

M5265P

LOW SATURATION OUTPUT TYPE CURRENT DRIVER

DESCRIPTION

M5265P is quad Darlington current driver (semiconductor integrated circuit) which consists of PNP and NPN transistors with clamp diode and it can be driven directly by very small input current.

Low saturation output can be obtained by separating the output stage transistor's collector from the drive stage transistors.

CHARACTERISTICS

- High voltage resistance $BV_{CEO} \geq 80V$
- High input voltage resistance $V_I \geq 20V$
- Large current drive $I_{C(max)} = 2.0A^*$
- Low saturation output $0.25V$ (typ) ($I_C = 0.3A$)
- Contains a clamp diode.
- Operates by the "L" level input.
- Wide operating temperature range . . $T_a = -40^\circ C \sim +85^\circ C$
 * $PW = 10$ ms, duty cycle $\leq 10\%$

APPLICATION

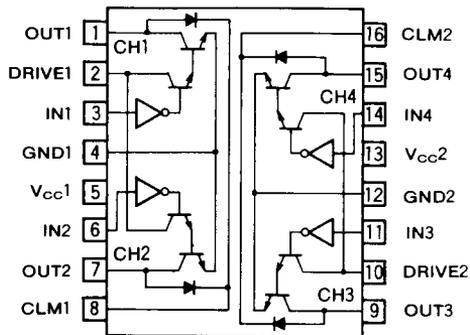
Motor drives for various relays or portable printers, digit drives for display elements such as LEDs and lamps, or power amplifiers

FUNCTION

Unlike the existing common-collector-type transistor arrays, M5265P realizes 0.25V of low saturation output voltage (typ, $I_C = 0.3A$) by separating the drive stage collector from the output stage collector. Therefore, the power dissipation which is determined by the product of the load current and the saturation output voltage can be greatly decreased.

The maximum output current is 2.0A and up to 80V can be applied as the output voltage.

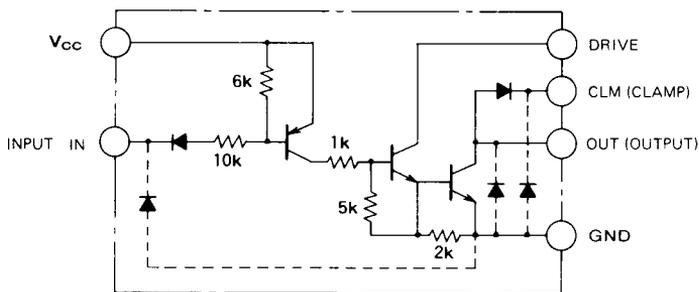
PIN CONFIGURATION (TOP VIEW)



Outline 16P4

CIRCUIT DIAGRAM

LOW ACTIVE



* OUTPUT - FUNCTION

Input	Output
L	L(ON)
H	H(OFF)

DRIVE, CLM, V_{CC} , and GND are common to channels 1-2 and 3-4.
 The diode indicated by dashed lines are already contained in the IC structure, therefore, it is not necessary to attach it externally.

Unit: Ω

LOW SATURATION OUTPUT TYPE CURRENT DRIVER**ABSOLUTE MAXIMUM RATINGS** ($T_a = 25^\circ\text{C}$, unless otherwise noted)

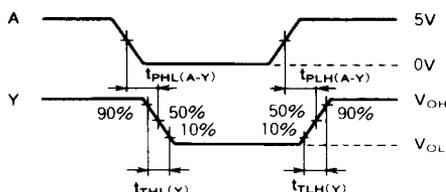
Symbol	Parameter	Conditions	Rating	Unit
V_{CC}	Supply voltage		20	V
V_D	Drive stage applied voltage		80	V
V_{CED}	Output voltage	When the output is "H"	80	V
V_I	Input voltage	$V_{CC} = 5\text{V}$	30	V
I_C	Output current	Current per circuit when the output is "L"	2.0*	A
V_R	Clamp diode reverse voltage		80	V
I_F	Clamp diode forward current		2.0	A
P_d	Power dissipation	$T_a = 25^\circ\text{C}$	2.0(2.5)**	W
T_{opr}	Operating temperature		-40 ~ +85	$^\circ\text{C}$
T_{stg}	Storage temperature		-55 ~ +150	$^\circ\text{C}$

* : $PW = 10\text{ms}$, duty cycle $\leq 10\%$ ** : 400mm² of copper film is added.**RECOMMENDED OPERATING CONDITIONS** ($T_a = 25^\circ\text{C}$, unless otherwise noted)

Symbol	Parameter	Condition	Limits			Unit
			Min	Typ	Max	
V_{CC}	Supply voltage		4	5	6	V
V_D	Drive stage applied voltage		4	5	70	V
V_{CE}	Output applied voltage		0		70	V
I_C	Output current	Current per circuit	0	0, 3	1, 25	A
V_R	Clamp diode reverse voltage		0		70	V
I_F	Clamp diode forward current		0		1, 25	A
P_d	Operating temperature		0		1, 0	W

ELECTRICAL CHARACTERISTICS ($T_a = 25^\circ\text{C}$, value/circuit unless otherwise noted)

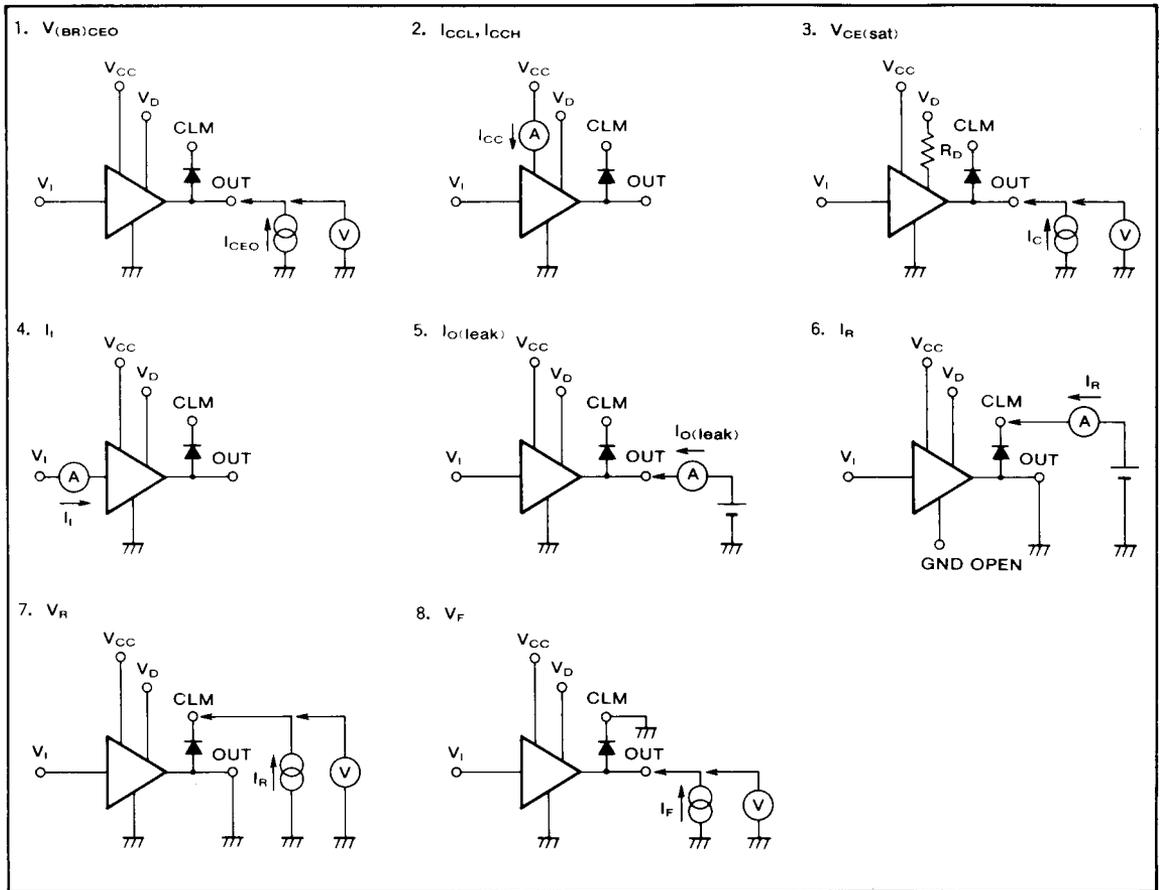
Symbol	Parameter	Test conditions	Limits			Unit
			Min	Typ	Max	
$V_{(BR)CEO}$	Output breakdown voltage	$I_{CEO} = 100\mu\text{A}$	80			V
I_{CCH}	Output "H" supply current	$V_{CC} = 6\text{V}$, $V_I = V_{CC}$			10	μA
I_{CCL}	Output "L" supply current	$V_{CC} = 6\text{V}$, $V_I = 0, 5\text{V}$			10	mA
$V_{CE(sat)}$	Saturation output voltage	$V_{CC} = 4\text{V}$ $V_D = 4\text{V}$ $V_I = 0, 5\text{V}$	$I_C = 1, 25\text{A}$, $R_D = 50\Omega$	1.0	1.8	V
			$I_C = 0, 7\text{A}$, $R_D = 100\Omega$	0.55	1.0	
			$I_C = 0, 3\text{A}$, $R_D = 260\Omega$	0.25	0.5	
I_I	Input current	$V_I = V_{CC} - 0, 5\text{V}$ $V_I = V_{CC} - 6\text{V}$			-0.1 -0.1	mA
$I_{O(Leak)}$	Output lead current	$V_{CE} = 80\text{V}$			100	μA
I_R	Clamp diode leak current	$V_R = 80\text{V}$			50	μA
V_R	Clamp diode reverse voltage	$I_R = 100\mu\text{A}$	80			V
V_F	Clamp diode forward voltage	$I_F = 1, 25\text{A}$			2.5	V
V_{IH}	"H" input voltage	$I_{O(Leak)} = 50\mu\text{A}$	$V_{CC} - 1, 0$			V
V_{IL}	"L" input voltage	$I_C = 1, 25\text{A}$			$V_{CC} - 3, 5$	V

TIMING DIAGRAM**TYPICAL SPEED (Example)**

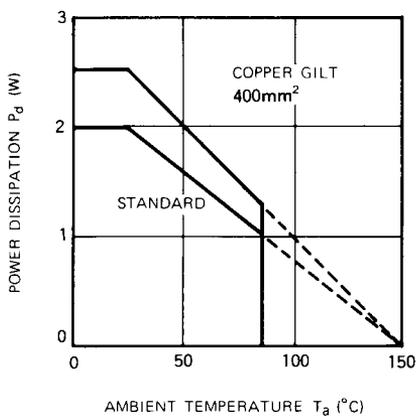
$t_{PHL(A-Y)}$	$t_{PLH(A-Y)}$	$t_{THL(Y)}$	$t_{TLH(Y)}$
140ns	8.0 μs	100ns	650ns

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TEST CIRCUITS

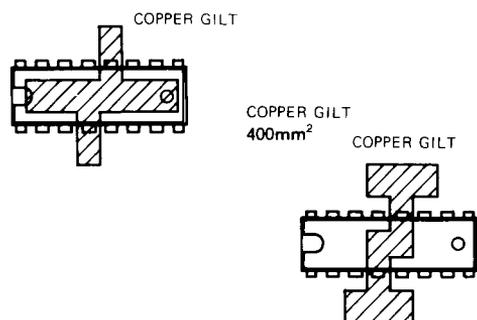


TYPICAL CHARACTERISTICS



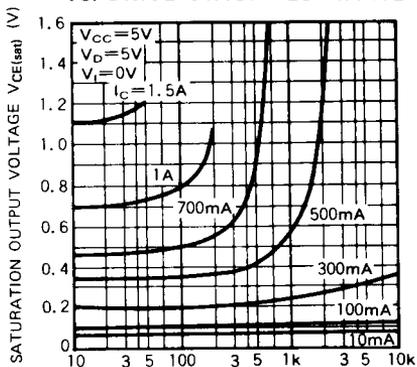
SAMPLE PCB LAYOUT

When you design a layout of a PCB, you have to consider the thermal derating. To improve the heat radiation of an IC, add a 400 mm² of copper film at the base of the GND pin. This will improve the thermal derating characteristics.



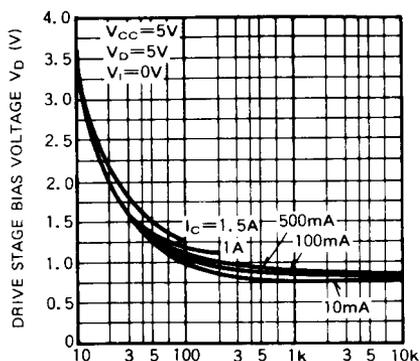
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SATURATION OUTPUT VOLTAGE VS. DRIVE STAGE RESISTANCE



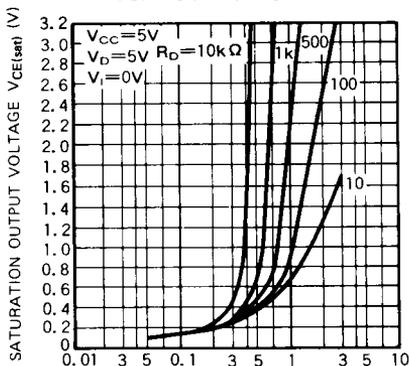
DRIVE STAGE RESISTANCE R_D (Ω)

DRIVE STAGE BIAS VOLTAGE VS. DRIVE STAGE RESISTANCE



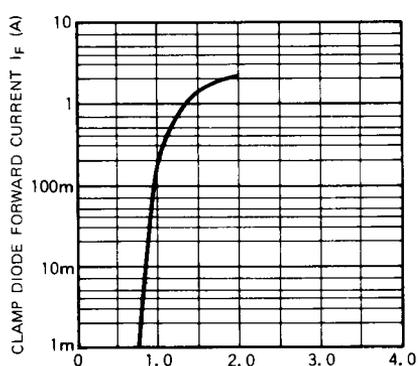
DRIVE STAGE RESISTANCE R_D (Ω)

SATURATION OUTPUT VOLTAGE VS. OUTPUT CURRENT



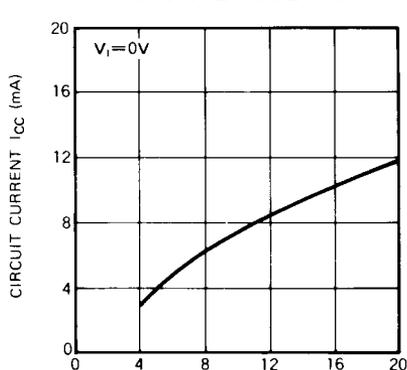
OUTPUT CURRENT I_C (A)

CLAMP DIODE FORWARD CURRENT VS. CLAMP DIODE FORWARD VOLTAGE



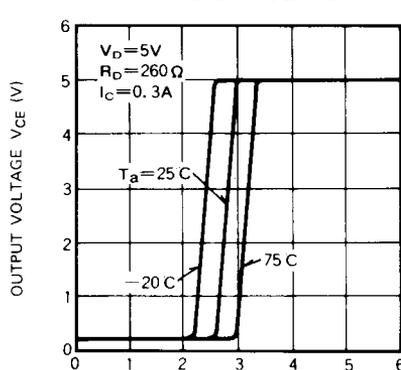
CLAMP DIODE FORWARD VOLTAGE V_F (V)

CIRCUIT CURRENT VS. SUPPLY VOLTAGE



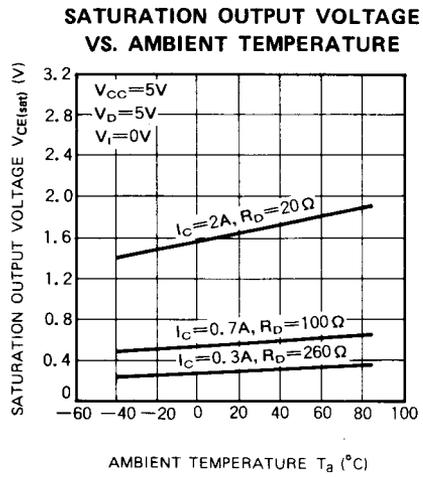
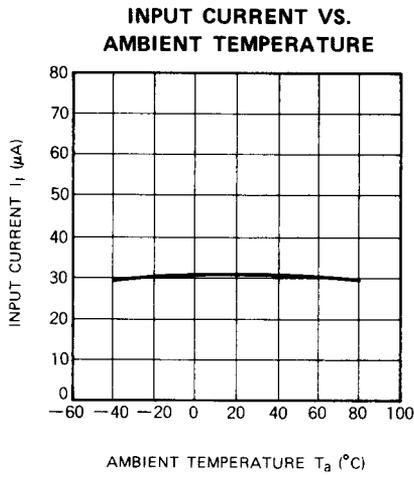
SUPPLY VOLTAGE V_{CC} (V)

OUTPUT VOLTAGE VS. INPUT VOLTAGE

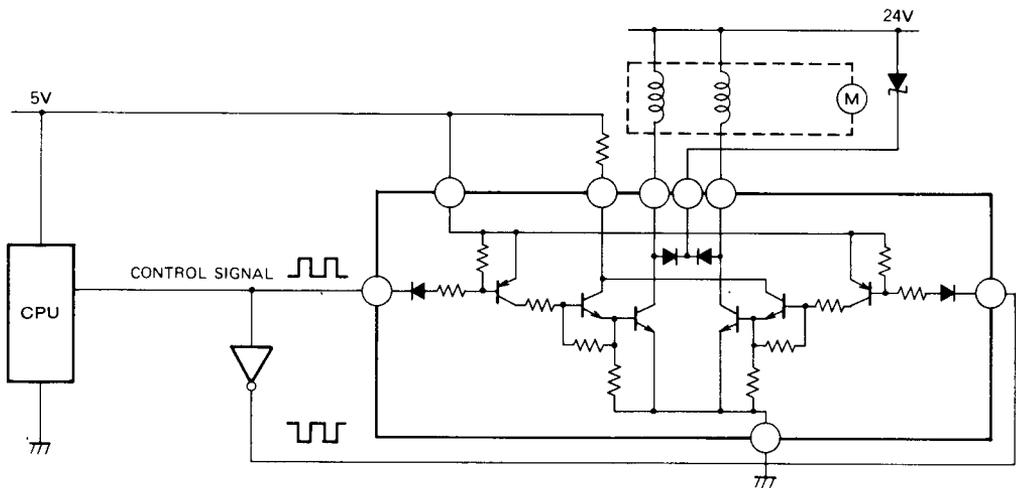


INPUT VOLTAGE V_i (V)

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APPLICATION CIRCUIT (Stepping motor drive for a printer)



V_{CC} , DRIVE, CLAMP, AND GND ARE THE SAME FOR BOTH CIRCUITS.