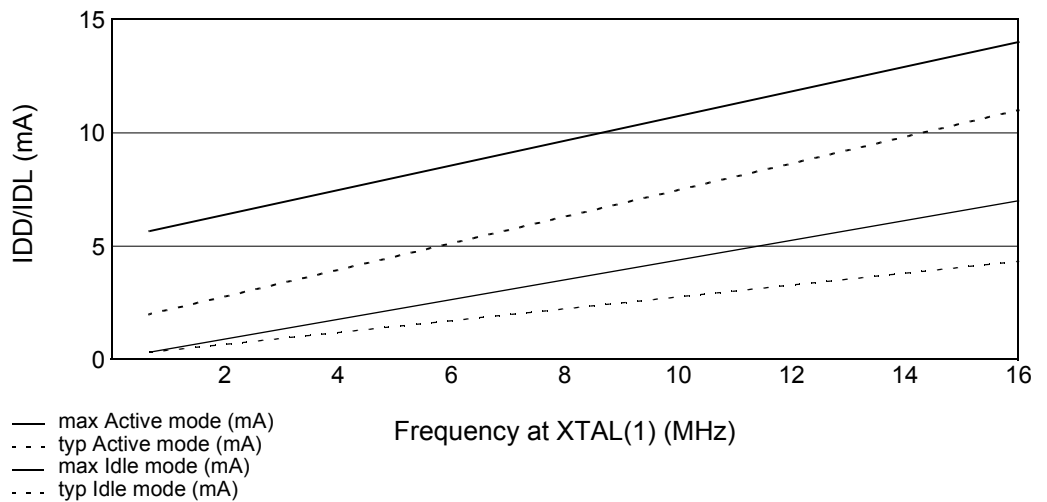
Ports 1-3 15 mA

Maximum Total IOL for all: Output Pins 71 mA

If IOL exceeds the test conditions, VOL may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions.

2. Capacitive loading on Ports 0 and 2 may cause spurious noise pulses above 0.4 V on the low-level outputs of ALE and Ports 1, 2, and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins change from high to low. In applications where capacitive loading exceeds 100 pF, the noise pulses on these signals may exceed 0.8 V. It may be desirable to qualify ALE or other signals with a Schmitt Trigger or CMOS-level input logic.
3. Capacitive loading on Ports 0 and 2 causes the V_{OH} on ALE and PSEN# to drop below the specification when the address lines are stabilizing.
4. Typical values are obtained using $V_{DD} = 3\text{ V}$ and $T_A = 25^\circ\text{C}$. They are not tested and there is not guarantee on these values.
5. The input threshold voltage of SCL and SDA meets the TWI specification, so an input voltage below $0.3 \cdot V_{DD}$ will be recognized as a logic 0 while an input voltage above $0.7 \cdot V_{DD}$ will be recognized as a logic 1.

Figure 29. I_{DD}/I_{DL} Versus X_{TAL} Frequency; $V_{DD} = 2.7$ to 3.6 V



Note: 1. The clock prescaler is not used: $F_{OSC} = F_{XTAL}$.

I_{DD} , I_{DL} and I_{PD} Test Conditions

Figure 30. I_{DD} Test Condition, Active Mode

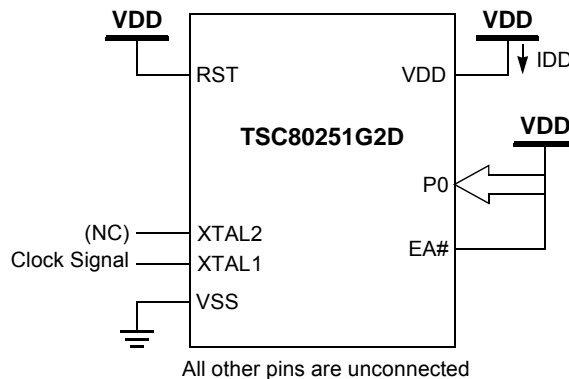


Figure 31. I_{DL} Test Condition, Idle Mode

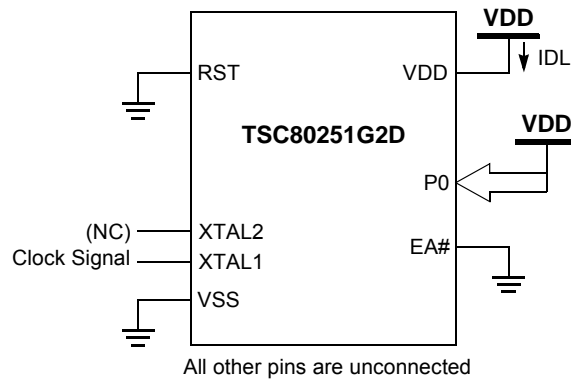
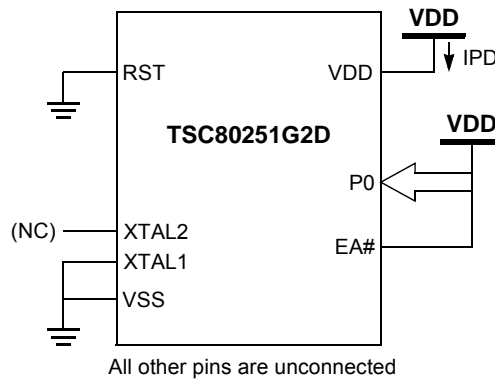


Figure 32. I_{PD} Test Condition, Power-Down Mode



Packages

List of Packages

- PDIL 40
- CDIL 40 with window
- PLCC 44
- CQPJ 44 with window
- VQFP 44 (10x10)

PDIL 40 - Mechanical Outline

Figure 33. Plastic Dual In Line

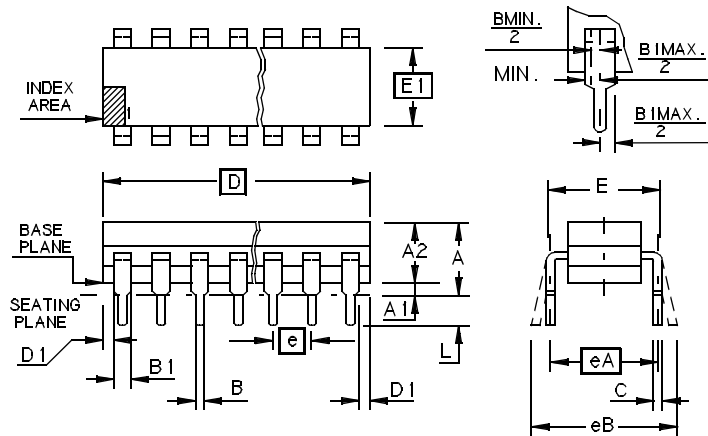


Table 57. PDIL Package Size

| | MM | | Inch | |
|----|--------------|-------|-------------|-------|
| | Min | Max | Min | Max |
| A | - | 5.08 | - | .200 |
| A1 | 0.38 | - | .015 | - |
| A2 | 3.18 | 4.95 | .125 | .195 |
| B | 0.36 | 0.56 | .014 | .022 |
| B1 | 0.76 | 1.78 | .030 | .070 |
| C | 0.20 | 0.38 | .008 | .015 |
| D | 50.29 | 53.21 | 1.980 | 2.095 |
| E | 15.24 | 15.87 | .600 | .625 |
| E1 | 12.32 | 14.73 | .485 | .580 |
| e | 2.54 B.S.C. | | .100 B.S.C. | |
| eA | 15.24 B.S.C. | | .600 B.S.C. | |
| eB | - | 17.78 | - | .700 |
| L | 2.93 | 3.81 | .115 | .150 |
| D1 | 0.13 | - | .005 | - |

CDIL 40 with Window - Mechanical Outline

Figure 34. Ceramic Dual In Line

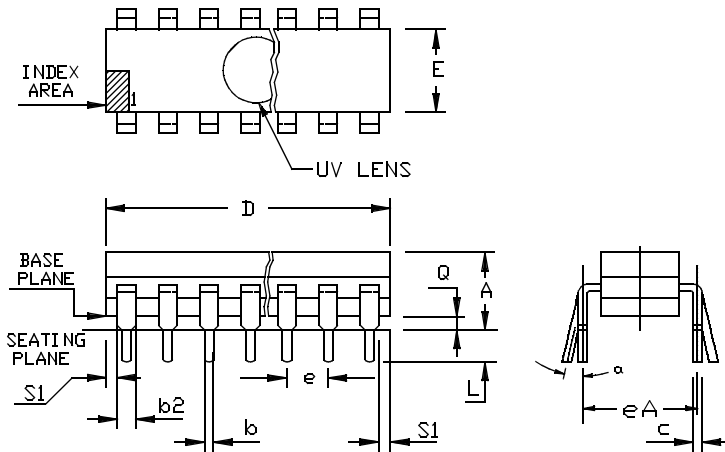


Table 58. CDIL Package Size

| | MM | | Inch | |
|----|--------------|-------|-------------|-------|
| | Min | Max | Min | Max |
| A | - | 5.71 | - | .225 |
| b | 0.36 | 0.58 | .014 | .023 |
| b2 | 1.14 | 1.65 | .045 | .065 |
| c | 0.20 | 0.38 | .008 | .015 |
| D | - | 53.47 | - | 2.105 |
| E | 13.06 | 15.37 | .514 | .605 |
| e | 2.54 B.S.C. | | .100 B.S.C. | |
| eA | 15.24 B.S.C. | | .600 B.S.C. | |
| L | 3.18 | 5.08 | .125 | .200 |
| Q | 0.38 | 1.40 | .015 | .055 |
| S1 | 0.13 | - | .005 | - |
| a | 0 - 15 | | 0 - 15 | |
| N | 40 | | | |

PLCC 44 - Mechanical Outline

Figure 35. Plastic Lead Chip Carrier

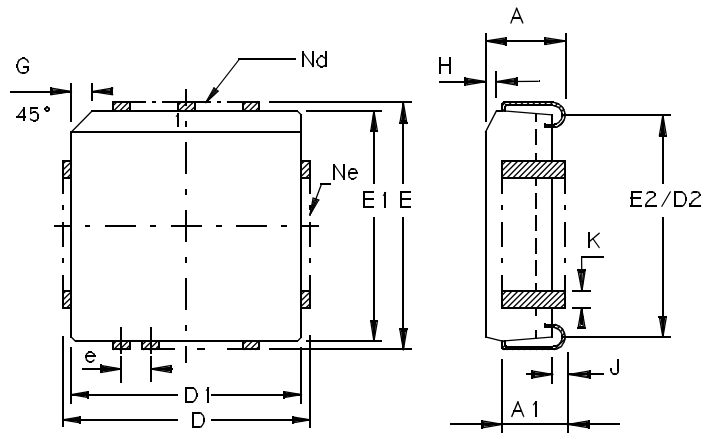


Table 59. PLCC Package Size

| | MM | | Inch | |
|----|----------|-------|----------|------|
| | Min | Max | Min | Max |
| A | 4.20 | 4.57 | .165 | .180 |
| A1 | 2.29 | 3.04 | .090 | .120 |
| D | 17.40 | 17.65 | .685 | .695 |
| D1 | 16.44 | 16.66 | .647 | .656 |
| D2 | 14.99 | 16.00 | .590 | .630 |
| E | 17.40 | 17.65 | .685 | .695 |
| E1 | 16.44 | 16.66 | .647 | .656 |
| E2 | 14.99 | 16.00 | .590 | .630 |
| e | 1.27 BSC | | .050 BSC | |
| G | 1.07 | 1.22 | .042 | .048 |
| H | 1.07 | 1.42 | .042 | .056 |
| J | 0.51 | - | .020 | - |
| K | 0.33 | 0.53 | .013 | .021 |
| Nd | 11 | | 11 | |
| Ne | 11 | | 11 | |

CQPJ 44 with Window - Mechanical Outline

Figure 36. Ceramic Quad Pack J

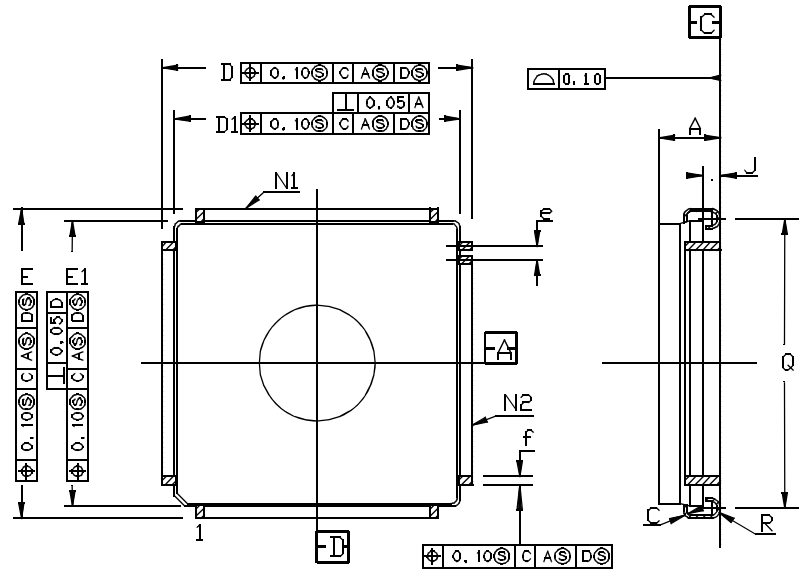


Table 60. CQPJ Package Size

| | MM | | Inch | |
|---------|----------|-------|----------|------|
| | Min | Max | Min | Max |
| A | - | 4.90 | - | .193 |
| C | 0.15 | 0.25 | .006 | .010 |
| D - E | 17.40 | 17.55 | .685 | .691 |
| D1 - E1 | 16.36 | 16.66 | .644 | .656 |
| e | 1.27 TYP | | .050 TYP | |
| f | 0.43 | 0.53 | .017 | .021 |
| J | 0.86 | 1.12 | .034 | .044 |
| Q | 15.49 | 16.00 | .610 | .630 |
| R | 0.86 TYP | | .034 TYP | |
| N1 | 11 | | 11 | |
| N2 | 11 | | 11 | |

**VQFP 44 (10x10) -
Mechanical Outline**

Figure 37. Shrink Quad Flat Pack (Plastic)

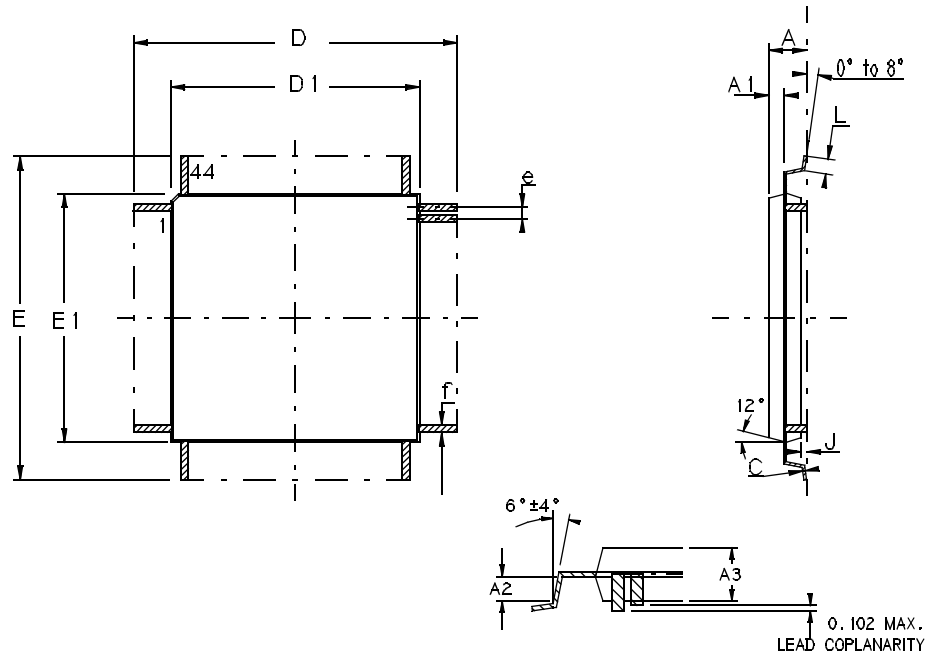


Table 61. VQFP Package Size

| | MM | | Inch | |
|----|----------|-------|-----------|------|
| | Min | Max | Min | Max |
| A | - | 1.60 | - | .063 |
| A1 | 0.64 REF | | .025 REF | |
| A2 | 0.64 REF | | .025REF | |
| A3 | 1.35 | 1.45 | .053 | .057 |
| D | 11.90 | 12.10 | .468 | .476 |
| D1 | 9.90 | 10.10 | .390 | .398 |
| E | 11.90 | 12.10 | .468 | .476 |
| E1 | 9.90 | 10.10 | .390 | .398 |
| J | 0.05 | - | .002 | 6 |
| L | 0.45 | 0.75 | .018 | .030 |
| e | 0.80 BSC | | .0315 BSC | |
| f | 0.35 BSC | | .014 BSC | |

Ordering Information

AT/TSC80251G2D ROMless

| Part Number | ROM | Description |
|--|---------|--|
| High Speed Versions 4.5 to 5.5 V, Commercial and Industrial | | |
| TSC80251G2D-16CB | ROMless | 16 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC80251G2D-24CB | ROMless | 24 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC80251G2D-24CE | ROMless | 24 MHz, Commercial 0° to 70°C, VQFP 44 |
| TSC80251G2D-24IA | ROMless | 24 MHz, Industrial -40° to 85°C, PDIL 40 |
| TSC80251G2D-24IB | ROMless | 24 MHz, Industrial -40° to 85°C, PLCC 44 |
| AT80251G2D-SLSUM | ROMless | 24 MHz, Industrial & Green -40° to 85°C, PLCC 44 |
| AT80251G2D-3CSUM | ROMless | 24 MHz, Industrial & Green -40° to 85°C, PDIL 40 |
| AT80251G2D-RLTUM | ROMless | 24 MHz, Industrial & Green -40° to 85°C, VQFP 44 |
| Low Voltage Versions 2.7 to 5.5 V | | |
| TSC80251G2D-L16CB | ROMless | 16 MHz, Commercial, PLCC 44 |
| TSC80251G2D-L16CE | ROMless | 16 MHz, Commercial, VQFP 44 |
| AT80251G2D-SLSUL | ROMless | 16 MHz, Industrial & Green, PLCC 44 |
| AT80251G2D-RLTUL | ROMless | 16 MHz, Industrial & Green, VQFP 44 |

AT/TSC83251G2D 32 kilobytes MaskROM

| Part Number ⁽¹⁾ | ROM | Description |
|--|-------------|--|
| High Speed Versions 4.5 to 5.5 V, Commercial and Industrial | | |
| TSC251G2Dxxx-16CB | 32K MaskROM | 16 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC251G2Dxxx-24CB | 32K MaskROM | 24 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC251G2Dxxx-24CE | 32K MaskROM | 24 MHz, Commercial 0° to 70°C, VQFP 44 |
| TSC251G2Dxxx-24IA | 32K MaskROM | 24 MHz, Industrial -40° to 85°C, PDIL 40 |
| TSC251G2Dxxx-24IB | 32K MaskROM | 24 MHz, Industrial -40° to 85°C, PLCC 44 |
| AT251G2Dxxx-SLSUM | 32K MaskROM | 24 MHz, Industrial & Green -40° to 85°C, PLCC 44 |
| AT251G2Dxxx-3CSUM | 32K MaskROM | 24 MHz, Industrial & Green -40° to 85°C, PDIL 40 |
| AT251G2Dxxx-RLTUM | 32K MaskROM | 24 MHz, Industrial & Green -40° to 85°C, VQFP 44 |
| AT251G2Dxxx-SLSTM | 32K MaskROM | 24 MHz, Automotive & Green -40° to 85°C, PLCC 44 |



| Part Number ⁽¹⁾ | ROM | Description |
|--|-------------|--|
| Low Voltage Versions 2.7 to 5.5 V | | |
| TSC251G2Dxxx-L16CB | 32K MaskROM | 16 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC251G2Dxxx-L16CE | 32K MaskROM | 16 MHz, Commercial 0° to 70°C, VQFP 44 |
| AT251G2Dxxx-SLSUL | 32K MaskROM | 16 MHz, Industrial & Green, PLCC 44 |
| AT251G2Dxxx-RLTUL | 32K MaskROM | 16 MHz, Industrial & Green, VQFP 44 |

Note: 1. xxx: means ROM code, is Cxxx in case of encrypted code.

AT/TSC87251G2D OTPROM

| Part Number | ROM | Description |
|--|------------|--|
| High Speed Versions 4.5 to 5.5 V, Commercial and Industrial | | |
| TSC87251G2D-16CB | 32K OTPROM | 16 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC87251G2D-24CB | 32K OTPROM | 24 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC87251G2D-24CED | 32K OTPROM | 24 MHz, Commercial 0° to 70°C, VQFP 44 |
| TSC87251G2D-24IA | 32K OTPROM | 24 MHz, Industrial -40° to 85°C, PDIL 40 |
| TSC87251G2D-24IB | 32K OTPROM | 24 MHz, Industrial -40° to 85°C, PLCC 44 |
| AT87251G2D-SLSUM | 32K OTPROM | 24 MHz, Industrial & Green -40° to 85°C, PLCC 44 |
| AT87251G2D-3CSUM | 32K OTPROM | 24 MHz, Industrial & Green -40° to 85°C, PDIL 40 |
| AT87251G2D-RLTUM | 32K OTPROM | 24 MHz, Industrial & Green -40° to 85°C, VQFP 44 |
| Low Voltage Versions 2.7 to 5.5 V | | |
| TSC87251G2D-L16CB | 32K OTPROM | 16 MHz, Commercial 0° to 70°C, PLCC 44 |
| TSC87251G2D-L16CED | 32K OTPROM | 16 MHz, Commercial 0° to 70°C, VQFP 44 |
| AT87251G2D-SLSUL | 32K OTPROM | 16 MHz, Industrial & Green, 0° to 70°C, PLCC 44 |
| AT87251G2D-RLTUL | 32K OTPROM | 16 MHz, Industrial & Green, 0° to 70°C, VQFP 44 |

Document Revision History

Changes from 4135D to 4135E

1. Added automotive qualification, and ordering information for ROM product version.

Changes from 4135E to 4135F

1. Absolute Maximum Ratings added for automotive product version.



Options (Please consult Atmel sales)

- ROM code encryption
- Tape & Reel or Dry Pack
- Known good dice
- Extended temperature range: -55°C to +125°C

Product Markings

ROMless versions

| |
|---|
| ATMEL Part number YYWW . Lot Number |
|---|

Mask ROM versions

| |
|---|
| ATMEL Customer Part number Part Number YYWW . Lot Number |
|---|

OTP versions

| |
|---|
| ATMEL Part number YYWW . Lot Number |
|---|





Atmel Corporation

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 487-2600

Regional Headquarters

Europe

Atmel Sarl
Route des Arsenalux 41
Case Postale 80
CH-1705 Fribourg
Switzerland
Tel: (41) 26-426-5555
Fax: (41) 26-426-5500

Asia

Room 1219
Chinachem Golden Plaza
77 Mody Road Tsimshatsui
East Kowloon
Hong Kong
Tel: (852) 2721-9778
Fax: (852) 2722-1369

Japan

9F, Tonetsu Shinkawa Bldg.
1-24-8 Shinkawa
Chuo-ku, Tokyo 104-0033
Japan
Tel: (81) 3-3523-3551
Fax: (81) 3-3523-7581

Atmel Operations

Memory

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 436-4314

Microcontrollers

2325 Orchard Parkway
San Jose, CA 95131, USA
Tel: 1(408) 441-0311
Fax: 1(408) 436-4314

La Chantrerie
BP 70602
44306 Nantes Cedex 3, France
Tel: (33) 2-40-18-18-18
Fax: (33) 2-40-18-19-60

ASIC/ASSP/Smart Cards

Zone Industrielle
13106 Rousset Cedex, France
Tel: (33) 4-42-53-60-00
Fax: (33) 4-42-53-60-01

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906, USA
Tel: 1(719) 576-3300
Fax: 1(719) 540-1759

Scottish Enterprise Technology Park
Maxwell Building
East Kilbride G75 0QR, Scotland
Tel: (44) 1355-803-000
Fax: (44) 1355-242-743

RF/Automotive

Theresienstrasse 2
Postfach 3535
74025 Heilbronn, Germany
Tel: (49) 71-31-67-0
Fax: (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906, USA
Tel: 1(719) 576-3300
Fax: 1(719) 540-1759

Biometrics/Imaging/Hi-Rel MPU/ High Speed Converters/RF Datacom

Avenue de Rochepleine
BP 123
38521 Saint-Egreve Cedex, France
Tel: (33) 4-76-58-30-00
Fax: (33) 4-76-58-34-80

Literature Requests

www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. **EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDITIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.** Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© Atmel Corporation 2006. All rights reserved. Atmel®, logo and combinations thereof, and Everywhere You Are® are the trademarks or registered trademarks, of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.



Printed on recycled paper.

4135F-8051-11/06